

Edexcel Maths M4

Mark Scheme Pack

2002-2015

# EDEXCEL FOUNDATION

Stewart House 32 Russell Square London WC1B 5DN

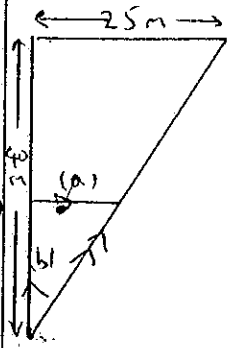
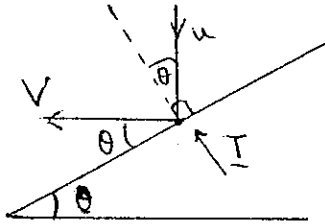
January 2002

Advanced Subsidiary / Advanced Level

General Certificate of Education

Subject MECHANICS 6680

Paper No. M4

Question number	Scheme	Marks
<p>1. (a)</p>  <p>(b)</p>	<p>Complete method for speed of current  e.g. <math>= \frac{25m}{30s}</math> or find <math>V(1.57)</math>, <math>\theta(32^\circ)</math> and use <math>V \sin \theta</math> or equiv.  <math>= \frac{5}{6} \text{ ms}^{-1}</math> or <math>0.83(3) \text{ ms}^{-1}</math></p> <p>Complete method for speed of swimmer  e.g. <math>= \frac{40m}{30s}</math> or <math>\sqrt{V^2 - (a)^2}</math> or <math>V_c \sin \theta_c</math>  <math>= \frac{4}{3} \text{ ms}^{-1}</math> or <math>1.3(3) \text{ ms}^{-1}</math></p>	<p>M1  A1 (2)  M1  A1 (2)</p>
<p>2.</p>	<p>Equation of motion: <math>-mg - mkv = ma</math> ; <math>\frac{dv}{dt} = -(g + kv)</math></p> <p>Separating variables: <math>\int dt = - \int \frac{dv}{g + kv}</math></p> <p>Integrating <math>t = -\frac{1}{k} [\ln(g + kv)] + c</math></p> <p>Using limits to give <math>T = \frac{1}{k} [\ln(g + kv)]_0^u</math> or using limits <math>[t=0, v=u]</math> to find <math>c</math>:</p> <p>Completing to give <math>T = \frac{1}{k} \ln\left(\frac{g + ku}{g}\right)</math></p> <p>[ Mark finding greatest height as Mr]</p>	<p>(M) A1  (M)  A1  (M) A1 ✓  MIA1 (8)</p>
<p>3. (a)</p>  <p>(b)</p>	<p>Parallel to plane: <math>u \sin \theta = V \cos \theta</math></p> <p>Perpendicular to plane: <math>e u \cos \theta = V \sin \theta</math></p> <p>Eliminating <math>u</math> and <math>V</math>: <math>e \cot \theta = \tan \theta</math></p> <p>Given result: <math>e = \tan^2 \theta</math> *</p> <p>Impulse = change in momentum = <math>m ( V \sin \theta + u \cos \theta )</math></p> <p>Expression in <math>m, u</math> and <math>\theta</math>:  <math>= m ( e u \cos \theta + u \cos \theta ) = mu \cos \theta ( 1 + \tan^2 \theta )</math>  or <math>= mu \left( \frac{\sin^2 \theta}{\cos \theta} + \cos \theta \right)</math></p> <p>Completion <math>= mu \sec \theta</math> *</p>	<p>(M) A1  (M) A1  (M)  A1 (6)  (M) A1  (M)  A1 (4)</p>

# EDEXCEL FOUNDATION

Stewart House 32 Russell Square London WC1B 5DN

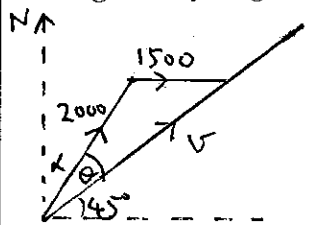
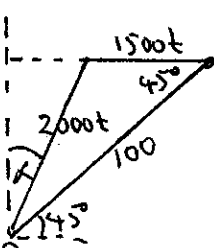
January 2002

Advanced Subsidiary / Advanced Level

General Certificate of Education

Subject MECHANICS 6680

Paper No. M4

Question number	Scheme	Marks
4. (a)	<p><i>Using velocity diagram</i></p>  $\frac{\sin \theta}{1500} = \frac{\sin 45^\circ}{2000}$ $\theta = 32^\circ \text{ (32.03)}$ $\text{Bearing} = 90^\circ - (45^\circ + \theta) = 013^\circ$ <p>(b) Method for <math>v</math>: e.g. (i) <math>v^2 = 1500^2 + 2000^2 - 2 \cdot 1500 \cdot 2000 \cdot \cos(90 + 13)^\circ</math>  or (ii) <math>v \cos 45^\circ = 2000 \cos 13_c^\circ</math>  or (iii) <math>\frac{\sin 45^\circ}{2000} = \frac{\sin 103^\circ}{v}</math>  <math>v = 2756 \text{ km h}^{-1}</math>  Time = <math>\frac{100}{v} \text{ h} = 131 \text{ s}</math></p> <p>[ Time = <math>\frac{100 \cos 45^\circ}{2000 \cos 13_c^\circ}</math> gains M1M1A1 immediately, correct answer gains A2]</p> <p><i>Using displacement method (several variations)</i></p> <p>(i) In the case below <math>\alpha</math> is bearing; but other relevant angle may be used  One equation in <math>t</math> and <math>\alpha</math>: e.g. <math>2000 t \sin \alpha = 50\sqrt{2} - 1500 t</math>  Second equation in <math>t</math> and <math>\alpha</math>: e.g. <math>2000 t \cos \alpha = 50\sqrt{2}</math>  Equation in one variable: e.g. <math>4 \cos \alpha - 4 \sin \alpha = 3</math>  Reducing to simple equation e.g. <math>4\sqrt{2} \cos(\alpha + 45^\circ) = 3</math>  Bearing = (0)13°</p>  <p>Sustituting for <math>\alpha</math> to find <math>t</math>; <math>t = 131 \text{ s}</math></p> <p>(ii) Using cosine rule: <math>(2000t)^2 = (1500t)^2 + 100^2 - 2 \cdot 100 \cdot 1500t \cos 45^\circ</math>  Quadratic form: <math>175t^2 + 15\sqrt{2}t - 1 = 0</math>  Solving: <math>t = 131 \text{ s}</math>  Equation in <math>t</math> and <math>\alpha</math>  Bearing = (0)13°</p>	<p>M1A1  M1A1  M1A1 (6)</p> <p>M1A1√</p> <p>A1  M1A1 (5)</p> <p>M1A1  M1A1  M1A1  M1A1√  A1</p> <p>M1A1</p> <p>M2A1A1  M1A1√  M1A1  M1A1  A1</p>

# EDEXCEL FOUNDATION

Stewart House 32 Russell Square London WC1B 5DN

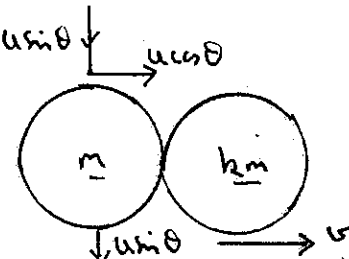
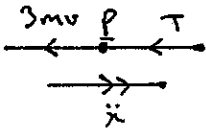
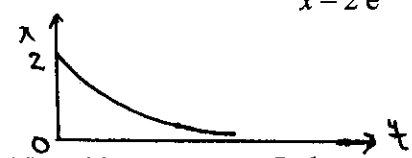
January 2002

Advanced Subsidiary / Advanced Level

General Certificate of Education

Subject MECHANICS 6680

Paper No. M4

Question number	Scheme	Marks
5. (a)	 <p>CLM: <math>mu \cos \theta = kmv</math>            NIL: <math>eu \cos \theta = v</math>            Eliminating <math>\theta</math></p> <p><math>e = \frac{1}{k} *</math></p>	<p>(M)A1 (M)A1 (M)A1 A1 (6)</p>
5. (b)	<p><math>\frac{1}{2} m v_a^2 + \frac{1}{2} (2m) (\frac{1}{2} u \cos \theta)^2 = \frac{3}{4} \cdot \frac{1}{2} m u^2</math> (or equivalent)  <math>\frac{1}{2} m (u \sin \theta)^2 + \frac{1}{2} (2m) (\frac{1}{2} u \cos \theta)^2 = \frac{3}{4} \cdot \frac{1}{2} m u^2</math> [M1 for <math>v_a = u \sin \theta</math>]  <math>[4 \sin^2 \theta + 2 \cos^2 \theta = 3]</math>  <math>4 \sin^2 \theta + 2(1 - \sin^2 \theta) = 3</math>  <math>\sin^2 \theta = \frac{1}{2}</math></p> <p><math>\theta = 45^\circ</math></p> <p>[ <math>\frac{1}{2} m (u \cos \theta)^2 - \frac{1}{2} (2m) (\frac{1}{2} u \cos \theta)^2 = \frac{1}{4} \cdot \frac{1}{2} m u^2</math> accepted for first 4 marks unless it is clear that candidate is working along line of centres only;            e.g. <math>\frac{1}{2} m (u \cos \theta)^2 - \frac{1}{2} (2m) (\frac{1}{2} u \cos \theta)^2 = \frac{1}{4} \cdot \frac{1}{2} m (u \cos \theta)^2</math>, then max M1]</p>	<p>(M)A1 (M)A1 (M)A1 A1 (6)</p>
6. (a)	 <p><math>T = \frac{2mL}{L} x</math></p> <p>Equation of motion: <math>-3mx - T = m \ddot{x}</math>  <math>\Rightarrow \ddot{x} + 3\dot{x} + 2x = 0 *</math></p>	<p>B1 M1A1 A1(cso) (4)</p>
6. (b)	<p>A.E. <math>m^2 + 3m + 2 = 0 \Rightarrow m = -1</math> or <math>-2</math>            G.S. <math>x = A e^{-t} + B e^{-2t}</math>  <math>t = 0, x = 2: \Rightarrow A + B = 2</math></p> <p>Differentiating <math>\dot{x} = -A e^{-t} - 2B e^{-2t}</math>  <math>t = 0, \dot{x} = -4: \Rightarrow A + 2B = 4</math> (any equivalent form)            Correctly solving simultaneous equations <math>(A = 0, B = 2)</math>  <math>x = 2 e^{-2t}</math></p>	<p>(M)A1 A1 B1 (M)A1 A1 (M)A1 A1 B1 B1 (8)</p>
6. (c)	 <p>Shape  <math>(0, 2), x = 0</math> asymptote  <i>Totally correct</i></p>	<p>B1 B1 (2)</p>
6. (d)	<p>No, with reason, e.g. <math>P</math> always moving</p>	<p>B1 (1)</p>

# EDEXCEL FOUNDATION

Stewart House 32 Russell Square London WC1B 5DN

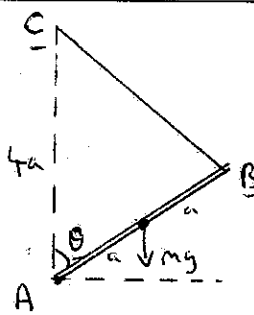
January 2002

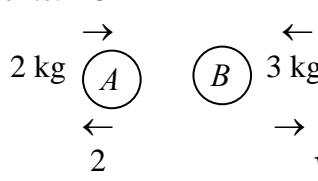
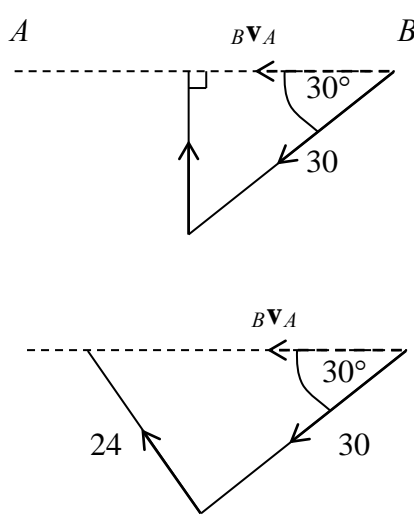
Advanced Subsidiary / Advanced Level

General Certificate of Education

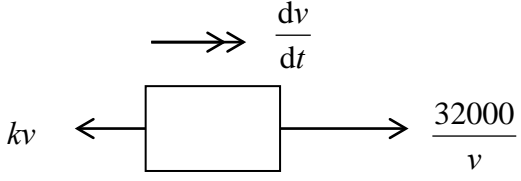
Subject MECHANICS 6680

Paper No. M4

Question number	Scheme	Marks
7. (a)	 <p>GPE: (from a fixed point) e.g. <math>mga \cos \theta</math> (+C)  EPE: <math>\frac{1}{2} mg \frac{(\text{ext})^2}{4a}</math></p> $BC^2 = (4a)^2 + (2a)^2 - 2 \cdot 4a \cdot 2a \cdot \cos \theta = 20a^2 - 16a^2 \cos \theta$ $\Rightarrow \text{EPE} = \frac{1}{2} mga [5 - 4 \cos \theta - 2\sqrt{5 - 4 \cos \theta}] + 1]$ <p><math>V = \text{GPE} + \text{EPE} (+C)</math> applied</p> $= mga \{-\cos \theta - \sqrt{5 - 4 \cos \theta} + 3\} + C \quad (\sqrt{\text{ dep. on all Ms)}$ $= mga \{-\cos \theta - \sqrt{5 - 4 \cos \theta}\} + \text{constant} \quad * \quad (\text{no errors seen})$	<p>M1 B1</p> <p>(M1)A1 (M1)A1</p> <p>M1</p> <p>A1√</p> <p>A1 (9)</p>
(b)	$\frac{dV}{d\theta} = mga \left\{ \sin \theta - \frac{4 \sin \theta}{2\sqrt{5 - 4 \cos \theta}} \right\}$ $\frac{dV}{d\theta} = 0 ; \quad [\sin \theta \{ \sqrt{5 - 4 \cos \theta} - 2 \} = 0]$ $\Rightarrow \sin \theta = 0 \quad \text{or} \quad \sqrt{5 - 4 \cos \theta} = 2$ $\Rightarrow \theta = 0 \text{ or } \pi \quad (0^\circ \text{ or } 180^\circ)$ $\Rightarrow \text{or } \theta = \cos^{-1} \left( \frac{1}{4} \right) = 1.32 \quad (75.5^\circ)$	<p>M1A1</p> <p>(M1)</p> <p>A1</p> <p>(M1)A1 (6)</p>

Question Number	Scheme	Marks
<p>1.</p>	<p><b>i</b> components: <math>3 \qquad u_1</math></p>  <p>Momentum <math>\leftarrow \rightarrow</math>: <math>2 \times 3 - 3u_1 = -2 \times 2 + 3v_1</math></p> <p>NLI: <math>10 = 3u_1 + 3v_1</math></p> <p><math>\frac{1}{2}(3 + u_1) = 2 + v_1</math></p> <p><math>1 = u_1 - 2v_1</math></p> <p>Solve for <math>u_1</math>, <math>23 = 9u_1 \Rightarrow u_1 = \frac{23}{9}</math></p> <p><b>j</b> component <math>= -u_1 \tan \alpha = -\frac{46}{9}</math></p> <p>Hence <math>\mathbf{u}_B = -\frac{23}{9} \mathbf{i} - \frac{46}{9} \mathbf{j}</math></p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1 A1</p> <p>M1 A1 ft</p> <p>A1</p> <p><b>(9 marks)</b></p>
<p>2.</p>	 <p><math>B\mathbf{v}_A</math> as <math>\leftarrow</math></p> <p>Correct <math>\Delta</math> for <math>\mathbf{v}_B</math> minimum</p> <p><math>v = 30 \sin 30^\circ = 15 \text{ km h}^{-1}</math></p> <p>Correct <math>\Delta</math></p> <p><math>\frac{30}{\sin \alpha} = \frac{24}{\sin 30^\circ}</math></p> <p><math>\Rightarrow \sin \alpha = \frac{5}{8}</math></p> <p><math> B\mathbf{v}_A  = 30 \cos 30^\circ + 24 \cos \alpha</math></p> <p><math>(\approx 44.716)</math></p> <p><math>T = \frac{20}{44.716} \approx 0.4473</math></p> <p><math>\Rightarrow 0927 \text{ hrs (awrt)}</math></p>	<p>M1</p> <p>M1</p> <p>A1 (3)</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>M1 A1</p> <p>M1</p> <p>A1 (7)</p> <p><b>(10 marks)</b></p>

(ft = follow through mark; awrt = anything which rounds to)

Question Number	Scheme	Marks
<p>3. (a)</p>	<div style="text-align: center;">  </div> $800 \frac{dv}{dt} = \frac{32000}{v} - kv$ $\Rightarrow 800v \frac{dv}{dt} = 32000 - kv^2 \quad (*)$	<p>M1 A1</p> <p>A1 (3)</p>
<p>(b)</p>	$v = 40, \quad \frac{dv}{dt} = 0 \Rightarrow 32000 = k \times 40^2$ $\Rightarrow k = 20$	<p>M1</p> <p>A1 (2)</p>
<p>(c)</p>	$\int dt = 800 \int \frac{v dv}{32000 - 20v^2} = \int \frac{40v dv}{1600 - v^2}$ $t = -20 \ln(1600 - v^2) (+ C)$ $t = 0, v = 0 \Rightarrow C = 20 \ln 1600 \text{ (or use of limits)}$ $t = 20 \ln 1600 - 20 \ln(1600 - v^2)$ $\Rightarrow t = 20 \ln \left( \frac{1600}{1600 - v^2} \right)$ $\frac{1600}{1600 - v^2} = e^{\frac{t}{20}}$ $1600 e^{-\frac{t}{20}} = 1600 - v^2$ $v = 40 \sqrt{\left( 1 - e^{-\frac{t}{20}} \right)}$	<p>M1</p> <p>M1 A1 ft</p> <p>M1 A1 ft</p> <p>M1</p> <p>A1 (7)</p> <p><b>(12 marks)</b></p>

((\*) indicates answer is given on the examination paper)

Question Number	Scheme	Marks
4.	(a) $AC = 4a \cos \theta \Rightarrow$ extension in spring $= 4a \cos \theta - 2a$	B1
	$V = -2mga \cos \theta - 2mg \times 3a \cos \theta + \frac{4mg}{4a}(4a \cos \theta - 2a) (+ C)$	M1 A1 A1
	$= -8mga \cos \theta + 4mg(2 \cos \theta - 1)^2 (+ C)$	
	$= 4mga[(2 \cos \theta - 1)^2 - 2 \cos \theta] (+ C)$	A1 (5)
	(b) $\frac{dV}{d\theta} = 4mga[2(2 \cos \theta - 1)(-2 \sin \theta) + 2 \sin \theta]$	M1 A1
$= 8mga \sin \theta(3 - 4 \cos \theta)$		
$= 0 \Rightarrow \cos \theta = \frac{3}{4} (\theta \neq 0, \pi)$	M1 A1	
$\Rightarrow \theta = 0.723$	A1 (4)	
(c) $\frac{d^2V}{d\theta^2} = 8mga \cos \theta(3 - 4 \cos \theta) + 32mga \sin^2 \theta$	M1 A1	
as $\theta = \frac{3}{4} \Rightarrow \frac{d^2V}{d\theta^2} = 0 + 32mga \times \frac{7}{16}$	M1	
$= 14mga$		
$> 0 \Rightarrow$ stable	A1 (4)	
<b>(13 marks)</b>		

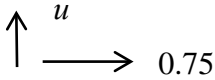
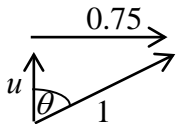
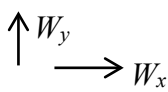

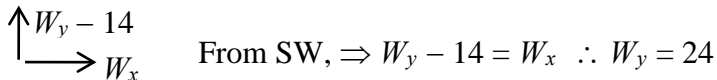
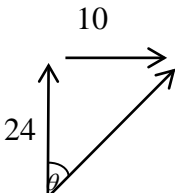


Question Number	Scheme	Marks
5.	<p>(a) <math>\mathbf{r}_P = \begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}</math>    <math>\mathbf{r}_Q = \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} + t \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}</math></p> <p><math>\begin{pmatrix} 1 \\ -2 \\ 3 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix} + t \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix}</math></p> <p><math>\Rightarrow t = 2</math> (one component)</p> <p>showing true for all components <math>\Rightarrow</math> collide</p> <p><math>\mathbf{r} = 3\mathbf{i} + 2\mathbf{j} + \mathbf{k}</math></p> <p>(b) <math>\mathbf{v}_R - \mathbf{v}_P = \lambda \begin{pmatrix} -5 \\ 4 \\ -1 \end{pmatrix}</math>,    <math>\mathbf{v}_R - \mathbf{v}_Q = \mu \begin{pmatrix} -2 \\ 2 \\ -1 \end{pmatrix}</math></p> <p><math>\mathbf{v}_Q - \mathbf{v}_P = \begin{pmatrix} 2 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} = \lambda \begin{pmatrix} -5 \\ 4 \\ -1 \end{pmatrix} - \mu \begin{pmatrix} -2 \\ 2 \\ -1 \end{pmatrix}</math></p> <p><math>\begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} = \lambda \begin{pmatrix} -5 \\ 4 \\ -1 \end{pmatrix} - \mu \begin{pmatrix} -2 \\ 2 \\ -1 \end{pmatrix}</math></p> <p><math>\left. \begin{array}{l} -5\lambda + 2\mu = 1 \\ 4\lambda - 2\mu = -2 \\ -\lambda + \mu = 2 \end{array} \right\}</math></p> <p>Solve for either <math>\lambda = 1</math> or <math>\mu = 3</math></p> <p>Hence <math>\mathbf{v}_R = -4\mathbf{i} + 6\mathbf{j} - 2\mathbf{k}</math></p> <p><math>\begin{pmatrix} 3 \\ 2 \\ 1 \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} + 2 \begin{pmatrix} -4 \\ 6 \\ -2 \end{pmatrix}</math></p> <p><math>\Rightarrow a = 11, b = -10, c = 5</math></p> <p><math>t = 0, R</math> is at <math>11\mathbf{i} - 10\mathbf{j} + 5\mathbf{k}</math></p>	<p>B1 (either)</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1 (5)</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>M1 A1</p> <p>A1</p> <p>M1 A1ft</p> <p>A1 (9)</p> <p><b>(14 marks)</b></p>

(ft = follow through mark)

Question Number	Scheme	Marks
<p>6. (a)</p> <p>(b)</p>	<div style="text-align: center;"> </div> <p> <math>T_1 = 4(1 + x) ; T_2 = 4(1 + \frac{1}{2} \sin 4t - x)</math>  <math>T_2 - T_1 = 2\ddot{x}</math>  <math>2\ddot{x} = 4(1 + \frac{1}{2} \sin 4t - x) - 4(1 + x)</math>  <math>\Rightarrow \ddot{x} + 4x = \sin 4t \quad (*)</math> </p> <p>                     CF: <math>x = A \sin 2t + B \cos 2t</math>                      PI: <math>x = P \sin 4t</math>  <math>-16P \sin 4t + 4P \sin 4t = \sin 4t</math>  <math>\Rightarrow P = -\frac{1}{12}</math>  <math>x = A \sin 2t + B \cos 2t - \frac{1}{12} \sin 4t</math>  <math>t = 0, x = 0 \Rightarrow B = 0</math>  <math>\dot{x} = 2A \cos 2t - \frac{1}{3} \cos 4t</math>  <math>t = 0, \dot{x} = 0 \Rightarrow A = \frac{1}{6}</math>  <math>\dot{x} = 0 \Rightarrow \frac{1}{3} \cos 2t - \frac{1}{3} \cos 4t = 0</math>  <math>\Rightarrow \cos 4t = \cos 2t</math>  <math>\Rightarrow 4t = 2t + 2\pi \text{ or } 2\pi - 2t</math>  <math>\Rightarrow t = \pi \text{ or } \frac{\pi}{3}</math>  <math>\Rightarrow</math> First at rest after <math>t = 0</math> when <math>t = \frac{\pi}{3}</math> </p>	<p>B1; B1</p> <p>M1</p> <p>A1</p> <p>A1 (5)</p> <p>B1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>M1</p> <p>A1 ft (8)</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>A1 cso (4)</p> <p><b>(17 marks)</b></p>

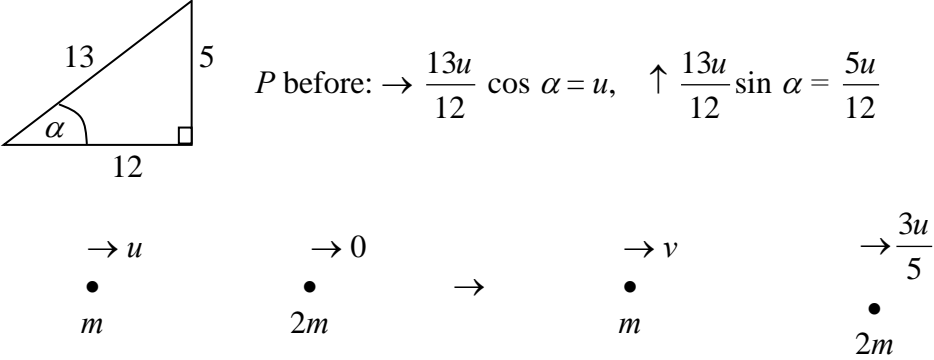
(ft = follow through mark; (\*) denotes answer is given on paper; cso = correct solution only)

Question Number	Scheme	Marks
1.	<p>Let boy's velocity be </p> <p>Speed = 1 <math>\Rightarrow 1^2 = u^2 + \frac{9}{16}</math>, <math>\therefore u^2 = \frac{7}{16}</math> or <math>u = \frac{\sqrt{7}}{4}</math> or 0.661...</p> <p>Time = <math>\frac{100}{\sqrt{7}/4} = 151.18\dots = 151\text{s}</math></p> <p></p> <p><math>\sin \theta = \frac{0.75}{1} \Rightarrow \theta = 48.6</math></p> <p><math>\therefore</math> Bearing is <math>049^\circ</math> or <math>048.6^\circ</math></p>	<p>M1</p> <p>M1 A1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(6)</p> <p><b>(6 marks)</b></p>
2.	<p>Let wind be </p> <p>Relative to A: </p> <p>Relative to B: </p> <p><math>\therefore</math> Magnitude of <math>W = \sqrt{10^2 + 24^2} = 26 \text{ km h}^{-1}</math></p> <p></p> <p><math>\tan \alpha = \frac{10}{24} \Rightarrow \alpha = 22.6</math></p> <p><math>\therefore</math> Bearing <math>023^\circ</math> or <math>022.6^\circ</math></p>	<p>M1</p> <p>M1, A1</p> <p>M1, A1</p> <p>A1</p> <p>A1</p> <p><b>(7 marks)</b></p>

Question Number	Scheme	Marks
3.	$(\downarrow) \quad mg - mkv^2 = ma$ $g - kv^2 = v \frac{dv}{dx}$ $x = \int \frac{v}{g - kv^2} dv$ $x = -\frac{1}{2k} \ln  g - kv^2  + c$ $x = 0, v = 0 \Rightarrow 0 = -\frac{1}{2k} + c$ $x = \frac{1}{2k} \ln \left  \frac{g}{g - kv^2} \right $ $e^{2kx} = \frac{g}{g - kv^2}$ $kv^2 = g(1 - e^{-2kx})$ $v = \sqrt{\frac{g}{k}(1 - e^{-2kD})}$	<p>M1 A1</p> <p><math>v \frac{dv}{dx}</math> M1</p> <p>M1</p> <p>M1 A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>must use <math>D</math> A1</p> <p><b>(11 marks)</b></p>

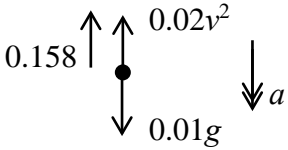
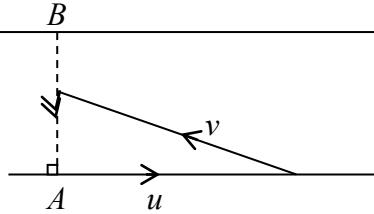
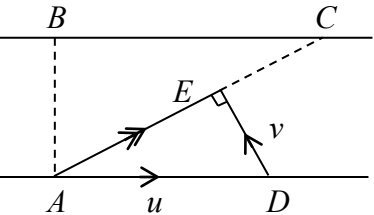
Question Number	Scheme	Marks
4. (a)	P.E.of rod = $mg \times 2a \sin 2\theta$ $AC = a \cot \theta$ EPE in String = $\frac{1}{2} \times \frac{3}{4} \times \frac{mg}{a} (a \cot \theta - a)^2$ Total P.E $V = mg \cdot 2a \sin 2\theta + \frac{3}{8} \frac{mg}{a} (a \cot \theta - a)^2$ $= \frac{mga}{8} [16 \sin 2\theta + 3 \cot^2 \theta - 6 \cot \theta + 3]$ i.e. $V = \frac{mga}{8} [16 \sin 2\theta + 3 \cot^2 \theta - 6 \cot \theta] + \text{const} \quad (*)$	B1 B1 M1 A1 M1 M1 A1 cso (7)
(b)	$\frac{dv}{d\theta} = \frac{mga}{8} [32 \cos 2\theta - 6 \cot \theta \operatorname{cosec}^2 \theta + 6 \operatorname{cosec}^2 \theta]$ $\left. \frac{dv}{d\theta} \right _{\theta=0.535} = \frac{mga}{8} (-0.5^{0.1\dots\dots})$ $\left. \frac{dv}{d\theta} \right _{\theta=0.545} = \frac{mga}{8} (0.2^{99\dots\dots})$ Change of sign $\therefore \frac{dv}{d\theta} = 0$ in range, so $\exists$ find a position of equilibrium	M1 A2, 1, 0 M1 A1 A1 (6)
(c)	$\left. \frac{dv}{d\theta} \right _{0.535} < 0, \left. \frac{dv}{d\theta} \right _{0.545} > 0$ So turning point is <i>minimum</i> , $\therefore$ equilibrium is <i>stable</i>	M1 A1, A1 (3) <b>(16 marks)</b>

Question Number	Scheme	Marks
5.	<p>(a) Auxiliary Equation.: <math>m^2 + 2m + 2 = 0, \Rightarrow m = -1 \pm i</math></p> <p><math>\therefore</math> Complementary. Function is: <math>x = e^{-t} (A \cos t + B \sin t)</math></p> <p>Let <math>x = p \cos 2t + q \sin 2t, \dot{x} = -2p \sin 2t + 2q \cos 2t, \ddot{x} = -4x</math></p> <p>Sub. in D.E.</p> $-2p \cos 2t - 2q \sin 2t - 4p \sin 2t + 4q \cos 2t = 12 \cos 2t - 6 \sin 2t$ $-2p + 4q = 12, -4p - 2q = -6$ $-10p = 0 \Rightarrow p = 0, q = 3$ <p><math>\therefore x = 3 \sin 2t + e^{-t} (A \cos t + B \sin t)</math></p> <p><math>t = 0, x = 0 \Rightarrow 0 = A</math></p> $\dot{x} = 6 \cos 2t - e^{-t} B \sin t + e^{-t} B \cos t$ <p><math>t = 0, \dot{x} = 0 \Rightarrow 0 = 6 + B \therefore B = -6</math></p> <p><math>\therefore x = 3 \sin 2t - 6 e^{-t} \sin t</math></p> <p>(b) <math>\dot{x} = 6[\cos 2t + e^{-t} \sin t - e^{-t} \cos t]</math></p> <p>Sub <math>t = \frac{\pi}{4} \dot{x} = 6[\cos 2t + e^{-t} - 6 e^{-t} \cos t]</math></p> $\dot{x} = 6 \left[ 0 + e^{-\frac{\pi}{4}} \times \frac{1}{\sqrt{2}} - e^{-\frac{\pi}{4}} \times \frac{1}{\sqrt{2}} \right] = 0$ <p><math>\therefore P</math> comes to instantaneous rest when <math>t = \frac{\pi}{4}</math></p> <p>(c) sub <math>t = \frac{\pi}{4}</math> in <math>x = 3 \sin \frac{\pi}{2} - 6 e^{-\frac{\pi}{4}} \frac{1}{\sqrt{2}}, = 1.07</math></p> <p>(d) <math>t \rightarrow \infty \quad x \approx 3 \sin 2t,</math> approximate period is <math>\pi</math></p>	<p>M1, A1</p> <p>M1 ft</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>B1</p> <p>M1</p> <p>A1 (11)</p> <p>M1</p> <p>A1 (2)</p> <p>M1, A1 (2)</p> <p>M1, A1 (2)</p> <p>(17 marks)</p>

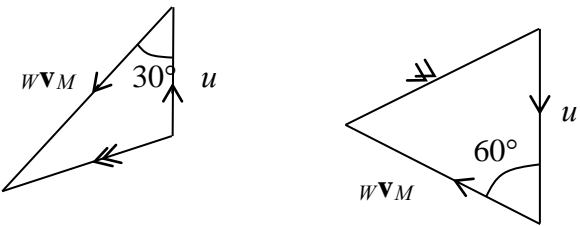
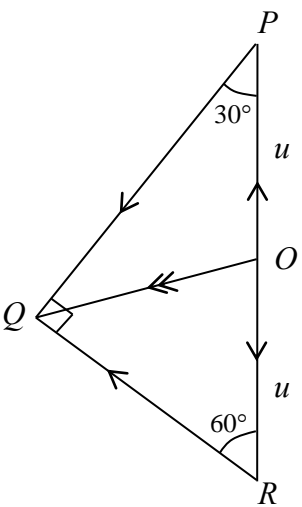
Question Number	Scheme	Marks
<p>6. (a)</p>	 <p><math>P</math> before: <math>\rightarrow \frac{13u}{12} \cos \alpha = u</math>, <math>\uparrow \frac{13u}{12} \sin \alpha = \frac{5u}{12}</math></p> <p><math>\rightarrow u</math>                      <math>\rightarrow 0</math>                      <math>\rightarrow v</math>                      <math>\rightarrow \frac{3u}{5}</math></p> <p><math>\bullet</math>                                      <math>\bullet</math>                                      <math>\bullet</math>                                      <math>\bullet</math></p> <p><math>m</math>                                      <math>2m</math>                                      <math>m</math>                                      <math>2m</math></p> <p>PCLM (<math>\rightarrow</math>)                      <math>mu = mv + 2m \frac{3u}{5}, \Rightarrow v = \frac{-u}{5}</math>, i.e. <math>\frac{u}{5} // CB</math></p> <p>(b) NLI <math>\rightarrow eu = v_2 - v_1 \Rightarrow eu = \frac{3u}{5} - \frac{u}{5}</math>, i.e. <math>e = \frac{4}{5}</math></p> <p>(c) <math>Q \rightarrow C</math> <math>t_1 = \frac{d_1}{3u/5} = \frac{5d_1}{3u}</math></p> <p><math>P</math> travels <math>\frac{u}{5} \times \frac{5d_1}{3u} = \frac{d_1}{3}</math> in direction <math>CB</math></p> <p><math>\therefore P</math> is <math>d_1 + \frac{d_1}{3} = \frac{4d_1}{3}</math> from <math>w</math> (*)</p> <p>(d) After hitting <math>w</math>, <math>Q</math> has speed <math>\frac{3u}{10}</math> in direction <math>CB</math></p> <p>Velocity of <math>Q</math> relative to <math>P</math> in direction <math>CB</math> is <math>\frac{u}{10}</math></p> <p>Time for <math>Q</math> to travel <math>\frac{4}{3}d_1</math> is: <math>\frac{4d_1}{3u} \times 10 = \frac{40d_1}{3u}</math></p> <p>Total time between collisions is: <math>\frac{40d_1}{3u} + \frac{5d_1}{3u} = \frac{15d_1}{u}</math> (*)</p> <p>(e) For collision to occur <math>P</math> must travel <math>\uparrow d_2</math> and <math>\downarrow d_2</math> in time <math>\frac{15d_1}{u}</math></p> <p><math>d_2 \uparrow</math> <math>t_2 = \frac{d_2}{5u/12} = \frac{12d_2}{5u}</math></p> <p><math>\downarrow d_2</math> velocity <math>\downarrow</math> is <math>\frac{5u}{24}</math>, <math>\therefore t_3 = \frac{d_2}{5u/24} = \frac{24d_2}{5u}</math></p> <p>Total time is <math>\frac{36d_2}{5u} = \frac{15d_1}{u}</math>,</p> <p><math>\therefore 12d_2 = 25d_1</math>, i.e. <math>d_1:d_2 = 12:25</math></p>	<p>B1, B1</p> <p>M1 A1 (4)</p> <p>M1, A1 (2)</p> <p>B1</p> <p>M1</p> <p>A1 c.s.o (3)</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>A1 c.s.o (4)</p> <p>B1</p> <p>B1, B1</p> <p>M1</p> <p>A1 (5)</p> <p><b>(18 marks)</b></p>





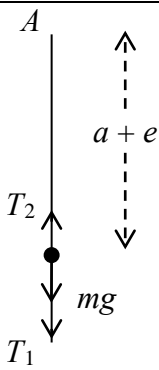
Question Number	Scheme	Marks
<p>1. (a)</p>  <p>(b)</p> $-\int \frac{v \, dv}{2v^2 + 6} = \int dx$ $x = \frac{1}{4} \ln(2v^2 + 6) + C$ $x = 0, v = 0 \Rightarrow C = \frac{1}{4} \ln 206$ $v = 0 \Rightarrow x = \frac{1}{4} \ln \frac{206}{6} \approx 0.884 \text{ m}$	$0.01a = 0.01g - 0.158 - 0.02v^2$ $a = v \frac{dv}{dx}$ $v \frac{dv}{dx} = -2v^2 - 6 (*)$	<p>M1</p> <p>M1</p> <p>A1 (3)</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>M1 A1 (5)</p> <p><b>(8 marks)</b></p>
<p>2. (a)</p>  <p>(b)</p> 	<p>vector triangle attempted</p> <p>vector triangle correct</p> <p>Explanation for <math>v &gt; u</math></p> <p>(e.g. ‘hypotenuse &gt; other sides’)</p> <p>vector triangle attempted</p> <p>right angle correctly placed</p> $\frac{BC}{AB} = \frac{AE}{ED} \quad \text{Use of similar triangles}$ $= \frac{\sqrt{(u^2 - v^2)}}{v}$	<p>M1</p> <p>A1</p> <p>A1 (3)</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>M1 A1 (5)</p> <p><b>(8 marks)</b></p>

((\*) indicates final line is given on the paper)

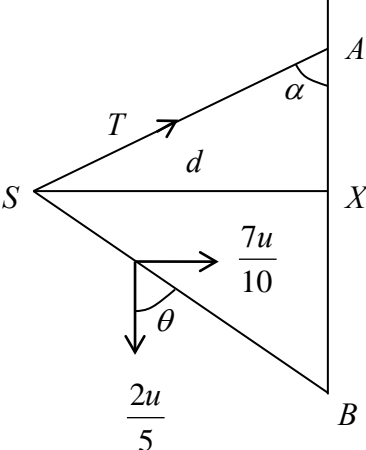
Question Number	Scheme	Marks
3.	<p><math>\mathbf{v}_W = w\mathbf{v}_M + \mathbf{v}_M</math> (used)</p>  <p>(one vector triangle)</p> <p>Combining</p>  <p> <math>P\hat{Q}R = 90^\circ</math>  <math>QR = 2u \sin 30^\circ = u</math>  <math>\Rightarrow</math> triangle <math>OQR</math> is equilateral  <math>\Rightarrow OQ = \mathbf{v}_w = u</math>                      also <math>\Rightarrow Q\hat{O}R = 60^\circ</math>                      Hence direction is from N <math>60^\circ</math> E                 </p>	<p>M1</p> <p>M1</p> <p>A1 A1</p> <p>M1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>A1 (9)</p> <p><b>(9 marks)</b></p>

Question Number	Scheme	Marks
4.	(a) Extension of string = $7a - 2a \cos \theta - a$ $= 2a(3 - \cos \theta)$	B1
	PE = $8mga \cos \theta + \frac{4mg}{5} \times \frac{4a^2}{2a} (3 - \cos \theta)^2$	B1, M1 A1
	$= 8mga \cos \theta + \frac{8mga}{5} (9 - 6 \cos \theta - \cos^2 \theta)$	M1
	$= \frac{8mga}{5} (\cos^2 \theta - \cos \theta) + C \quad (*)$	A1 (6)
	(b) $\frac{dV}{d\theta} = \frac{8mga}{5} (-2 \cos \theta \sin \theta + \sin \theta)$	M1 A1
	$= 0$	M1
	$\Rightarrow \sin \theta = 0 \text{ or } \cos \theta = \frac{1}{2}$	
	$\Rightarrow \theta = 0 \text{ or } \pi, \text{ or } \theta = \frac{\pi}{3}$	A1, A1 (5)
	(c) $\frac{d^2V}{d\theta^2} = \frac{8mga}{5} (\cos \theta + 2 \sin^2 \theta - 2 \cos^2 \theta)$	M1 A1
	$\theta = 0 \quad V'' < 0 \left( = -\frac{8mga}{5} \right) \quad \text{unstable}$	
$\theta = \pi \quad V'' < 0 \left( = -3 \times \frac{8mga}{5} \right) \quad \text{unstable}$	A1	
$\theta = \frac{\pi}{3} \quad V'' > 0 \left( = 3 \times \frac{8mga}{5} \right) \quad \text{stable}$	A1 (4)	
	<b>(15 marks)</b>	

((\*) indicates final line is given on the paper)

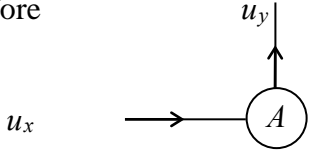
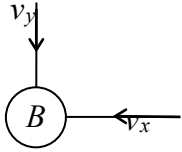
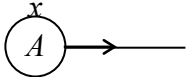
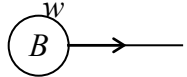
Question Number	Scheme	Marks
5. (a)	 $T_2 = T_1 + mg$ $\frac{mge}{a} = \frac{mg}{a}(2a - e) + mg$ $e = \frac{3a}{2} \Rightarrow AE = \frac{5a}{2} \quad (*)$	M1 M1 A1 A1 A1 cso (5)
(b)	$mg + \frac{mg}{a} \left( \frac{1}{2}a - x \right) - \frac{mg}{a} \left( \frac{3}{2}a + x \right) - 2m \sqrt{\frac{g}{a}} \frac{dx}{dt} = m \frac{d^2x}{dt^2}$ $\Rightarrow \frac{d^2x}{dt^2} + 2k \frac{dx}{dt} + 2k^2x = 0 \quad (*)$	M1 A3 (-1eeoo) A1 (5)
(c)	AE: $m^2 + 2km + 2k^2 = 0$ $m = -k \pm ki$ GS: $x = e^{-kt}(A \cos kt + B \sin kt)$ $t = 0, x = \frac{1}{2}a \Rightarrow A = \frac{1}{2}a$ $\frac{dx}{dt} = ke^{-kt}(A \cos kt + B \sin kt) + e^{-kt}(-kA \sin kt + kB \cos kt)$ $t = 0, \frac{dx}{dt} = 0 \Rightarrow -kA + kB = 0 \Rightarrow B = A = \frac{1}{2}a$ $x = \frac{1}{2}a e^{-kt}(\cos kt + \sin kt)$	M1 A1 A1 ft B1 M1 M1 A1 (7) <b>(17 marks)</b>

(cso = correct solution only; ft = follow through mark; (\*) indicates final line is given on the paper; eeoo = each error or omission)

Question Number	Scheme	Marks	
<p>6. (a)</p> <p>(b)</p> <p>(c)</p>	<p>No impulse perpendicular to line of centres  <math>\Rightarrow</math> velocity perpendicular to line of centres unchanged = <math>U \cos \alpha</math> (*)</p> <p>(<math>\leftarrow</math>): CLM <math>U \sin \alpha = v + w</math></p> <p>NLI <math>eU \sin \alpha = w - v</math></p> <p><math>\Rightarrow v = \frac{1}{2} U \sin \alpha (1 - e)</math></p>	<p>B1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1 A1 (7)</p>	
	<p>Component perpendicular to wall = <math>v \sin \alpha + U \cos \alpha \cos \alpha</math></p> <p><math>= \frac{1}{2} U \sin^2 \alpha (1 - e) + U \cos^2 \alpha</math></p> <p><math>= \frac{1}{2} U (\sin^2 \alpha - e \sin^2 \alpha + 2 - 2 \sin^2 \alpha)</math></p> <p><math>= \frac{1}{2} U [2 - \sin^2 \alpha (1 + e)]</math> (*)</p> <p>Component parallel to wall = <math>U \cos \alpha \sin \alpha - v \cos \alpha</math></p> <p><math>= U \cos \alpha \sin \alpha - \frac{1}{2} U \sin \alpha \cos \alpha (1 - e)</math></p> <p><math>= \frac{1}{2} U \cos \alpha \sin \alpha (1 + e)</math> (*)</p>	<p>M1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>A1 (6)</p>	
	<p><math>e = \frac{2}{3}, \tan \alpha = \frac{3}{4}</math></p> <p>Component perpendicular to wall = <math>\frac{1}{2} U (2 - \frac{9}{25} \times \frac{5}{3}) = \frac{7u}{10}</math></p> <p>Component parallel to wall = <math>\frac{1}{2} U \times \frac{4}{5} \times \frac{3}{12} \times \frac{5}{3} = \frac{2u}{5}</math></p>	<p>B1</p> <p>B1</p>	
	 <p>Distance of A from X = <math>d \cot \theta = \frac{4d}{3}</math></p> <p><math>BX = d \cot \theta</math></p> <p><math>\cot \theta = \frac{2u}{5} \times \frac{7u}{10} = \frac{4}{7}</math></p> <p><math>\therefore</math> Total distance <math>AB = \frac{4d}{3} + \frac{4d}{7}</math></p> <p><math>= \frac{40d}{21}</math></p>	<p>B1</p> <p>M1</p> <p>A1</p> <p>A1 (5)</p>	
	<p><b>(18 marks)</b></p>		

((\*) indicates final line is given on the paper)

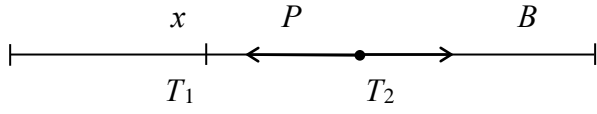
EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME

Question Number	Scheme	Marks
1.	<p>N2L <math>-2v = 3a</math></p> <p><math>-2v = 3v \frac{dv}{ds}</math></p> <p><math>s = -\frac{3}{2}v(+c)</math> or <math>v = -\frac{2}{3}s(+c)</math> cancelling <math>v</math> and integrating</p> <p><math>s = 0, v = 5 \Rightarrow c = \frac{15}{2}</math> or <math>s = \left[-\frac{3}{2}v\right]_5^2</math></p> <p>Distance travelled is 4.5 m</p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p><b>(5 marks)</b></p>
2.	<p>(a) Before</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;">  </div> <div style="text-align: center;">  </div> </div> <p>A: <math>\uparrow</math> <math>u_y = 2.5 \sin \alpha = 2.5 \times \frac{4}{5} = 2 \text{ (ms}^{-1}\text{)}</math> either</p> <p><math>\rightarrow</math> <math>u_x = 2.5 \cos \alpha = 2.5 \times \frac{3}{5} = 1.5 \text{ (ms}^{-1}\text{)}</math> both</p> <p>B: <math>\downarrow</math> <math>v_y = 1.3 \sin \beta = 1.3 \times \frac{12}{13} = 1.2 \text{ (ms}^{-1}\text{)}</math> either</p> <p><math>\leftarrow</math> <math>v_x = 1.3 \cos \beta = 1.3 \times \frac{5}{13} = 0.5 \text{ (ms}^{-1}\text{)}</math> both</p> <p>(b) After</p> <div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;">  </div> <div style="text-align: center;">  </div> </div> <p>LM <math>2x + w = 3 - 0.5 \text{ (= 2.5)}</math></p> <p>NEL <math>w - x = \frac{1}{2} \times 2 \text{ (= 1)}</math></p> <p>Solving <math>x = 0.5, y = 1.5</math> M1 solving for either</p> <p>Speed of A is <math>\sqrt{(2^2 + 0.5^2)} = \sqrt{4.25} \approx 2.1 \text{ (ms}^{-1}\text{)}</math> M1 either</p> <p>Speed of B is <math>\sqrt{(1.2^2 + 1.5^2)} = \sqrt{3.69} \approx 1.9 \text{ (ms}^{-1}\text{)}</math></p> <p><i>Note: Not 1 d.p. loses maximum of one mark</i></p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(4)</p> <p>M1 A1 ft</p> <p>M1 A1 ft</p> <p>M1 A1</p> <p>M1 A1</p> <p>A1</p> <p>(9)</p> <p><b>(13 marks)</b></p>

EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME


Question Number	Scheme	Marks
3.	(a) $AP = s - AD - DE$ $= s - L - 2L \sin \theta$	M1 A1 (2)
	(b) $V(\theta) = 2 \times 2mg \times L \cos \theta + \dots$ $= \dots + mg(2L \cos \theta - AP)$ $= 4mgL \cos \theta + mg(2L \cos \theta + 2L \sin \theta) (+C)$ $= 2mgL(3 \cos \theta + \sin \theta) + \text{constant} (*) \quad \text{cso}$	B1 M1 M1 A1 (4)
	(c) $V'(\theta) = 2mgL(-3 \sin \theta + \cos \theta)$ $= 0$ $\tan \theta = \frac{1}{3}$ $\theta \approx 18^\circ \quad \text{awrt } 18^\circ, 0.32^c$	M1 M1 A1 A1 (4)
	(d) $V''(\theta) = 2mgL(-3 \cos \theta - \sin \theta)$ $\left( V''\left(\arctan \frac{1}{3}\right) = -2\sqrt{10}mgL \right)$ $V''(\theta) < 0, \text{ for any acute } \theta$ Equilibrium is <u>unstable</u> ft any acute $\theta$	M1 A1  M1 A1 ft (4) <b>(14 marks)</b>

EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME

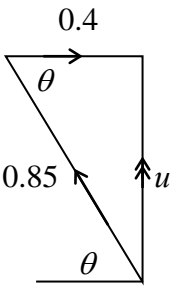
Question Number	Scheme	Marks
4.	<p>(a) </p> <p>HL <math>T_1 = \frac{2mk^2L(0.5L+x)}{L}</math>      either      M1</p> <p>HL <math>T_2 = \frac{2mk^2L(0.5L-x)}{L}</math>      both      A1</p> <p>N2L <math>T_2 - T_1 - 2mk \frac{dx}{dt} = m \frac{d^2x}{dt^2}</math>      M1 A1, A1</p> <p><math>4mk^2x - 2mk \frac{dx}{dt} = m \frac{d^2x}{dt^2}</math></p> <p><math>\frac{d^2x}{dt^2} + 2k \frac{dx}{dt} + 4k^2x = 0</math> *      cso      A1      (6)</p> <p>(b) <math>m^2 + 2km + 4m^2 = 0</math>      ae      M1</p> <p><math>m = -k \pm k\sqrt{3}i</math>      M1</p> <p><math>x = e^{-kt} (A \cos \sqrt{3}kt + B \sin \sqrt{3}kt)</math>      oe      A1</p> <p><math>t = 0, x = \frac{L}{2} \Rightarrow A = \frac{L}{2}</math>      B1</p> <p><math>\dot{x} = -k e^{-kt} (A \cos \sqrt{3}kt + B \sin \sqrt{3}kt)</math></p> <p><math>\quad + \sqrt{3}k e^{-kt} (-A \sin \sqrt{3}kt + B \cos \sqrt{3}kt)</math>      M1</p> <p><math>t = 0, \dot{x} = 0 \Rightarrow 0 = -kA + \sqrt{3}kB</math>      M1</p> <p><math>B = \frac{1}{\sqrt{3}} A = \frac{L}{2\sqrt{3}}</math>      A1</p> <p><math>AP = 1.5L + \frac{L}{2\sqrt{3}} e^{-kt} (\sqrt{3} \cos \sqrt{3}kt + \sin \sqrt{3}kt)</math>      oe      A1      (8)</p> <p><i>Alternatives forms of the answer are given on the next page</i></p>	<p>(14 marks)</p>



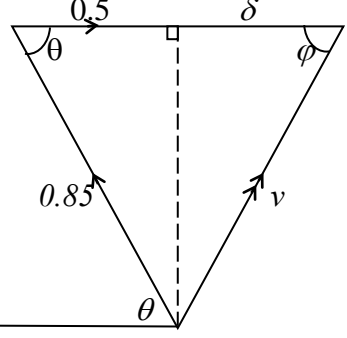
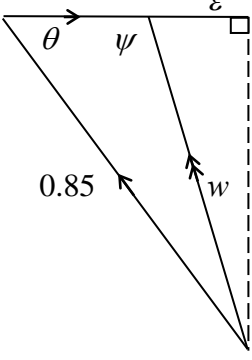
EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME

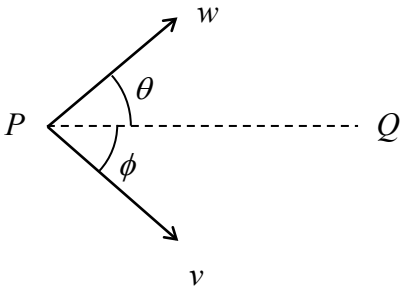
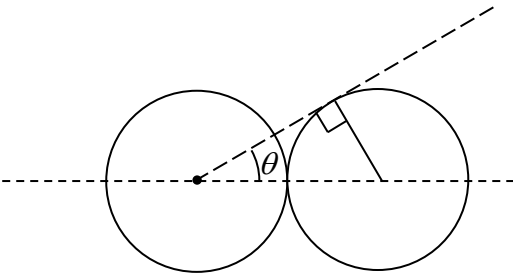
Question Number	Scheme	Marks
<p>4.</p>	<p>(b) <i>Alternative form of the General Solution</i> As before</p> $x = Ae^{-kt} \cos(\sqrt{3kt} - \varepsilon)$ $t = 0, x = \frac{L}{2} \Rightarrow \frac{L}{2} = A \cos(-\varepsilon) (= A \cos \varepsilon)$ $\dot{x} = -kAe^{-kt} \cos(\sqrt{3kt} - \varepsilon) - \sqrt{3k}Ae^{-kt} \sin(\sqrt{3kt} - \varepsilon)$ $t = 0, \dot{x} = 0 \Rightarrow 0 = -kA \cos \varepsilon - \sqrt{3k}A \sin(-\varepsilon)$ <p>Leading to <math>\tan \varepsilon = \frac{1}{\sqrt{3}} \Rightarrow \varepsilon = \frac{\pi}{6}</math> and <math>A = \frac{L}{\sqrt{3}}</math> both</p> $AP = 1.5L + \frac{L}{\sqrt{3}} e^{-kt} \cos\left(\sqrt{3kt} - \frac{\pi}{6}\right)$ <p>Note: Another possible trig form is <math>\sin\left(\sqrt{3kt} + \frac{\pi}{3}\right)</math></p>	<p>M1 M1 A1 B1 M1 M1 A1 A1 (8)</p>
<p>5.</p>	<p>(a) Before After</p>  <p>→ LM <math>600u = 800x</math>          → NEL <math>x = eu</math>  <math>e = 0.75</math></p> <p>(b) Van N2L <math>-500 = 800a</math>  <math>0^2 = x^2 - 2 \times 0.625 \times 45</math>, <math>x^2 = 56.25</math> (<math>x = 7.5</math>)          Car N2L <math>-300 = 600a</math>  <math>0^2 = v^2 - 2 \times 0.5 \times 21</math>, <math>v^2 = 21</math>          From (a) NEL <math>u = \frac{4}{3} \times 7.5 = 10</math>  <math>V^2 = 10^2 + 21</math>, <math>\Rightarrow V = 11</math> (<math>\text{ms}^{-1}</math>) cao</p>	<p>M1 A1 M1 A1 A1 (5) M1 M1, A1 M1 M1, A1 M1 M1, A1 (9) <b>(14 marks)</b></p>

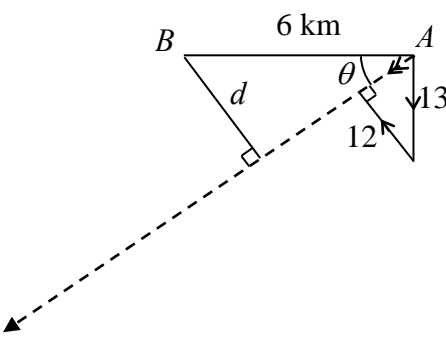
EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME

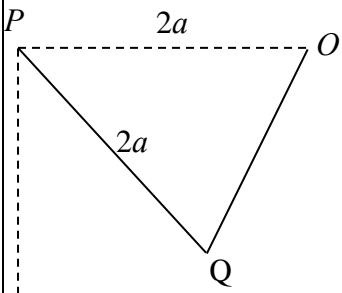
Question Number	Scheme	Marks	
<p>6.</p> 	<p>(a) Vector ! or ←</p> $\cos \theta = \frac{0.4}{0.85}$ $\theta \approx 61.9^\circ$ <p>(b) <math>u = \sqrt{(0.85^2 - 0.4^2)}</math> or <math>u = 0.85 \sin \theta</math></p> $t = \frac{60}{u} = \frac{60}{0.75} = 80 \text{ (s)}$	<p>M1 M1 A1 (3) M1 M1 A1 (3)</p>	
	<p>(c) <math>\mathbf{v}_{N \text{ rel } W} = -0.4\mathbf{i} (+0.75\mathbf{j})</math> Allow for <math>\pm 0.4\mathbf{i}</math></p> $\mathbf{v}_N = \mathbf{v}_{N \text{ rel } W} + 0.5\mathbf{i} = 0.1\mathbf{i} + (0.75\mathbf{j})$ $t = \frac{40}{0.75} = \frac{160}{3}$ $\delta = 0.1 \times \frac{160}{3} = \frac{16}{3}$ <p>awrt 5.3</p>	<p>M1 A1 M1 M1 A1 (5)</p>	
	<p>(d) As in (c) <math>\mathbf{v}_N = -0.2\mathbf{i} + 0.75\mathbf{j}</math> <math>\pm 0.2\mathbf{i}</math></p> $t = \frac{20}{0.75} = \frac{80}{3}$ $\delta = 0.2 \times \frac{80}{3} = \frac{16}{3}$ <p>Hence N lands at D</p> <p>cso</p>	<p>M1 M1 M1 A1 (4)</p>	
	<p>Notes:</p> <ol style="list-style-type: none"> <li>In (c) and (d), the candidate can take components without using vectors. Mark as vector method.</li> <li>After the first line in (d), the result is clear by proportion. Allow as long as some explanation given.</li> <li><math>\cos \theta = \frac{8}{17} = 0.4705\dots</math>, <math>\sin \theta = \frac{15}{17} = 0.8823\dots</math></li> <li>Alternatives to (c) and (d), using vector triangles are given on the next page.</li> </ol>		<p>(15 marks)</p>

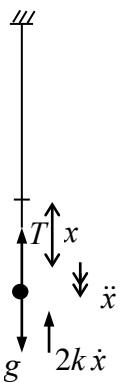
EDEXCEL 6680 MECHANICS M4 JANUARY 2004 MARK SCHEME

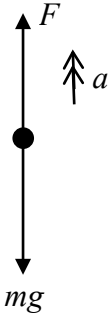
Question Number	Scheme	Marks
<p>6.</p> <p>(c)</p> <p>(d)</p>	<p><i>Alternatives to (c) and (d)</i></p> <div style="display: flex; justify-content: space-between;"> <div style="width: 45%;">  </div> <div style="width: 50%;"> <math display="block">v^2 = 0.5^2 + 0.85^2 - 2 \times 0.5 \times 0.85 \times \cos \theta</math> <math display="block">= 0.5725 \quad (v = \frac{\sqrt{229}}{20} \approx 82.4^\circ)</math> <math display="block">\frac{\sin \phi}{0.85} = \frac{\sin \theta}{v}</math> <math display="block">\sin \phi = \frac{15}{\sqrt{229}} \quad (\approx 0.9912; \phi \approx 82.4^\circ)</math> <math display="block">\frac{\delta}{40} = \cot \phi; \quad \delta = 40 \times \frac{2}{5} = \frac{16}{3} \text{ awrt } 5.3</math> </div> </div> <div style="display: flex; justify-content: space-between;"> <div style="width: 45%;">  </div> <div style="width: 50%;"> <math display="block">w^2 = 0.2^2 + 0.85^2 - 2 \times 0.2 \times 0.85 \times \cos \theta</math> <math display="block">= 0.6025 \quad \left( w = \frac{\sqrt{241}}{20} \approx 0.7762... \right)</math> <math display="block">\frac{\sin \psi}{0.85} = \frac{\sin \theta}{w}</math> <math display="block">\sin \psi = \frac{15}{\sqrt{241}} \quad (\approx 0.9662; \psi \approx 104.9^\circ)</math> <p><math>\psi = 75.1^\circ</math> gains M1</p> <math display="block">\frac{\epsilon}{20} = \cot(180^\circ - \psi) = \frac{4}{15}</math> <math display="block">\epsilon = \frac{16}{3} = \delta</math> <p>Hence <i>N</i> lands at <i>D</i>      cso</p> </div> </div> <p><i>Note: Exact working is needed for final A1 but all previous marks in (c) and (d) may be gained by approximate working.</i></p>	<p>M1</p> <p>M1</p> <p>A1</p> <p>M1 A1 (5)</p> <p>M1</p> <p>M1</p> <p>M1</p> <p>A1 (4)</p>

Question Number	Scheme	Marks
<p>1. (a)</p>  <p>(b)</p>	$v_A = v_{AW} + v_W$ $\Rightarrow \begin{pmatrix} k \\ 0 \end{pmatrix} = \begin{pmatrix} v \cos \phi \\ -v \sin \phi \end{pmatrix} + \begin{pmatrix} w \cos \theta \\ w \sin \theta \end{pmatrix}$ $\Rightarrow v \sin \phi = w \sin \theta^*$ $k = v \sin \phi + w \sin \theta$ $= \frac{v \sqrt{v^2 - w^2 \sin^2 \theta}}{v} + w \cos \theta$ $= \sqrt{v^2 - w^2 \sin^2 \theta} + w \cos \theta$	<p>M1</p> <p>A1 (2)</p> <p>M1 A1</p> <p>M1</p> <p>A1 (4)</p> <p><b>(6 marks)</b></p>
<p>2.</p> 	$\sin \theta = \frac{a}{2a}$ $\Rightarrow \theta = 30^\circ$ $v_1 + v_2 = u \cos \theta$ $-v_1 + v_2 = eu \cos \theta$ $\frac{u \sin \theta}{v_1} = \tan (\theta + 30^\circ) \text{ (or equivalent)}$ <p>Producing an equation in <math>e</math> only</p> $e = \frac{1}{3}$	<p>M1</p> <p>A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1</p> <p>A1 c.s.o</p> <p><b>(11 marks)</b></p>

Question Number	Scheme	Marks
<p>3. (a)</p> <p>(b)</p> <p>(c)</p>	 <p>Vector <math>\Delta</math></p> $\cos \theta = \frac{12}{13}$ $(\theta = 22.6^\circ)$ <p>Course is <math>360^\circ - 22.6^\circ</math>  <math>= 337^\circ</math> (AWRT)</p> $v = \sqrt{13^2 - 12^2} = 5$ $t = \frac{6 \cos \theta}{5} = 1.107$ <p>Time is 1.06 p.m.</p> $d = 6 \sin \theta = 6 \times \frac{5}{13} = 2.31 \text{ km}$ <p>(AWRT 2.3 km)</p>	<p>M1 A1</p> <p>M1</p> <p>A1 (4)</p> <p>M1 A1 (2)</p> <p><b>(11 marks)</b></p>

Question Number	Scheme	Marks
<p>4. (a)</p> 	<p><math>OQ = 4a \sin \theta</math></p> <p><math>V = (-) mga \sin 2\theta; + \frac{mg}{2\sqrt{3}2a} (4a \sin \theta - a)^2 + C</math></p> <p><math>= -mga \sin 2\theta + \frac{mga^2}{4a\sqrt{3}} (16 \sin^2 \theta - 8 \sin \theta + 1) + C</math></p> <p><math>= -mga \sin 2\theta + \frac{mga}{4\sqrt{3}} (8(1 - \cos 2\theta) - 8 \sin \theta) + C</math></p> <p>i.e. <math>V = -\frac{mga}{\sqrt{3}} (2 \cos 2\theta + \sqrt{3} \sin 2\theta + 2 \sin \theta) + C</math> *</p> <p>(b) <math>V'(\theta) = -\frac{mga}{\sqrt{3}} (-4 \sin 2\theta + 2\sqrt{3} \cos 2\theta + 2 \cos \theta)</math></p> <p><math>V'(\frac{\pi}{6}) = -\frac{mga}{\sqrt{3}} (-2\sqrt{3} + 2\sqrt{3} \frac{1}{2} + 2 \frac{\sqrt{3}}{2}) = 0</math></p> <p>(c) <math>V''(\theta) = \frac{mga}{\sqrt{3}} (+8 \cos 2\theta + 4\sqrt{3} \sin 2\theta + 2 \sin \theta)</math></p> <p>Hence, <math>V''(\frac{\pi}{6}) = \frac{11mga}{\sqrt{3}} &gt; 0 \therefore</math> stable</p>	<p>B1</p> <p>B1; M1 A1</p> <p>M1</p> <p>M1</p> <p>A1 c.s.o (7)</p> <p>M1 A1</p> <p>M1 A1 (4)</p> <p>M1 A1</p> <p>M1 A1 c.s.o (4)</p> <p><b>(15 marks)</b></p>

Question Number	Scheme	Marks
<p>5. (a)</p>	 <p style="text-align: center;"><math>R(\downarrow), mg - 2k \dot{x} m - T = m \ddot{x}</math></p> $g - 2k \dot{x} - \frac{2ak^2 x}{a} = \ddot{x}$ $\Rightarrow \ddot{x} + 2k \dot{x} + 2k^2 x = g \quad *$	<p>M1</p> <p>A1 c.s.o (4)</p>
<p>(b)</p>	$t = 0, x = a: \quad a = D + \frac{g}{2k^2} \Rightarrow D = a - \frac{g}{2k^2}$ $\dot{x} = -ke^{-kt}(C \sin kt + D \cos kt) + -ke^{-kt}(C \cos kt - D \sin kt)$ $t = 0, \dot{x} = 0: \quad 0 = -kD + kC \Rightarrow C = D$ $\Rightarrow C = a - \frac{g}{2k^2}$	<p>M1 A1</p> <p>M1 A1</p> <p>A1 (5)</p>
<p>(c)</p>	$\dot{x} = 0 \Rightarrow C(\sin kt + \cos kt) + C(\cos kt - \sin kt)$ $\Rightarrow \sin kt = 0$ $\Rightarrow kt = \pi$ $\Rightarrow t = \frac{\pi}{k}$	<p>M1</p> <p>A1 ft</p> <p>A1 (3)</p>
<p>(d)</p>	<p>When <math>t = \frac{\pi}{k}, x = -De^{-\pi} + \frac{g}{2k^2}</math></p> $\frac{g}{2k^2} - e^{-\pi} \left( a - \frac{g}{2k^2} \right)$ $\Rightarrow xe^{\pi} = \frac{g}{2k^2} (e^{\pi} + 1) - a$ <p>&gt; 0 (given)</p> $\Rightarrow g(e^{\pi} + 1) > 2k^2 a \quad *$	<p>M1</p> <p>A1 ft</p> <p>M1</p> <p>A1 c.s.o (4)</p> <p><b>(16 marks)</b></p>

Question Number	Scheme	Marks
<p>6. (a)</p> 	$F = \frac{kmg}{v}$ $R(\uparrow), F - mg = ma$ $\frac{kmg}{v} - mg = mv \frac{dv}{dx}$ $g(k - v) = v^2 \frac{dv}{dx} \quad *$	<p>B1</p> <p>M1</p> <p>M1</p> <p>A1 (4)</p>
<p>(b)</p>	$g dx = \frac{v^2}{k - v} dv$ $\int g dx = \int -v - k + \frac{k^2}{k - v} dv$ $gx = -\frac{v^2}{2} - kv - k^2 \ln(k - v) + (c)$ <p><math>x = 0, v = 0</math></p> $0 = 0 - 0 - k^2 \ln k + c$ $c = k^2 \ln k$ $gx = -\frac{v^2}{2} - kv - k^2 \ln \left( \frac{k}{k - v} \right) \quad *$	<p>M1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1</p> <p>A1 (7)</p>
<p>(c)</p>	<p>Work done by engine = Energy gain</p> $kmg t = \frac{1}{2} mv^2 + mgx$ $kmg t = mk^2 \ln \left( \frac{k}{k - v} \right) - mkv$ $\Rightarrow t = \frac{k}{g} \ln \left( \frac{k}{k - v} \right) - \frac{v}{g}$	<p>M1 A1</p> <p>M1</p> <p>A1 (5)</p> <p><b>(16 marks)</b></p>



1. (a) Impulse on  $A$  is in the direction of the line of centres.

$$\text{Impulse on } A = \Delta(mv) = m(-2\mathbf{i} + 5\mathbf{j}) - m(\mathbf{i} + 2\mathbf{j}) = m(-3\mathbf{i} + 3\mathbf{j}).$$

Therefore direction of line of centres is  $(-\mathbf{i} + \mathbf{j})$ . A unit vector in this direction is  $\frac{(-\mathbf{i} + \mathbf{j})}{\sqrt{2}}$ .

- (b) Let velocity of  $b$  after collision be  $v_1\mathbf{i} + v_2\mathbf{j}$

$$\text{Momentum conserved: } m(\mathbf{i} + 2\mathbf{j}) + 5m(-\mathbf{i} + 3\mathbf{j}) = m(-2\mathbf{i} + 5\mathbf{j}) + 5m(v_1\mathbf{i} + v_2\mathbf{j})$$

$$\begin{aligned} \text{Cancel } m \text{ and equate coefficients:} \quad & \mathbf{i}: -4 = -2 + 5v_1 & v_1 = -\frac{2}{5} \\ & \mathbf{j}: 17 = 5 + 5v_2 & v_2 = \frac{12}{5} \end{aligned}$$

$$\text{Velocity of } B \text{ after collision} = -\frac{2}{5}\mathbf{i} + \frac{12}{5}\mathbf{j}.$$

2. (a) Velocity of wind relative to man =  $\mathbf{V}_{WM} = \mathbf{V}_W - \mathbf{V}_M$ .  $\therefore v(3\mathbf{i} - 4\mathbf{j}) = \mathbf{V}_W - u\mathbf{j}$

$$\text{Similarly } w\mathbf{i} = \mathbf{V}_W - \frac{1}{5}u(-3\mathbf{i} + 4\mathbf{j}).$$

$$\text{Equate the two expressions for } \mathbf{V}_M \text{ that these produce: } v(3\mathbf{i} - 4\mathbf{j}) + u\mathbf{j} = w\mathbf{i} + \frac{1}{5}u(-3\mathbf{i} + 4\mathbf{j})$$

$$\begin{aligned} \text{Equate coefficients:} \quad & \mathbf{i}: -3v = w - \frac{3}{5}u \\ & \mathbf{j}: -4v + u = \frac{4}{5}u \quad \therefore v = \frac{1}{20}u \end{aligned}$$

$$(b) \mathbf{V}_W = \frac{1}{20}u(3\mathbf{i} - 4\mathbf{j}) + u\mathbf{j} = \frac{1}{20}u(3\mathbf{i} + 16\mathbf{j})$$

3. Treat  $B$  when  $t = 0$  as the origin.

$$\mathbf{r}_A = 12t\mathbf{i} + 4\mathbf{j}. \quad \mathbf{r}_B = 16t\left(\frac{\sqrt{3}}{2}\mathbf{i} + \frac{1}{2}\mathbf{j}\right)$$

$$\mathbf{BA} = \mathbf{r}_A - \mathbf{r}_B = \mathbf{i}(12t - 8t\sqrt{3}) + \mathbf{j}(4 - 8t)$$

$$\text{Length of } \mathbf{AB} = \sqrt{\left((12t - 8t\sqrt{3})^2 + (4 - 8t)^2\right)} = \sqrt{\left((144 - 192\sqrt{3} + 192)t^2 + 16 - 64t + 64t^2\right)}$$

Minimum when derivative of terms inside square root = 0:

$$2t(144 - 192\sqrt{3} + 192) - 64 + 128t = 0, \quad t \approx 0.47. \quad (\text{Minimum because this is a +ve quadratic.})$$

Substitute back into length of  $\mathbf{AB}$ :  $|\mathbf{AB}| \approx 0.90 \text{ km.}$

4. Apply  $F = ma$ :  $m \frac{dv}{dt} = \frac{RU}{v} - R$

Separate the variables:  $\int_{\frac{u}{4}}^{\frac{u}{2}} \frac{mv dv}{R(U-v)} = \int_0^T dt$ .

$$\frac{m}{R} \int_{\frac{u}{4}}^{\frac{u}{2}} \left( -1 + \frac{U}{(U-v)} \right) dv = [t]_0^T = T$$

$$\frac{m}{R} [-v - U \ln|U-v|]_{\frac{u}{4}}^{\frac{u}{2}} = T$$

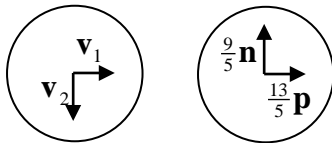
$$T = \frac{m}{R} \left( \left( -\frac{1}{2}U - U \ln\left(\frac{1}{2}U\right) \right) - \left( -\frac{1}{4}U - U \ln\left(\frac{3}{4}U\right) \right) \right)$$

$$T = \frac{mU}{R} \left( -\frac{1}{4} + \ln\left(\frac{3}{2}\right) \right)$$

5. (Note: error in question:  $\mathbf{p} = +\frac{4}{5}\mathbf{i} + \frac{3}{5}\mathbf{j}$ .)

(a)  $\frac{9}{5}\mathbf{n} + \frac{13}{5}\mathbf{p} = \frac{9}{5}\left(-\frac{3}{5}\mathbf{i} + \frac{4}{5}\mathbf{j}\right) + \frac{13}{5}\left(\frac{4}{5}\mathbf{i} + \frac{3}{5}\mathbf{j}\right) = \frac{25}{25}\mathbf{i} + \frac{75}{25}\mathbf{j} = \mathbf{i} + 3\mathbf{j}$

(b) Before After



No impulse parallel to the wall so velocity parallel to wall unchanged:  $\mathbf{v}_1 = \frac{13}{5}\mathbf{p}$

Newton's law of Restitution perpendicular to the wall:  $e\mathbf{v}_2 = -\frac{9}{5}\mathbf{n}$

Put in values:  $\frac{9}{16}\mathbf{v}_2 = -\frac{9}{5}\left(-\frac{3}{5}\mathbf{i} + \frac{4}{5}\mathbf{j}\right)$ ,  $\mathbf{v}_2 = -\frac{16}{5}\left(-\frac{3}{5}\mathbf{i} + \frac{4}{5}\mathbf{j}\right) = \frac{39}{25}\mathbf{i} - \frac{64}{25}\mathbf{j}$

$$\mathbf{v}_1 + \mathbf{v}_2 = \frac{13}{5}\left(\frac{4}{5}\mathbf{i} + \frac{3}{5}\mathbf{j}\right) - \frac{16}{5}\left(-\frac{3}{5}\mathbf{i} + \frac{4}{5}\mathbf{j}\right) = 4\mathbf{i} - \mathbf{j}$$

(c) Change in KE =  $\frac{1}{2} \times \frac{1}{2} \times (4^2 + 1^2) - \frac{1}{2} \times \frac{1}{2} \times (3^2 + 1^2) = 1.75 \text{ J}$

6. (a) Take  $O$  as zero p.e.

$$\text{Mechanical potential energy (} mgh \text{)} = -mga \cos 2\theta$$

$$\text{Elastic potential energy } \left( \frac{\lambda x^2}{2l} \right) = \frac{1}{2} \times \frac{4mg}{\frac{5}{4}a} \left( 2a \cos 2\theta - \frac{5}{4}a \right)^2$$

$$\begin{aligned} \text{Total p.e.} &= -mga(2\cos^2 \theta - 1) + \frac{8mg}{5a} \left( \frac{8a \cos \theta - 5a}{4} \right)^2 \\ &= -2mga \cos^2 \theta + mga + \frac{mga}{10} (8\cos \theta - 5)^2 \\ &= \frac{mga}{10} (8\cos \theta - 5)^2 - 2mga \cos^2 \theta + c \end{aligned}$$

(change of constant with referral  
of p.e. to any other zero position.)

- (b) Equilibrium when p.e. is max/min so  $\frac{dE}{d\theta} = 0$

$$\frac{dE}{d\theta} = \frac{mga}{10} \times 16 \times (8\cos \theta - 5)(-\sin \theta) + 4mga \cos \theta \sin \theta = 0$$

$$mga \sin \theta \left( -\frac{64}{5} \cos \theta + 8 + 4 \cos \theta \right) = 0$$

$$mga \sin \theta \left( 8 - \frac{44}{5} \cos \theta \right) = 0$$

$$\sin \theta = 0, \quad \theta = 0$$

or

$$\cos \theta = \frac{10}{11}, \quad \theta = 24.6^\circ$$

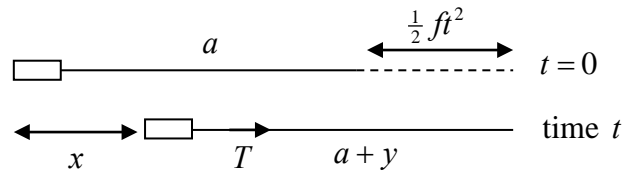
- (c)  $\frac{d^2 E}{d\theta^2} = mga \sin \theta \left( \frac{44}{5} \sin \theta \right) + mga \cos \theta \left( 8 - \frac{44}{5} \cos \theta \right)$

When  $\theta = 0$ ,  $\frac{d^2 E}{d\theta^2} = mga \left( 8 - \frac{44}{5} \right) = -\frac{4}{5} mga$  which is  $< 0$  so max  $E$  so unstable.

When  $\theta = 24.6^\circ$ ,  $\frac{d^2 E}{d\theta^2} = mga \left( \frac{44}{5} \left( 1 - \left( \frac{10}{11} \right)^2 \right) + \frac{10}{11} \left( 8 - \frac{44}{5} \times \frac{10}{11} \right) \right) = \frac{84}{55} mga$

which is  $> 0$  so min  $E$  so stable.

7. (a)



At time  $t$ :

- the particle has moved  $x$ ,
- the string is length  $(a+y)$ ,
- the end of the string has moved  $\frac{1}{2}ft^2$ .  $\therefore a + \frac{1}{2}ft^2 = x + a + y$ ,  $\therefore x + y = \frac{1}{2}ft^2$ .

(b)  $F = ma$  to particle:  $T = m\ddot{x}$

$$\frac{man^2}{a}y = m\ddot{x}$$

$$n^2\left(\frac{1}{2}ft^2 - x\right) = \ddot{x}$$

$$\ddot{x} + n^2x = \frac{1}{2}n^2ft^2$$

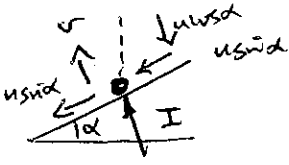
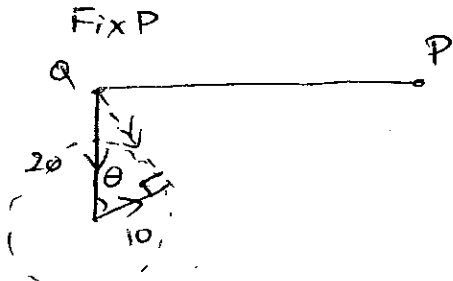
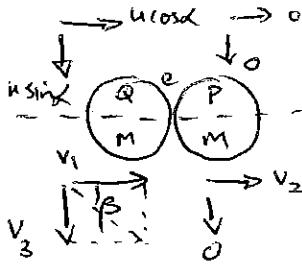
(c)  $x = 0, t = 0 \therefore 0 = A - \frac{f}{n^2}, A = \frac{f}{n^2}$

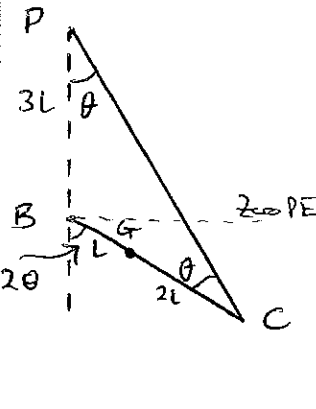
Differentiating the solution:  $\dot{x} = -nA\sin nt + nB\cos nt + ft$  (or get  $\ddot{x}$  from original d.e.)  
 $\dot{x} = 0, t = 0 \therefore 0 = nB, B = 0$

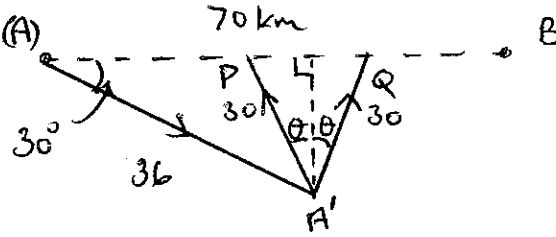
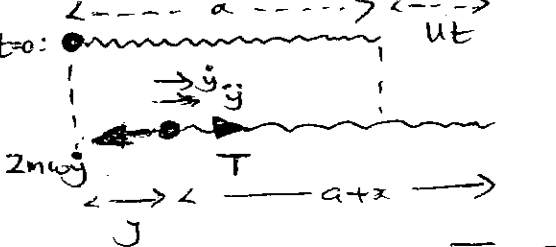
(d) Differentiating again:  $\ddot{x} = -n^2A\cos nt - n^2B\sin nt + f = -f\cos nt + f$

$$T = m\ddot{x} = mf(1 - \cos nt).$$

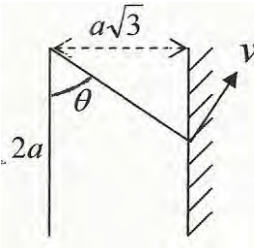
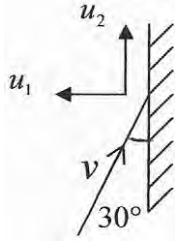
This takes max value of  $2mf$  (when  $\cos nt = -1$ ).

Question Number	Scheme	Marks
1. (a)	 <p> <math>\text{Cpt along plane} = 10 \sin \alpha</math>  <math>\text{after impact} = 10 \times \frac{3}{5}</math>  <math>= 6</math> </p> <p> <math>V = e \times 10 \cos \alpha</math>  <math>(= \frac{1}{2} \times 10 \times \frac{4}{5} = 4)</math> </p> <p> <math>\text{Speed} = \sqrt{4^2 + 6^2} = \underline{7.21 \text{ ms}^{-1} \text{ (3SF)}}</math> </p>	<p>B1</p> <p>M1 A1</p> <p>M1 A1 (5)</p>
1. (b)	<p> <math>I = \frac{1}{2} (4 - -8) = \underline{6 \text{ N s}}</math> </p>	<p>M1 A1 (2)</p> <p>(7)</p>
2.	 <p> <math>\text{Vector } \Delta</math>  <math>\cos \theta = \frac{10}{20}</math>  <math>\Rightarrow \theta = \underline{0.60^\circ}</math> </p>	<p>M1 A1</p> <p>M1 A1</p> <p>A1 (5)</p>
3.	 <p> <math>v_3 = u \sin \alpha</math> </p> <p> <math>\text{CLM: } v_1 + v_2 = u \cos \alpha</math>  <math>\text{NIL: } -v_1 + v_2 = e u \cos \alpha</math>  <math>\frac{v_3}{v_1} = \tan \beta</math> </p> <p> <math>\text{elim } v_2</math>  <math>\text{elim } v_3</math>  <math>\text{elim } u</math> </p> <p> <math>\Rightarrow \underline{\tan \beta (1-e) = 2 \tan \alpha} *</math> </p>	<p>B1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1</p> <p>M1</p> <p>M1</p> <p>A1 (11)</p>

Question Number	Scheme	Marks
4.(a)	For constant speed, $F - kv^2 = 0$ $\Rightarrow v = \sqrt{\frac{F}{k}}$ *	M1 A1 (2)
(b)	$F - kv^2 = Ma$ $\Rightarrow F - kv^2 = Mv \frac{dv}{dx}$ $\int dx = M \int \frac{v}{F - kv^2} dv$ $x = \frac{-M}{2k} \ln(F - kv^2) + C$ $x=0, v=0 \Rightarrow C = \frac{M}{2k} \ln F$ $x = \frac{M}{2k} \left\{ \ln F - \ln(F - kv^2) \right\}$ $X = \frac{M}{2k} \ln \left( \frac{F}{F - k \cdot \frac{F}{4k}} \right)$ $= \frac{M}{2k} \ln \frac{4}{3}$ *	M1 A1 M1 M1 A1 M1 A1 M1 A1 (9) (11)
5.(a)	 $GPE = -mgL \cos 2\theta$ $EPE = \frac{mg}{6} \frac{(6L \cos \theta - L)^2}{2L}$ $= \frac{mg}{12L} (36L^2 \cos^2 \theta - 12L^2 \cos \theta + L^2)$ $= mgL (3 \cos^2 \theta - \cos \theta) + C$ $V = -mgL (2 \cos^2 \theta - 1) + mgL (3 \cos^2 \theta - \cos \theta) + C$ $= mgL (\cos^2 \theta - \cos \theta) + C$ *	B1 M1 M1 M1 M1 M1 A1 (6)
(b)	$\frac{dV}{d\theta} = mgL (-2 \cos \theta \sin \theta + \sin \theta) = 0$ $\sin \theta (-2 \cos \theta + 1) = 0$ $\sin \theta = 0$ or $\cos \theta = \frac{1}{2}$ $\theta = 0$ or $\theta = \pm \frac{\pi}{3}$	M1 A1; M1 M1 A1 A1 (6) (12)

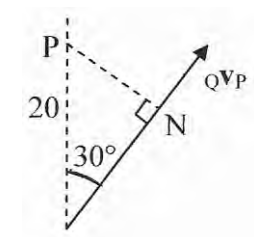
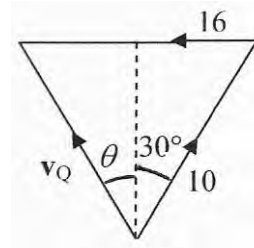
<p>(a)</p>  <p>Minimum speed for interception = <math>36 \sin 30^\circ = 18</math></p> <p><math>\cos \theta = \frac{18}{30} (= \frac{3}{5})</math></p> <p><math>\Rightarrow \tan \theta = \frac{4}{3}</math></p> <p>Explanation</p>	<p>M1 A1</p> <p>M1 A1</p> <p>A1</p> <p>M1</p> <p>A1 (7)</p>
<p>(b)</p> <p><math>AQ = 36 \cos 30^\circ + 30 \sin \theta</math> ( <math>18\sqrt{3} + 24</math> )</p> <p>Time = <math>\frac{70}{(18\sqrt{3} + 24)} = 1.27 \text{ hrs.}</math></p>	<p>M1 A2</p> <p>M1 A1 (5)</p> <p>(12)</p>
<p>7. (a)</p>  <p><math>y + ut = y + (v+x)</math></p> <p><math>ut = y + x</math> *</p>	<p>M1</p> <p>A1 (2)</p>
<p>(b)</p> <p>For particle, <math>R(\rightarrow)</math>, <math>T - 2m\omega \dot{y} = m\ddot{y}</math></p> <p><math>T = \frac{5m\omega^2 x}{a}</math></p> <p><math>u = \dot{y} + \dot{x}</math>; <math>0 = \ddot{y} + \ddot{x}</math></p> <p><math>5\frac{m\omega^2 x}{a} - 2\frac{m\omega}{a}(u - \dot{x}) = m(-\ddot{x})</math></p> <p><math>\Rightarrow \ddot{x} + 2\omega \dot{x} + 5\omega^2 x = 2\omega u</math> *</p>	<p>M1 A1</p> <p>M1</p> <p>B1; B1</p> <p>M1 A1 (7)</p>
<p>(c)</p> <p>AE: <math>u^2 + 2\omega u + 5\omega^2 = 0 \Rightarrow (u + \omega)^2 = -4\omega^2</math></p> <p><math>u = -\omega + 2i\omega</math></p> <p>CF: <math>x = e^{-\omega t} (A \cos 2\omega t + B \sin 2\omega t)</math></p> <p>PI: <math>x = \frac{2\omega u}{5\omega^2} = \frac{2u}{5\omega}</math></p> <p>ES: <math>x = e^{-\omega t} (A \cos 2\omega t + B \sin 2\omega t) + \frac{2u}{5\omega}</math></p> <p><math>x=0, t=0: 0 = A + \frac{2u}{5\omega} \Rightarrow A = -\frac{2u}{5\omega}</math></p> <p><math>\ddot{x} = -\omega e^{-\omega t} (A \cos 2\omega t + B \sin 2\omega t) + e^{-\omega t} (-2\omega A \sin 2\omega t + 2\omega B \cos 2\omega t)</math></p> <p><math>t=0, \dot{y}=0 \Rightarrow \dot{x} = u</math></p> <p><math>u = -\omega A + 2\omega B \Rightarrow B = \frac{3u}{10\omega}</math></p> <p><math>x = e^{-\omega t} \left( \frac{3u}{10\omega} \sin 2\omega t - \frac{2u}{5\omega} \cos 2\omega t \right) + \frac{2u}{5\omega}</math></p>	<p>B1</p> <p>M1</p> <p>B1</p> <p>B1</p> <p>M1 A1 ✓</p> <p>M1</p> <p>A1 (8)</p> <p>(17)</p>

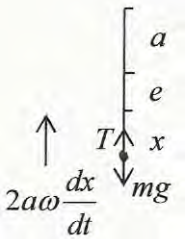
MJJ. 4.705

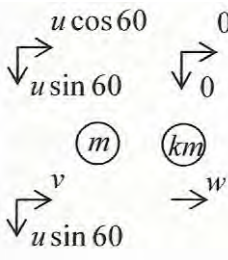
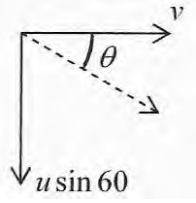
Question Number	Scheme	Marks
1.	<p>(a) <math>\frac{1}{2} \frac{dv}{dt} = \frac{1}{2}g - 2v</math>  <math>\Rightarrow 5 \frac{dv}{dt} = 49 - 20v</math> (*)</p> <p>(b) <math>\int \frac{5dv}{49 - 20v} = \int dt</math> (separate variables)  <math>\frac{-5}{20} \ln(49 - 20v) = t + c</math>  <math>t = 0, v = 0 \Rightarrow c = -\frac{1}{4} \ln 49</math> (attempt to get c)  <math>t = \frac{1}{4} \ln \left( \frac{49}{49 - 20v} \right)</math>  <math>t = 1 : 1 = \frac{1}{4} \ln \left( \frac{49}{49 - 20v} \right)</math> (correct use of logs/exp)  <math>\rightarrow v \approx 2.41ms^{-1}</math> or <math>2.4ms^{-1}</math></p>	<p>M1 A1 (2)</p> <p>M1 A1 M1 M1 A1 (5) <b>Total 7 marks</b></p>
2.	<p>(a) Energy: <math>\frac{1}{2}m \left( \frac{37ga}{5} - v^2 \right) = mg \cdot 2a(1 - \cos \theta)</math>  Using <math>\theta = \frac{\pi}{3}</math> &amp; solve: <math>\rightarrow v = \sqrt{\frac{27ga}{5}}</math> (*)</p>  <p>(b) Impact: <math>u_1 = ev \sin 30</math>  KE loss = <math>\frac{1}{2}m(v^2 \sin^2 30 - e^2 v^2 \sin^2 30)</math>  <math>\left[ +\frac{1}{2}mv^2 \cos^2 30 - \frac{1}{2}mu_2^2 \right] = \frac{3mga}{5}</math>  [Using <math>u_2 = v \cos 30</math> if necessary &amp; ]  reducing to equation in (m, g, a) e alone  <math>\frac{3mga}{5} = \frac{1}{2}m \cdot \frac{27ga}{5} \cdot \frac{1}{4}(1 - e^2)</math>  Solve for e: <math>\rightarrow e = \frac{1}{3}</math></p> 	<p>M1 A1 M1 A1 (4)</p> <p>M1 A1 M1 A1 A1 M1 A1 (7) <b>Total 11 marks</b></p>



Question Number	Scheme	Marks
3.	<p>(a)</p> <p>(i) <math>\mathbf{v}_Q = \mathbf{v}_Q + \mathbf{v}_P + \mathbf{v}_P</math>  <math> \mathbf{v}_Q ^2 = (10 \cos 30)^2 + (16 - 10 \sin 30)^2</math>  <math>= 75 + 121</math>  <math>\Rightarrow  \mathbf{v}_Q  = 14 \text{ms}^{-1}</math></p> <p>(ii) <math>\tan \theta = \frac{16 - \sin 30}{10 \cos 30}</math> (o.e.)  <math>\theta \approx 51.8^\circ, \Rightarrow \text{bearing } \underline{308^\circ}</math> (nearest degree)</p> <p>(b) At nearest approach: <math>PN = 20 \sin 30</math>  <math>= \underline{10 \text{ km}}</math></p> <p>(c) <math>\text{Time} = \frac{20 \cos 30}{10} \approx 1.732 \text{ hrs}</math>  <math>\Rightarrow \underline{\text{Time} \approx 4.44 \text{ pm}}</math> (AWRT)</p> <p><u>Alternatives</u></p> <p>(a) Use of cosine rule in velocity vector triangle.</p> <p>(b) &amp; (c) Use of scalar product of relative velocity and relative position or differentiating magnitude of relative position vector squared to find the minimum distance and time at which it occurs.</p>	<p>M1 A1 A1 M1 A1, A1 (6)</p> <p>M1 A1 A1 (3)</p> <p>M1 A1 A1 (3)</p> <p><b>Total 12 marks</b></p>

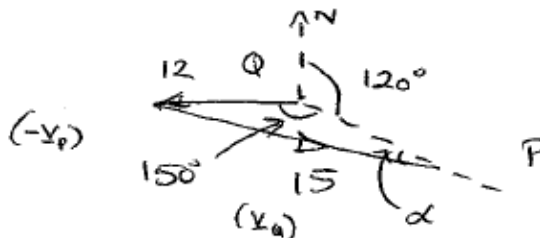
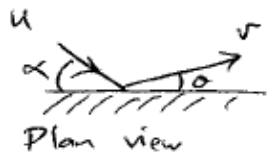


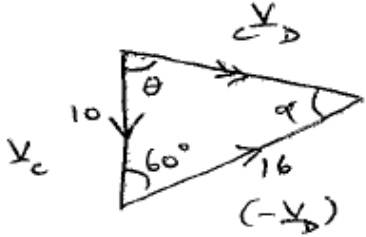
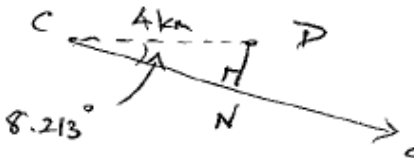
Question Number	Scheme	Marks
4.	<p>(a) R(↓) <math>m \frac{d^2x}{dt^2} = mg - T - 2m\omega \frac{dx}{dt}</math> (4 terms)</p> $m \frac{d^2x}{dt^2} = mg - \frac{2m\omega^2 a}{a} (e + x) - 2m\omega \frac{dx}{dt}$ $\rightarrow \frac{d^2x}{dt^2} + 2\omega \frac{dx}{dt} + 2\omega^2 x = 0 \quad (*)$  <p>(b) <math>x = e^{-\omega t} (A \cos \omega t + b \sin \omega t)</math>  <math>t = 0, x = 0 \Rightarrow \underline{A = 0}</math>  <math>\frac{dx}{dt} = -\omega e^{-\omega t} \cdot B \sin \omega t + e^{-\omega t} \cdot B \omega \cos \omega t</math> (use of product rule)  <math>t = 0, \frac{dx}{dt} = U : U = B\omega \Rightarrow \underline{B = \frac{U}{\omega}}</math></p> <p>(c) <math>\frac{dx}{dt} = -Ue^{-\omega t} \sin \omega t + Ue^{-\omega t} \cos \omega t = 0</math>  <math>\Rightarrow \tan \omega t = 1</math> (solve for <math>\tan \omega t</math>)  <math>\Rightarrow \underline{t = \frac{\pi}{4\omega}}</math></p>	<p>M1 A1          ↓          M1          ↓          M1 A1          (5)</p> <p>B1          M1          M1 A1          (4)</p> <p>M1          M1          A1          (3)</p> <p><b>Total 12 marks</b></p>

Question Number	Scheme	Marks
5.	<p>(a) <math>CLM(\leftrightarrow): mu \cos 60 = mv + kmw</math>  <math>NLI: \frac{1}{2}u \cos 60 = w - v</math>                      Solve for <math>w: (1+k)w = \frac{1}{2}u\left(1 + \frac{1}{2}\right)</math>  <math>\Rightarrow w = \frac{3u}{4(k+1)} \quad (*)</math></p> <p>(b) Solve for <math>v \rightarrow v = \frac{u(2-k)}{4(k+1)}</math>  <math>\tan \theta = 2\sqrt{3} = \frac{u \sin 60}{v}</math>  <math>= \frac{u\sqrt{3}}{2} \cdot \frac{4(k+1)}{u(2-k)}</math>                      Solve <math>k: \rightarrow k = \frac{1}{2}</math></p> <p>(c) <math>k = \frac{1}{2} \Rightarrow v = \frac{u}{4}, w = \frac{u}{2}</math>  <math>KE \text{ loss} = \frac{1}{2}mu^2 - \left(\frac{1}{2}m \cdot \frac{u^2}{16} + \frac{1}{2}m \cdot \frac{3u^2}{4} + \frac{1}{2} \cdot \frac{1}{2}m \cdot \frac{u^2}{4}\right)</math>  <math>= \frac{1}{2}mu^2 \left(1 - \frac{1}{16} - \frac{3}{4} - \frac{1}{8}\right)</math>  <math>= \frac{1}{32}mu^2</math></p>	 <p>M1 A1                      M1 A1                      M1                      A1                      (6)</p>  <p>M1 A1                      M1 A1                      M1 A1                      (6)</p> <p>B1                      M1 A1                      A1                      (4)</p> <p><b>Total 16 marks</b></p>

Question Number	Scheme	Marks
6.	<p>(a) PE of R = <math>-\sqrt{2}mga \cos 2\theta</math> (+c) (1)</p> <p>PE of LH mass = <math>-\frac{3}{2}mg(2a - 2a \sin(45 + \theta))</math> (+c) (2)</p> <p>PE of RH mass = <math>-\frac{3}{2}mg(2a - 2a \sin(45 - \theta))</math> (+c) (3)</p> <p><math>V = (1) + (2) + (3)</math> (in terms of <math>\theta</math> etc.)</p> <p><math>= -\sqrt{2}mga \cos 2\theta - \frac{3}{2}mg[4a - a\sqrt{2}(\cos \theta + \sin \theta + \cos \theta - \sin \theta)]</math></p> <p><math>= -\sqrt{2}mga \cos 2\theta - \frac{3}{2}mga(-2\sqrt{2} \cos \theta + 4)</math></p> <p><math>= \sqrt{2}mga(3 \cos \theta - \cos 2\theta) + \text{constant}</math> (*)</p> <p>(b) <math>\frac{dV}{d\theta} = \sqrt{2}mga(-3 \sin \theta + 2 \sin 2\theta)</math></p> <p><math>\frac{dV}{d\theta} = 0 \Rightarrow 2 \sin 2\theta - 3 \sin \theta = 0</math></p> <p><math>\Rightarrow \sin \theta(4 \cos \theta - 3) = 0</math></p> <p><math>\Rightarrow \theta = 0, \text{ or } \theta = \pm \arccos \frac{3}{4} (= \pm 0.723)</math></p> <p>(c) <math>\frac{d^2V}{d\theta^2} = \sqrt{2}mga(-3 \cos \theta + 4 \cos 2\theta)</math></p> <p><math>\cos \theta = \frac{3}{4} : \frac{d^2V}{d\theta^2} = \sqrt{2}mga\left(-3 \cdot \frac{3}{4} + 4\left(2 \cdot \frac{9}{16} - 1\right)\right)</math></p> <p><math>= \sqrt{2}mga\left(-\frac{9}{4} + \frac{1}{2}\right)</math></p> <p><math>&lt; 0 \therefore \text{Unstable}</math></p>	<p>B1</p> <p>M1 A1</p> <p>A1</p> <p>M1</p> <p>M1</p> <p>A1 (7)</p> <p>M1 A1</p> <p>M1</p> <p>M1</p> <p>A1, A1 (6)</p> <p>M1 A1</p> <p>M1</p> <p>A1 (4)</p> <p><b>Total 17 marks</b></p>

June 2006  
6680 Mechanics M4  
Mark Scheme

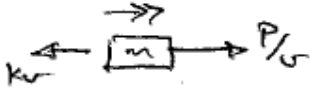
Question Number	Scheme	Marks
1.	 $\frac{\sin \alpha}{12} = \frac{\sin 150^\circ}{15}$ $\Rightarrow \sin \alpha = \frac{6}{15}$ $\Rightarrow \alpha = 23.6^\circ$ <p style="text-align: center;"><math>\therefore</math> <u>Course is 096 (.4°)</u></p>	<p style="text-align: center;">M1</p> <p style="text-align: center;">M1 A1</p> <p style="text-align: center;">A1</p> <p style="text-align: center;">A1 (5)</p>
2.	 <p style="text-align: center;">Plan view</p> $\begin{aligned} (\rightarrow) \quad u \cos \alpha &= v \cos \theta \\ (\uparrow) \quad e u \sin \alpha &= v \sin \theta \end{aligned}$ $\Rightarrow v^2 = u^2 (\cos^2 \alpha + e^2 \sin^2 \alpha)$ $\Rightarrow \underline{KE = \frac{1}{2} m u^2 (\cos^2 \alpha + e^2 \sin^2 \alpha)}$	<p style="text-align: center;">M1 A1</p> <p style="text-align: center;">M1 A1</p> <p style="text-align: center;">M1</p> <p style="text-align: center;">A1 (6)</p>

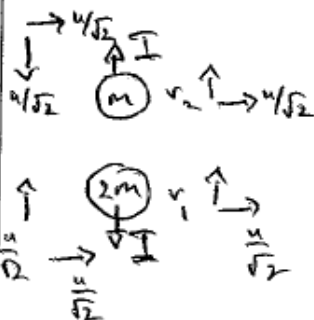
Question Number	Scheme	Marks
3-(a)	 $ \underline{v}_{CD} ^2 = 10^2 + 16^2 - 2 \times 10 \times 16 \cos 60^\circ$ $= 196$ $ \underline{v}_{CD}  = 14 \text{ ms}^{-1} \quad *$ <p>(b) <math>\alpha</math> is acute (opposite shortest side)</p> $\frac{\sin \alpha}{10} = \frac{\sin 60^\circ}{14}$ $\Rightarrow \alpha = 38.213^\circ$  <p>(i) <math>DN = 4000 \sin 8.213^\circ</math>  <math>\approx 571 \text{ m} \left( \frac{4000}{7} \right)</math></p> <p>(ii) <math>t = \frac{4000 \cos 8.213^\circ}{14} \text{ sec.}</math>  <math>\approx 282.78 \dots \text{ sec.}</math>  <u>Time is 2.05 pm (nearest minute)</u></p>	M1 A1 A1 (3)  M1 A1  M1 A1  M1 A1  A1 (7)  (10)

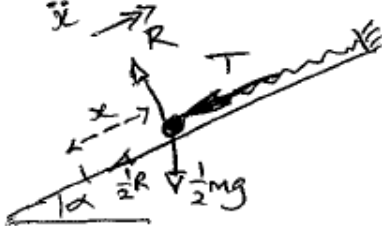
Question number	Scheme	Marks
4.(c)	<p>PE of rod = <math>-mgL \cos \theta</math></p> <p>EPE of string = <math>\frac{kmg}{2L} (2L \cos \theta - L)^2</math></p> <p>Total PE of system, <math>V = -mgL \cos \theta + \frac{kmgL}{2} (2 \cos \theta - 1)^2 + c</math></p> <p><math>= -mgL \cos \theta + \frac{kmgL}{2} (4 \cos^2 \theta - 4 \cos \theta + 1) + c</math></p> <p><math>= mgL (-\cos \theta + 2k \cos^2 \theta - 2k \cos \theta) + c'</math></p> <p><math>= \underline{mgL [ 2k \cos^2 \theta - (2k+1) \cos \theta ]} + c' *</math></p>	<p>B1</p> <p>M1 A1</p> <p>M1</p> <p>M1 A1</p> <p>A1 (7)</p>
(b)	<p><math>\frac{dV}{d\theta} = mgL (-4k \cos \theta \sin \theta + (2k+1) \sin \theta)</math></p> <p>At equil<sup>m</sup>, <math>mgL \sin \theta (-4k \cos \theta + (2k+1)) = 0</math></p> <p><math>\Rightarrow \sin \theta = 0</math> or <math>\cos \theta = \frac{2k+1}{4k}</math></p> <p><math>\Rightarrow \theta = 0</math> (<math>\theta &gt; 0</math>) <math>\frac{2k+1}{4k} &lt; 1</math></p> <p><math>2k+1 &lt; 4k</math></p> <p><math>1 &lt; 2k</math></p> <p><math>\frac{1}{2} &lt; k *</math></p>	<p>M1 A1</p> <p>M1</p> <p>M1</p> <p>A1 (5)</p> <p>(12)</p>

Question number	Scheme	Marks
4.(a)	<p>PE of rod = <math>-mgL \cos \theta</math></p> <p>EPE of string = <math>\frac{kmg}{2L} (2L \cos \theta - L)^2</math></p> <p>Total PE of system, <math>V = -mgL \cos \theta + \frac{kmgL}{2} (2 \cos \theta - 1)^2 + c</math></p> <p><math>= -mgL \cos \theta + \frac{kmgL}{2} (4 \cos^2 \theta - 4 \cos \theta + 1) + c</math></p> <p><math>= mgL (-\cos \theta + 2k \cos^2 \theta - 2k \cos \theta) + c'</math></p> <p><math>= \underline{mgL [2k \cos^2 \theta - (2k+1) \cos \theta]} + c' *</math></p>	<p>BI</p> <p>M1 A1</p> <p>M1</p> <p>M1 A1</p> <p>A1 (7)</p>
(b)	<p><math>\frac{dV}{d\theta} = mgL (-4k \cos \theta \sin \theta + (2k+1) \sin \theta)</math></p> <p>At equil<sup>a</sup>, <math>mgL \sin \theta (-4k \cos \theta + (2k+1)) = 0</math></p> <p><math>\Rightarrow \sin \theta = 0</math> or <math>\cos \theta = \frac{2k+1}{4k}</math></p> <p><math>\Rightarrow \theta = 0</math> (<math>\theta &gt; 0</math>) <math>\frac{2k+1}{4k} &lt; 1</math></p> <p><math>2k+1 &lt; 4k</math></p> <p><math>1 &lt; 2k</math></p> <p><math>\frac{1}{2} &lt; k *</math></p>	<p>M1 A1</p> <p>M1</p> <p>M1</p> <p>A1 (5)</p> <p>(12)</p>



Question number	Scheme	Marks
5.(a)	 $(\rightarrow): \frac{P}{v} - kv = m \frac{dv}{dt}$ $\Rightarrow P = m v \frac{dv}{dt} + kv^2 \quad *$	B1 M1 A1 (3)
(b)	$\int_0^T dt = \int_u^{2u} \frac{m v dv}{P - kv^2} \quad (u = \frac{1}{3} \sqrt{\frac{P}{k}})$ $\Rightarrow T = \frac{m}{2k} \left[ \ln(P - kv^2) \right]_u^{2u}$ $= \frac{m}{2k} \left\{ \ln\left(P - \frac{k}{9} \frac{P}{k}\right) - \ln\left(P - \frac{4k}{9} \frac{P}{k}\right) \right\}$ $= \frac{m}{2k} \left\{ \ln \frac{8P}{9} - \ln \frac{5P}{9} \right\}$ $= \frac{m}{2k} \ln \left( \frac{8P}{9} \times \frac{9}{5P} \right)$ $= \frac{m}{2k} \ln \frac{8}{5}$	M1 A1 A2 M1 A1 M1 A1 (8) (11)

Question number	Scheme	Marks
6.(a)	 <p>Form: <math>I = m(v_1 + \frac{u}{\sqrt{2}})</math></p> <p>CM(<math>\uparrow</math>): <math>2\frac{mu}{\sqrt{2}} - \frac{mu}{\sqrt{2}} = 2mv_1 + mv_2</math></p> <p><math>\frac{u}{\sqrt{2}} = 2v_1 + v_2</math> <math>\oplus</math></p> <p>NIL: <math>e \frac{2u}{\sqrt{2}} = \frac{u}{\sqrt{2}} = -v_1 + v_2</math> <math>\ominus</math></p> <p><math>\Rightarrow \cancel{\frac{u}{\sqrt{2}}} = \cancel{v_2}</math></p> <p><math>\Rightarrow I = m\left(\frac{u}{\sqrt{2}} + \frac{u}{\sqrt{2}}\right)</math></p> <p><math>= \underline{\underline{mu\sqrt{2}}}</math></p>	<p>M1 A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>A1 (9)</p>
(b)	<p><math>v_2 - v_1 = \frac{u}{\sqrt{2}}</math> (Separation speed)</p> <p>time to wall = <math>\frac{d}{u/\sqrt{2}} = \frac{d\sqrt{2}}{u}</math></p> <p><math>\therefore</math> Separation = <math>\frac{d\sqrt{2}}{u} \times \frac{u}{\sqrt{2}} = d</math></p>	<p>M1</p> <p>M1 A1</p> <p>M1 A1</p> <p>(5)</p> <p>(14)</p>

Question number	Scheme	Marks
7.(a)	 $F = \frac{1}{2}R$ $R = mg \cos \alpha$ $T = \frac{4mgx}{L}$ $(\rightarrow): -F - mg \sin \alpha - T = m \ddot{x}$ $-\frac{1}{2} \cdot \frac{4mg}{5} - \frac{3}{5}mg - \frac{4mgx}{L} = m \ddot{x}$ $\Rightarrow \frac{d^2x}{dt^2} + 4\omega^2 x = -g \quad *$ $(u = \sqrt{3}/L)$	M1 B1 B1 M1 A1 A1 (6)
(b)	$m^2 + 4\omega^2 = 0 \Rightarrow m = \pm 2\omega i$ <p>C.F. ii <math>x = A \sin 2\omega t + B \cos 2\omega t</math></p> <p>P.I. ii <math>x = \frac{-g}{4\omega^2} = -\frac{L}{4}</math></p> <p>G.S. ii <math>x = A \sin 2\omega t + B \cos 2\omega t - \frac{L}{4}</math></p> <p><math>t=0, x=0</math>: <math>B = \frac{L}{4}</math>  <math>\dot{x} = 2\omega A \cos 2\omega t - 2\omega B \sin 2\omega t</math></p> <p><math>t=0, \dot{x} = \frac{1}{2}\sqrt{g}</math>: <math>\frac{\sqrt{g}}{2} = 2\omega A \Rightarrow A = \frac{L}{4}</math></p> $\Rightarrow x = \frac{L}{4} (\sin 2\omega t + \cos 2\omega t - 1)$	M1 B1 B1 M1 A1 M1 A1 (7)
(c)	$\dot{x} = 0 \Rightarrow \cancel{2\omega} A \cos 2\omega t - \cancel{2\omega} B \sin 2\omega t = 0$ $\Rightarrow \tan 2\omega t = \frac{A}{B} = 1$ $\Rightarrow 2\omega t = \frac{\pi}{4} \quad (\text{first value})$ $\Rightarrow x = \frac{L}{4} \left( \frac{\sqrt{2}}{2} + \frac{\sqrt{2}}{2} - 1 \right)$ $= \frac{L}{4} (\sqrt{2} - 1)$	M1 A1 M1 A1 (4) (17)

# Mark Scheme (Final)

## Summer 2007

GCE

### GCE Mathematics (6680/01)

June 2007  
6680 Mechanics M4  
Mark Scheme

General:

For M marks, correct number of terms, dimensionally correct, all terms that need resolving are resolved.

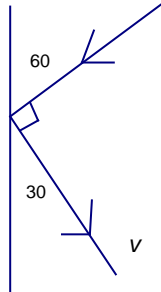
Omission of  $g$  from a resolution is an accuracy error, not a method error.

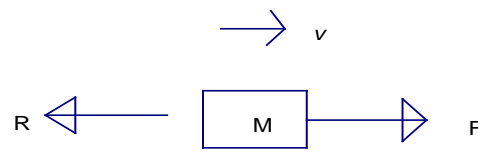
Omission of mass from a resolution is a method error.

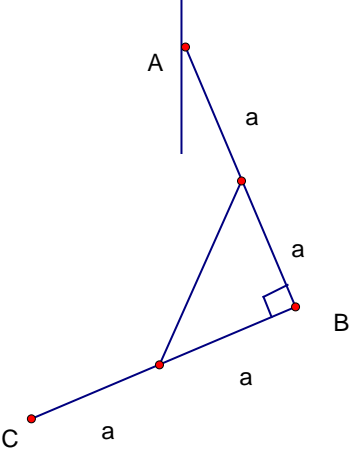
Omission of a length from a moments equation is a method error.

Where there is only one method mark for a question or part of a question, this is for a *complete* method.

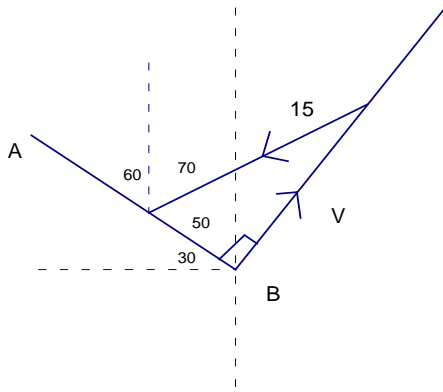
Omission of units is not (usually) counted as an error.

Question Number	Scheme	Marks
1(a)	 $u \cos 60^\circ = v \cos 30^\circ$ $u = v\sqrt{3}$ $\text{KE lost} = \frac{1}{2}m(u^2 - v^2)$ $\text{Fraction of KE lost} = 1 - \left(\frac{v}{u}\right)^2$ $= 1 - \frac{1}{3} = \frac{2}{3} \text{ or at least 3sf ending in 7}$ $\text{or } \frac{3}{4}(1 - e^2)$	M1A1 A1  M1 DM1 A1 (6)
(b)	$e = \frac{v \sin 30^\circ}{u \sin 60^\circ}$ $= \frac{v}{u} \cdot \frac{1}{\sqrt{3}}$ $= \frac{1}{3}$	M1A1  DM1 A1 (4)
a)	M1 Resolve parallel to the wall <i>Alt: reasonable attempt at equation connecting two variables</i> A1 Correct as above or equivalent <i>equation correct</i> A1 $u$ in terms of $v$ or $v.v.$ - not necessarily simplified. <i>or ratio of the two variables correct</i> M1 expression for KE lost DM1 expression in one variable for fraction of KE lost – could be $u/v$ as above A1 cao	<i>The first three marks can be awarded in (b) if not seen in (a)</i>
b)	M1 Use NIL perpendicular to the wall and form equation in $e$ A1 Correct unsimplified expression as above or $eu \sin 60^\circ = v \sin 30^\circ$ or equivalent DM1 Substitute values for trig functions or use relationship from (a) and rearrange to $e = \dots$ A1 cao accept decimals to at least 3sf	<i>The first two marks can be awarded in (a)</i>

<p>2(a)</p> <p>(b)</p>	 <p> <math display="block">F = \frac{Ru}{v}</math> <math display="block">R(\rightarrow), \frac{Ru}{v} - R = M \frac{dv}{dt}</math> <math display="block">R(u - v) = Mv \frac{dv}{dt} *</math> </p> <p> <math display="block">\int_0^T dt = \frac{M}{R} \int_{\frac{1}{4}U}^{\frac{1}{3}U} \frac{v dv}{u - v}</math> <math display="block">\Rightarrow T = \frac{M}{R} \int_{\frac{1}{4}U}^{\frac{1}{3}U} -1 + \frac{u}{u - v} dv</math> <math display="block">= \frac{M}{R} \left[ -v - u \ln(u - v) \right]_{\frac{1}{4}U}^{\frac{1}{3}U}</math> <math display="block">= \frac{M}{R} \left[ -\frac{u}{3} - u \ln\left(\frac{2u}{3}\right) + \frac{u}{4} + u \ln\left(\frac{3u}{4}\right) \right] \quad \left( C = -\frac{Mu}{R} \left( \ln \frac{3u}{4} + \frac{1}{4} \right) \right)</math> <math display="block">= \frac{Mu}{R} \left( -\frac{1}{12} + \ln \frac{9}{8} \right)</math> <p>Hence <math>k = \ln \frac{9}{8} - \frac{1}{12}</math></p> </p>	<p>B1</p> <p>M1</p> <p>A1</p> <p>(3)</p> <p>M1A1</p> <p>DM1</p> <p>A1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>(7)</p>
<p>a)</p> <p>b)</p>	<p>B1 Correct expression involving the driving force.</p> <p>M1 Use of <math>F = ma</math> to form a differential equation. Condone sign errors. a must be expressed as a derivative, but could be any valid form.</p> <p>A1 Rearrange to <b>given form</b>.</p> <p>M1 Separate the variables</p> <p>A1 Separation correct (limits not necessarily seen at this stage)</p> <p>DM1 Attempt a complete integration process</p> <p>A1 Integration correct</p> <p>M1 Correct use of both limits – substitute and subtract. Condone wrong order.</p> <p>M1 Simplify to find k from an expression involving a logarithm</p> <p>A1 Answer as given, or exact equivalent. Need to see <math>k = \ln A + B</math></p>	

Question Number	Scheme	Marks
3. (a)	 $V = -mga \cos \theta - mg(2a \cos \theta + a \sin \theta)$ $= -mga(3 \cos \theta + \sin \theta) \quad (+const) *$	M1A1A1 A1 (4)
(b)	$\frac{dV}{d\theta} = -mga(-3 \sin \theta + \cos \theta)$	M1A1
	$= 0 \Rightarrow \tan \theta = \frac{1}{3}$	M1
	$\Rightarrow \theta = 0.32(1)^{\circ} \text{ or } 18.4^{\circ} \text{ accept awrt}$	A1 (4)
(c)	$\frac{d^2V}{d\theta^2} = -mga(-3 \cos \theta - \sin \theta)$ $= mga(3 \cos \theta + \sin \theta)$	M1A1
	<p>Hence, when <math>\theta = 0.32^{\circ}</math>, <math>\frac{d^2V}{d\theta^2} &gt; 0</math> i.e. stable</p>	M1 A1 (4)
a)	<p>M1 Expression for the potential energy of the two rods. Condone trig errors. Condone sign errors. BC term in two parts A1 correct expression for AB A1 correct expression for BC A1 Answer <b><u>as given</u></b> .</p>	<p><i>These 4 marks are dependent on the use of derivatives</i></p>
b)	<p>M1 Attempt to differentiate V. Condone errors in signs and in constants. A1 Derivative correct M1 Set derivative = 0 and rearrange to a single trig function in <math>\theta</math> A1 Solve for <math>\theta</math> or M1A1 find the position of the center of mass M1A1 form and solve trig equation for <math>\theta</math></p>	
c)	<p>M1 Differentiate to obtain the second derivative A1 Derivative correct M1 Determine the sign of the second derivative A1 Correct conclusion. cso Or: M1 Find the value of <math>\frac{dV}{d\theta}</math> on both sides of the minimum point A1 signs correct M1 Use the results to determine the nature of the turning point A1 Correct conclusion, cso.</p>	

4 (a)



Fix A

$$v_{\min} = 15 \sin 50^\circ \\ = 11.5 \text{ km h}^{-1} \text{ (3 s.f.)}$$

or: triangle without the right angle

$$\text{identified and } \frac{15}{\sin \theta} = \frac{v_B}{\sin 50}$$

$$\Rightarrow v_B = \frac{15 \sin 50}{\sin \theta}$$

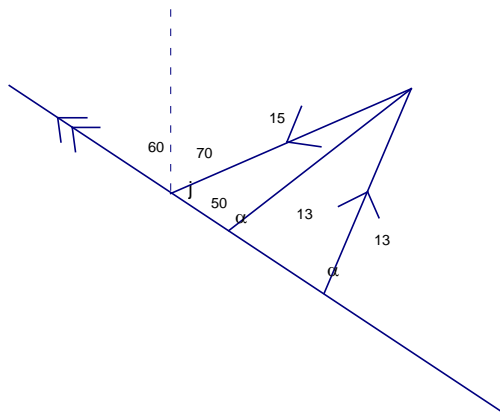
minimum value  $\Rightarrow \theta = 90$  for M1

As above for A1A1

M1A1  
A1

(3)

(b)



Ambiguous Sine Rule:

2 possible solutions for  $\alpha$

$$\frac{\sin \alpha}{15} = \frac{\sin 50}{13}$$

$$\alpha = 62.1^\circ \text{ (or } 118^\circ)$$

(smaller value gives larger relative velocity)

$\Rightarrow$  either

$$v = 13 \cos 62.1 + 15 \cos 50 = 15.72 \text{ kmh}^{-1}$$

Or

$$v^2 = 15^2 + 13^2 - 390 \cos 67.9 = 247.27$$

$$v = 15.7 \text{ kmh}^{-1}$$

$$\text{Time} = \frac{20}{\text{their } 15.72 \dots} \\ = 1.272 \dots \text{ hrs}$$

Earliest time is 13.16hrs or 13.17 hrs  
accept 1.16 (pm) or 1.17 (pm)

B1B1

(2)

M1A1

A1

M1A1

M1  
A1

M1 A1

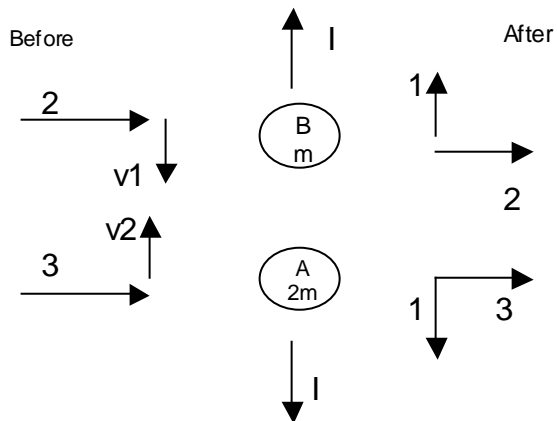
A1

(8)



<p>a)</p> <p>b)</p> <p>c)</p>	<p>M1 Velocity of B relative to A is in the direction of the line joining AB. Minimum V requires a right angled triangle. Convincing attempt to find the correct side.</p> <p>A1 <math>15 \times \sin(\text{their } 50^\circ)</math></p> <p>A1 Q specifies 3sf, so 11.5 only</p> <p>B1B1 Convincing argument B1B0 Argument with some merit</p> <p>M1 Use of Sine Rule A1 Correct expression A1 (2 possible values,) pick the correct value. M1 Use trig. to form an equation in v A1 correct equation</p> <p>M1 <math>time = \frac{distance}{speed}</math></p> <p>A1ft correct expression with their v (not necessarily evaluated) A1 correct time in hours &amp; minutes</p> <p>Or:</p> <p>M1 Use of cosine rule A1 <math>13^2 = 15^2 + v^2 - 2 \times 15 \times v \times \cos 50</math> A1 (Award after the next two marks) 15.72 or awrt 15.72 M1 Attempt to solve the equation for v</p> <p>A1 <math display="block">\frac{30 \cos 50 \pm \sqrt{(30 \cos 50)^2 - 4 \times 56}}{2}</math></p> <p>(15.72 or 3.562) Finish as above</p>	
-------------------------------	--	--

5. (a)



CLM:  $2v_2 - v_1 = 1 - 2 = -1$

NIL:  $1 + 1 = \frac{1}{2}(v_1 + v_2)$

$\therefore v_2 = 1, v_1 = 3$   
above

*Dependent on both M's*

Horizontal components unchanged (i.e. 2 & 3)

*Independent of all other marks*

$\mathbf{v}_A = 3\mathbf{i} + \mathbf{j}; \mathbf{v}_B = 2\mathbf{i} - 3\mathbf{j}$

For B:  $I = m(1 - (-3)) = 4m$

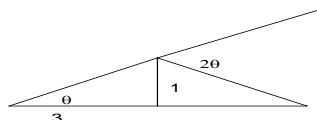
(Or For A:  $-I = 2m(-1 - 1) \therefore I = 4m$ )

$\begin{pmatrix} 3 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 3 \\ -1 \end{pmatrix} = \sqrt{3^2 + 1^2} \cdot \sqrt{3^2 + (-1)^2} \cos \theta$

$\Rightarrow 8 = 10 \cos \theta$

$\theta = 37^\circ$

Alternative:



M1  
where  $\tan \theta = \frac{1}{3}$

required angle is  $2\theta$

A1

M1A1

M1A1

M1A1

DM1

A1

A1

(7)

M1A1

(2)

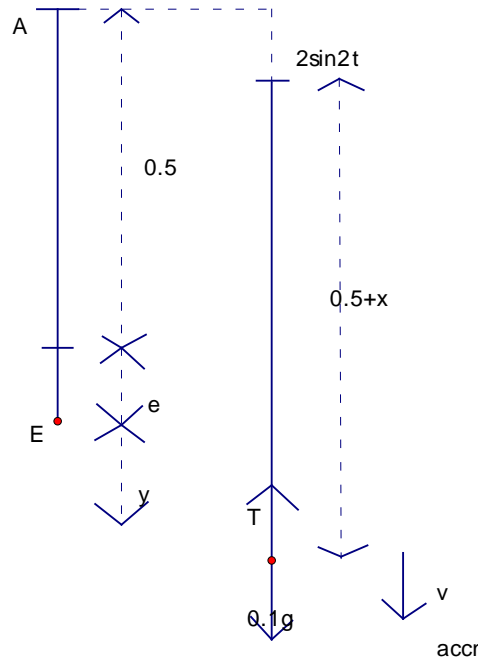
M1A1

M1

A1

(4)

<p>a)</p> <p>b)</p> <p>c)</p>	<p>M1 Conservation of momentum along the line of centres. Condone sign errors A1 equation correct</p> <p>M1 Impact law along the line of centres. <math>e</math> must be used correctly, but condone sign errors. A1 equation correct. The signs need to be consistent between the two equations</p> <p>M1 Solve the simultaneous equations for their <math>v_1</math> and <math>v_2</math>. A1 <math>i</math> components correct – independent mark A1 <math>v_A</math> &amp; <math>v_B</math> correct</p> <p>M1 Impulse = change in momentum for one sphere. Condone order of subtraction. A1 Magnitude correct.</p> <p>M1 Any complete method to find the trig ratio of a relevant angle. A1 <math>\cos\theta = \frac{4}{5}</math>, <math>\tan\frac{\theta}{2} = \frac{1}{3}</math>, ...</p> <p>Or M1 find angle of approach to the line of centres and angle after collision. A1 values correct. (both 71.56 .....</p> <p>M1 solve for <math>\theta</math> A1 <math>37^\circ</math> (Q specifies nearest degree)</p> <p>Special case: candidates who act as if the line of centres is in the direction of <math>i</math>:</p> <p>CLM <math>u+2v = 8</math> NIL <math>v-u = 2</math></p> <p><math>u=4/3, v=10/3</math></p> <p><math>4/3i + j ; 10/3i - j</math></p> <p>Impulse <math>2m-4/3m = 2/3m</math></p> $\frac{10+1}{\sqrt{10}\sqrt{\frac{109}{9}}} = \cos\theta \quad \theta = 1.70^\circ$ <p>Work is equivalent, so treat as a MR: M1A0M1A0M1A1A1 M1A1 M1A1M1A1</p>	
-------------------------------	---	--

<p>6 (a)</p>	 <p>At E, <math>\frac{2.45e}{0.5} = 0.1g</math>  <math>\Rightarrow e = 0.2</math></p> <p><math>\Rightarrow</math>  <math>0.5(orl) + 0.2 + y = 2 \sin 2t + 0.5(orl) + x</math></p> <p><math>\Rightarrow 0.2 + y = 2 \sin 2t + x</math> *</p>	<p>M1 A1</p> <p>B1</p> <p>(3)</p>
<p>(b)</p>	<p><math>0.1g - T = 0.1\ddot{y}</math></p> <p><math>R(\downarrow)</math> <math>0.1g - \frac{2.45x}{0.5} = 0.1\ddot{y}</math></p> <p><math>0.98 - 4.9(0.2 + y - 2 \sin 2t) = 0.1\ddot{y}</math>  <math>(-4.9y + 9.8 \sin 2t = 0.1\ddot{y})</math></p> <p><math>\Rightarrow \frac{d^2y}{dt^2} + 49y = 98 \sin 2t</math> *</p>	<p>M*1</p> <p>M1</p> <p>DM*1A1</p> <p>A1 cso</p> <p>(5)</p>
<p>(c)</p>	<p>CF is <math>y = A \cos 7t + B \sin 7t</math></p> <p>Hence GS is <math>y = A \cos 7t + B \sin 7t + \frac{98}{45} \sin 2t</math></p> <p><math>t = 0, y = 0: 0 = A</math> so, <math>y = B \sin 7t + \frac{98}{45} \sin 2t</math></p> <p><math>\dot{y} = 7B \cos 7t + \frac{196}{45} \cos 2t</math></p> <p><math>t = 0, \dot{y} = 0: 0 = 7B + \frac{196}{45} \Rightarrow B = -\frac{28}{45}</math></p> <p><math>\Rightarrow y = \frac{14}{45}(7 \sin 2t - 2 \sin 7t)</math></p>	<p>M1</p> <p>A1</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>(5)</p>
<p>(d)</p>	<p><math>\dot{y} = \frac{14}{45}(14 \cos 2t - 14 \cos 7t)</math></p> <p><math>\dot{y} = 0 \Rightarrow \cos 2t = \cos 7t</math>  <math>\Rightarrow 7t = 2k\pi \pm 2t</math>  <math>k=1 \Rightarrow 9t = 2\pi</math> (or <math>5t = 2\pi</math>)  <math>t = \frac{2\pi}{9}</math>, accept 0.698s, 0.70s.</p>	<p>B1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>(4)</p>

- a) M1 Hooke's law to find extension at equilibrium  
 A1 cao  
 B1 Q specifies reference to a diagram. Correct reasoning leading to **given answer**.
- b) M1 Use of  $F=ma$ . Weight, tension and acceleration. Condone sign errors.  
 M1 Substitute for tension in terms of  $x$   
 M1 Use given result to substitute for  $x$  in terms of  $y$   
 A1 Correct unsimplified equation  
 A1 Rearrange to **given form** cso.
- c) M1 Correct form for CF  
 A1 GS for  $y$  correct  
 B1 Deduce coefficient of  $\cos \theta = 0$   
 M1 Differentiate their  $y$  and substitute  $t=0$ ,  $\dot{y} = 0$   
 A1  $y$  in terms of  $t$ . Any exact equivalent.
- d) B1  $\dot{y}$  correct  
 M1 set  $\dot{y} = 0$   
 M1 solve for general solution for  $t$ :  $7t = 2k\pi \pm 2t$   
 or:  $\sin \frac{9t}{2} \times \sin \frac{5t}{2} = 0 \Rightarrow \sin \frac{9t}{2} = 0$  or  $\sin \frac{5t}{2} = 0$   
 A1 Select smallest value

GCE

Edexcel GCE

Mathematics

Mechanics 4 M4 (6680)

June 2008

advancing learning, changing lives

Mark Scheme - Final

Edexcel GCE  
**Mathematics**

## General Marking Guidance

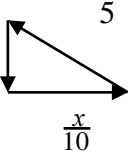
- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- When examiners are in doubt regarding the application of the mark scheme to a candidate's response, the team leader must be consulted.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

June 2008  
6680 Mechanics M4  
Mark Scheme

Question Number	Scheme	Marks
1.	${}^Q\mathbf{V}_P = \mathbf{V}_Q - \mathbf{V}_P = (3\mathbf{i} + 7\mathbf{j}) - (5\mathbf{i} - 4\mathbf{j})$ $= (-2\mathbf{i} + 11\mathbf{j})$ $\tan\theta = \frac{11}{2} \Rightarrow \theta = 79.69^\circ \dots$ <p>Bearing is <math>350^\circ</math></p>	<p>M1 A1</p> <p>M1 A1</p> <p>A1      <b>5</b></p>
2.	$2m(2\mathbf{i} - 2\mathbf{j}) + m(-3\mathbf{i} - \mathbf{j}) = 2m(\mathbf{i} - 3\mathbf{j}) + m\mathbf{v}$ $(\mathbf{i} - 5\mathbf{j}) = (2\mathbf{i} - 6\mathbf{j}) + \mathbf{v}$ $(-\mathbf{i} + \mathbf{j}) = \mathbf{v}$ $ \mathbf{v}  = \sqrt{(-1)^2 + 1^2} = \sqrt{2} \text{ m s}^{-1}$ <p style="text-align: right;">cwo</p>	<p>M1 A1</p> <p>A1</p> <p>DM1 A1      <b>5</b></p>
3.	$mg - mkv = m \frac{dv}{dt}$ $\int dt = \int \frac{dv}{g - kv}$ $t = -\frac{1}{k} \ln(g - kv) + c$ $t = 0, v = u \Rightarrow c = \frac{1}{k} \ln(g - ku)$ $T = \frac{1}{k} \ln(g - ku) - \frac{1}{k} \ln(g - 2ku)$ $= \frac{1}{k} \ln\left(\frac{g - ku}{g - 2ku}\right)$	<p>M1*</p> <p>A1 A1</p> <p>DM1*</p> <p>A1cao</p> <p>M1†</p> <p>DM1†</p> <p>A1      <b>8</b></p>



Question Number	Scheme	Marks
4.	$u \cos 2\theta = v \cos \theta$ $\frac{3}{8} u \sin 2\theta = v \sin \theta$ $3 \tan 2\theta = 8 \tan \theta$ $\frac{6 \tan \theta}{1 - \tan^2 \theta} = 8 \tan \theta$ $\tan^2 \theta = \frac{1}{4} \quad (\tan \theta \neq 0)$ $\tan \theta = \frac{1}{2}$	M1 A1 M1 A1  M1  M1   M1 A1 <b>8</b>
5.(a)	$-T - \frac{1}{2} mg - 2mv \sqrt{\frac{g}{l}} = m\ddot{x}$ $\frac{-mgx}{l} - \frac{1}{2} mg - 2m\dot{x} \sqrt{\frac{g}{l}} = m\ddot{x}$ $\frac{d^2 x}{dt^2} + 2\omega \frac{dx}{dt} + \omega^2 x = -0.5g \quad (\text{AG})$	M1 A3,2,1,0  M1  A1 (6)
(b)	$u^2 + 2\omega u + \omega^2 = 0 \Rightarrow u = \omega \quad (\text{twice})$ <p>CF is <math>x = e^{-\omega t} (At + B)</math></p> <p>PI is <math>x = -\frac{1}{2} l \quad \left(-\frac{g}{2\omega^2}\right)</math></p> <p>GS is <math>x = e^{-\omega t} (At + B) - \frac{1}{2} l</math></p> <p><math>t = 0, x = 0 \Rightarrow B = \frac{1}{2} l \quad \left(\frac{g}{2\omega^2}\right)</math></p> $\frac{dx}{dt} = -\omega e^{-\omega t} (At + B) + A e^{-\omega t}$ <p><math>t = 0, \frac{dx}{dt} = \sqrt{gl} = \omega l \Rightarrow A = \frac{3}{2} \omega l \left(= \frac{3\sqrt{gl}}{2}\right) \left(= \sqrt{gl} + \frac{0.5g}{\omega}\right)</math></p> <p>so <math>x = e^{-\omega t} \left(\frac{3}{2} \omega l t + \frac{1}{2} l\right) - \frac{1}{2} l = \frac{1}{2} l e^{-\omega t} (3\omega t + 1) - \frac{1}{2} l</math></p>	B1  M1  M1  M1  M1  A1 (6)
(c)	$\frac{dx}{dt} = 0 \Rightarrow -\omega e^{-\omega t} (At + B) + A e^{-\omega t} = 0$ $\Rightarrow t = \frac{2}{3\omega}$	M1  M1 A1 (3)  <b>15</b>

6.(a)	<div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;">  </div> <div>vector triangle</div> </div> $v^2 + \left(\frac{x}{10}\right)^2 = 5^2$ $\Rightarrow 100v^2 = 2500 - x^2$	M1 M1 A1 (3)
(b)	$200v \frac{dv}{dx} = -2x$ $200 \frac{d^2x}{dt^2} + 2x = 0$ $\frac{d^2x}{dt^2} + \frac{x}{100} = 0 \quad *$	M1 A1 D M1 A1 (4)
(c)	<p>Aux equn: <math>m^2 + \frac{1}{100} = 0</math></p> $\Rightarrow m = \pm \frac{i}{10}$ $x = A \sin \frac{t}{10} + B \cos \frac{t}{10}$ $t = 0, x = 0 \Rightarrow B = 0$ $\frac{dx}{dt} = \frac{A}{10} \cos \frac{t}{10}$ $t = 0, x = 0 \Rightarrow v = \frac{dx}{dt} = 5$ $\Rightarrow 5 = \frac{A}{10} \Rightarrow A = 50$ $\Rightarrow x = 50 \sin \frac{t}{10}$ $x = 30: 30 = 50 \sin \frac{t}{10}$ $\Rightarrow t = 10 \sin^{-1} \left( \frac{3}{5} \right) = 6.44 \text{ s}$	M1 A1 A1 B1 M1 M1 A1 M1A1 (9)

7.(a)	<p>PE of rod = <math>-kMg\sin 2\theta</math>  <math>BP = 2 \times 2a \sin \theta = 4a \sin \theta</math>  PE of mass = <math>-Mg(6a - 4a \sin \theta)</math>  <math>V = -Mg(6a - 4a \sin \theta) - kMg \sin 2\theta</math>  <math>= Mga(4 \sin \theta - k \sin 2\theta) + \text{constant} \quad *</math></p>	<p>B1 M1 A1  M1 A1 (5)</p>
(b)	<p><math>\frac{dV}{d\theta} = Mga(4 \cos \theta - 2k \cos 2\theta)</math>  so, <math>4 \times \frac{3}{4} - 2k(2(\frac{3}{4})^2 - 1) = 0</math>  <math>\Rightarrow k = 12</math></p>	<p>M1 A1  M1 M1 A1 (5)</p>
(c)	<p><math>4 \cos \theta - 24(2 \cos^2 \theta - 1) = 0</math>  <math>12 \cos^2 \theta - \cos \theta - 6 = 0</math>  <math>(4 \cos \theta - 3)(3 \cos \theta + 2) = 0</math>  <math>\cos \theta = -\frac{2}{3}</math></p>	<p>M1  D M1  A1 (3)</p>
(d)	<p><math>\frac{d^2V}{d\theta^2} = (Mga)(-4 \sin \theta + 4k \sin 2\theta)</math>   when <math>\cos \theta = \frac{3}{4}</math>, <math>\frac{d^2V}{d\theta^2} = (Mga) \times 44.97.. \Rightarrow \text{stable}</math>   when <math>\cos \theta = -\frac{2}{3}</math>, <math>\frac{d^2V}{d\theta^2} = (Mga) \times -50.68.. \Rightarrow \text{unstable}</math></p>	<p>M1 A1  M1 A1  A1 (5)  <b>18</b></p>

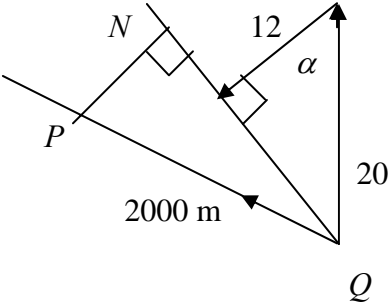
# Mark Scheme (Results) Summer 2009

GCE

GCE Mathematics (6680/01)

June 2009  
6680 Mechanics M4  
Mark Scheme

Question Number	Scheme	Marks
Q1	<p>CLM along plane: <math>v \cos 30^\circ = u \cos 45^\circ</math></p> $v = u \sqrt{\frac{2}{3}}$ <p>Fraction of KE Lost = <math>\frac{\frac{1}{2}mu^2 - \frac{1}{2}mv^2}{\frac{1}{2}mu^2} = \frac{\frac{1}{2}mu^2 - \frac{1}{2}m\frac{2}{3}u^2}{\frac{1}{2}mu^2} = \frac{1}{3}</math></p>	<p>M1 A1 A1 M1 M1 A1 [6]</p>
Q2	$-mg - mkv^2 = ma$ $-(g + kv^2) = v \frac{dv}{dx}$ $\pm \int_0^x dx = \int_{\sqrt{\frac{g}{k}}}^{\frac{1}{2}\sqrt{\frac{g}{k}}} \frac{-v dv}{(g + kv^2)}$ $X = \frac{1}{2k} \left[ \ln(g + kv^2) \right]_{\frac{1}{2}\sqrt{\frac{g}{k}}}^{\sqrt{\frac{g}{k}}}$ $= \frac{1}{2k} \left( \ln 2g - \ln \frac{5g}{4} \right)$ $= \frac{1}{2k} \ln \frac{8}{5}$	<p>M1 A1 M1 DM1 A1 (both previous) M1 A1 M1 A1 [9]</p>

Question Number	Scheme	Marks
Q3 (a)	 <p style="text-align: center;"> <math>\cos \alpha = \frac{12}{20}</math>                      Bearing is <math>180^\circ + \alpha = 233^\circ</math> (nearest degree)                 </p>	<p>M1</p> <p>M1 A1</p> <p>A1</p> <p style="text-align: right;">(4)</p>
(b)	$PN = 2000\cos(135^\circ - \alpha) = 200\sqrt{2} \text{ m or decimal equivalent}$	<p>M1A1ft A1</p> <p style="text-align: right;">(3)</p>
(c)	<p>Time to closest approach = <math>\frac{\sqrt{20^2 - 12^2}}{20}</math></p> $= \frac{2000\sin(135^\circ - \alpha)}{16}$ <p>Distance moved by Q = their <math>t \times 12</math></p> $= 1050\sqrt{2} \text{ m or decimal equivalent}$	<p>B1</p> <p>M1</p> <p>A1</p> <p>DM1</p> <p>A1</p> <p style="text-align: right;">(5)</p> <p style="text-align: right;">[12]</p>

Question Number	Scheme	Marks
Q4 (a)	$V = -mg2a \sin 2\theta - \frac{7}{20}mg(L - 4a \sin \theta)$ $= \frac{1}{5}mga(7 \sin \theta - 10 \sin 2\theta) - \frac{7}{20}mgL$	M1 B1 A1 A1 (4)
(b)	$\frac{dV}{d\theta} = \frac{1}{5}mga(7 \cos \theta - 20 \cos 2\theta)$ $\frac{1}{5}mga(7 \cos \theta - 20 \cos 2\theta) = 0$ $7 \cos \theta - 20(2 \cos^2 \theta - 1) = 0$ $40 \cos^2 \theta - 7 \cos \theta - 20 = 0$ $(5 \cos \theta - 4)(8 \cos \theta + 5) = 0$ $\cos \theta = \frac{4}{5} \text{ or } (\cos \theta = -\frac{5}{8} \Rightarrow 2\theta > 180^\circ)$	M1 A1 DM1 DM1 A1 DM1 A1 DM1 (8)
(c)	$\frac{d^2V}{d\theta^2} = \frac{1}{5}mga(-7 \sin \theta + 40 \sin 2\theta)$ $= \frac{1}{5}mga(-7 \sin \theta + 80 \sin \theta \cos \theta)$ <p>When <math>\cos \theta = \frac{4}{5}</math>,</p> $\frac{d^2V}{d\theta^2} = \frac{1}{5}mga\left(\frac{-21}{5} + 80 \times \frac{3}{5} \times \frac{4}{5}\right) = \frac{171}{25}mga$ $> 0 \text{ therefore stable}$	M1 A1 M1 A1 cso (4) [16]

Question Number	Scheme	Marks
Q5 (a)	<p>CLM: <math>2(\mathbf{i} + 2\mathbf{j}) + -2\mathbf{i} = 2\mathbf{j} + \mathbf{v}</math>  <math>\mathbf{v} = 2\mathbf{j} \text{ m s}^{-1}</math></p>	<p>M1 A1 A1 (3)</p>
(b)	<p><math>\mathbf{I} = 2(\mathbf{j} - (\mathbf{i} + 2\mathbf{j}))</math>  <math>= (-2\mathbf{i} - 2\mathbf{j}) \text{ Ns}</math>            Since <math>\mathbf{I}</math> acts along l.o.c.c. , l.o.c.c is parallel to <math>\mathbf{i} + \mathbf{j}</math></p>	<p>M1 A1 A1 B1 (4)</p>
(c)	<p>Before A: <math>(\mathbf{i} + 2\mathbf{j}) \cdot \frac{1}{\sqrt{2}}(\mathbf{i} + \mathbf{j}) = \frac{3}{\sqrt{2}}</math>            B: <math>-2\mathbf{j} \cdot \frac{1}{\sqrt{2}}(\mathbf{i} + \mathbf{j}) = \frac{-2}{\sqrt{2}}</math></p> <p>After A: <math>\mathbf{j} \cdot \frac{1}{\sqrt{2}}(\mathbf{i} + \mathbf{j}) = \frac{1}{\sqrt{2}}</math>            B: <math>2\mathbf{j} \cdot \frac{1}{\sqrt{2}}(\mathbf{i} + \mathbf{j}) = \frac{2}{\sqrt{2}}</math></p> <p>NIL:</p> $e = \frac{\frac{2}{\sqrt{2}} - \frac{1}{\sqrt{2}}}{\frac{3}{\sqrt{2}} - \frac{-2}{\sqrt{2}}} = \frac{1}{5}$	<p>M1 A3</p>
		<p>DM1 A1  (6) [13]</p>



Question Number	Scheme	Marks
Q6 (a)	$(\rightarrow), T = m\ddot{y}$ <p>Hooke's Law:</p> $T = \frac{2mn^2ax}{2a} = mn^2x$ $\left. \begin{aligned} x + y &= \frac{1}{2}ft^2 \\ \dot{x} + \dot{y} &= ft \\ \ddot{x} + \ddot{y} &= f \end{aligned} \right\}$ <p>so, <math>(\rightarrow), mn^2x = m\ddot{y} = m(f - \ddot{x})</math></p> $\ddot{x} + n^2x = f^{**}$	<p>M1</p> <p>B1</p> <p>B2</p> <p>DM1</p> <p>A1</p>
(b)	<p>C.F. : <math>x = A \cos nt + B \sin nt</math></p> <p>P.I. : <math>x = \frac{f}{n^2}</math></p> <p>Gen solution: <math>x = A \cos nt + B \sin nt + \frac{f}{n^2}</math></p> $\dot{x} = -An \sin nt + Bn \cos nt$ $\left. \begin{aligned} t = 0, x = 0 &\Rightarrow A = -\frac{f}{n^2} \\ t = 0, \dot{x} = 0 &\Rightarrow B = 0 \end{aligned} \right\}$ $x = \frac{f}{n^2}(1 - \cos nt)$	<p>(6)</p> <p>B1</p> <p>B1</p> <p>M1</p> <p>M1 A1ft</p> <p>M1 A1</p> <p>A1</p>
(c)	$\dot{x} = 0 \Rightarrow nt = \pi$ $x_{\max} = \frac{f}{n^2}(1 - (-1)) = \frac{2f}{n^2}$	<p>(8)</p> <p>M1</p> <p>M1 A1</p>
(d)	$\dot{y} = ft - \dot{x}$ $= f \frac{\pi}{n} - 0 = \frac{f\pi}{n}$	<p>(3)</p> <p>M1</p> <p>A1</p> <p>(2)</p> <p>[19]</p>

# Mark Scheme (Results) Summer 2010

GCE

GCE Mechanics M4 (6680/01)

Edexcel is one of the leading examining and awarding bodies in the UK and throughout the world. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. Through a network of UK and overseas offices, Edexcel's centres receive the support they need to help them deliver their education and training programmes to learners.

For further information, please call our GCE line on 0844 576 0025, our GCSE team on 0844 576 0027, or visit our website at [www.edexcel.com](http://www.edexcel.com).

If you have any subject specific questions about the content of this Mark Scheme that require the help of a subject specialist, you may find our [Ask The Expert](#) email service helpful.

Ask The Expert can be accessed online at the following link:

<http://www.edexcel.com/Aboutus/contact-us/>

Summer 2010

Publications Code UA024478

All the material in this publication is copyright

© Edexcel Ltd 2010

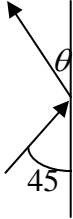
### Mechanic guidance:

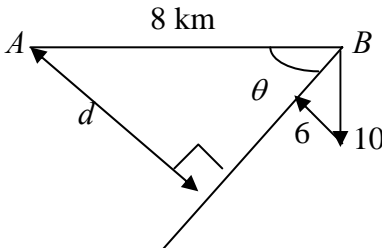
- For M marks, correct number of terms, dimensionally correct, all terms that need resolving are resolved.
- Omission of  $g$  from a resolution is an accuracy error, not a method error.
- Omission of mass from a resolution is a method error.
- Omission of a length from a moments equation is a method error.
- Where there is only one method mark for a question or part of a question, this is for a *complete* method.
- Omission of units is not (usually) counted as an error.
- Use of 9.81 for  $g$  is a rubric error. Deduct the final A1 from the first part of any question affected.
- More than 3 sf in an answer using an approximation for  $g$  is an accuracy error. Deduct the final A1 from the first part of any question affected.
- A dimensionally incorrect equation is a method error unless a correct equation was quoted and the error arises from a slip in substitution of values.
- For a misread which does not alter the character of a question or materially simplify it, all marks in that part of the question affected become ft. Deduct the first 2 A or B marks gained as a result and give the rest.



Summer 2010  
 Mechanics M4 6680  
 Mark Scheme

Question Number	Scheme	Marks
Q1	$v(3\mathbf{i} - 4\mathbf{j}) = \mathbf{v}_w - u\mathbf{j}$ $\mathbf{v}_w = 3v\mathbf{i} + (u - 4v)\mathbf{j}$ $w\mathbf{i} = \mathbf{v}_w - \frac{u}{5}(-3\mathbf{i} + 4\mathbf{j})$ $\mathbf{v}_w = (w - \frac{3u}{5})\mathbf{i} + \frac{4u}{5}\mathbf{j}$ $(u - 4v) = \frac{4u}{5}$ $v = \frac{u}{20}$ $\mathbf{v}_w = \frac{3u}{20}\mathbf{i} + \frac{4u}{5}\mathbf{j}$	<p>M1A1</p> <p>M1A1</p> <p>M1</p> <p>A1</p> <p>A1</p>

Question Number	Scheme	Marks
Q2	<p>(a)</p> $\begin{array}{ccc} \uparrow 2 & & \uparrow 1 \\ 1 \leftarrow & & \rightarrow 1 \\ S \ 0.3\text{kg} & & T \ 0.6 \text{ kg} \\ 2 \uparrow & & \uparrow 1 \\ \rightarrow v & & w \leftarrow \\ 0.3v - 0.6w = 0.3 \\ v - 2w = 1 \\ \frac{1}{2} (v + w) = 2 \\ v + w = 4 \\ w = 1, v = 3 \\ \text{(i) } \mathbf{u}_1 = 3\mathbf{i} + 2\mathbf{j} \quad \text{(ii) } \mathbf{u}_2 = -\mathbf{i} + \mathbf{j} \end{array}$ <p>(b)</p> $\begin{array}{ccc} \uparrow 1 & & \\ v \leftarrow & & \\ & & v = 0.5 \\ 1 \uparrow & & \\ \rightarrow 1 & & \end{array}$  <p> <math>\tan \theta = 0.5</math>  <math>\theta = 26.6</math>          Defln angle = <math>45 + 26.6 = 71.6^\circ</math> </p> <p> <math>\tan \theta = \text{their } v</math>          their <math>\theta + 45^\circ</math> </p> <p>(c)</p> $\begin{aligned} \text{KE Loss} &= \frac{1}{2} \times 0.6 \times \{(1^2 + 1^2) - (1^2 + v^2)\} \\ &= 0.225 \text{ J} \end{aligned}$	<p>M1 A1</p> <p>M1 A1</p> <p>A1 A1</p> <p>(6)</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(5)</p> <p>M1 A1</p> <p>A1</p> <p>(3)</p> <p>14</p>

Question Number	Scheme	Marks
Q3	<p>(a)</p>  <p style="text-align: center;"> <math>\cos \theta = \frac{6}{10} \Rightarrow \theta = 53.1^\circ</math>            Bearing is <math>307^\circ</math> </p> <p>(b)</p> <p style="text-align: center;"> <math>d = 8 \sin \theta (=8 \times 0.8)</math>  <math>= 6.4 \text{ km}</math> </p> <p>(c)</p> <p style="text-align: center;"> <math>T = \frac{8 \cos \theta}{\sqrt{10^2 - 6^2}}</math>  <math>= 0.6 \text{ hrs}</math>            i.e. the time is 12:36 pm         </p>	<p>M1</p> <p>M1 A1</p> <p>A1</p> <p style="text-align: right;">(4)</p> <p>M1 A1</p> <p>A1</p> <p style="text-align: right;">(3)</p> <p>M1 A1</p> <p>A1</p> <p style="text-align: right;">(3)</p> <p style="text-align: right;">10</p>



Question Number	Scheme	Marks
Q4		
(a)	$-mg\left(1 + \frac{v^2}{k^2}\right) = m \frac{dv}{dt}$ $g \int_0^T dt = \int_U^0 \frac{-k^2 dv}{(k^2 + v^2)}$ $T = \frac{k}{g} \left[ \tan^{-1} \frac{v}{k} \right]_0^U$ $= \frac{k}{g} \tan^{-1} \frac{U}{k}$	M1 A1 DM1 A1 DM1A1 (6)
(b)	$-mg\left(1 + \frac{v^2}{k^2}\right) = mv \frac{dv}{dx}$ $g \int_0^H dx = \int_U^0 \frac{-k^2 v dv}{(k^2 + v^2)}$ $H = \frac{k^2}{2g} \left[ \ln(k^2 + v^2) \right]_0^U$ $H = \frac{k^2}{2g} \ln \frac{(k^2 + U^2)}{k^2}$	M1 A1 DM1 A1 DM1A1 (6) 12

Question Number	Scheme	Marks
Q5	<p>(a)</p> $\sqrt{4a^2 + 16a^2 - 16a^2 \sin \theta}$ <p>Let length of string be <math>L</math>.</p> $V = -4mga \cos \theta - mg(L - \sqrt{4a^2 + 16a^2 - 16a^2 \sin \theta})$ $= -4mga \cos \theta - mgL + 2mga\sqrt{5 - 4 \sin \theta}$ $= 2mga \left\{ \sqrt{5 - 4 \sin \theta} - 2 \cos \theta \right\} + \text{constant} \quad **$ <p>(b)</p> $V'(\theta) = 2mga \left\{ \frac{-2 \cos \theta}{\sqrt{5 - 4 \sin \theta}} + 2 \sin \theta \right\}$ <p>For equilibrium, <math>V'(\theta) = 0</math></p> $\left\{ \frac{-2 \cos \theta}{\sqrt{5 - 4 \sin \theta}} + 2 \sin \theta \right\} = 0$ $\frac{\cos^2 \theta}{5 - 4 \sin \theta} = \sin^2 \theta$ $1 - \sin^2 \theta = \sin^2 \theta (5 - 4 \sin \theta)$ $4 \sin^3 \theta - 6 \sin^2 \theta + 1 = 0 \quad **$ <p>(c)</p> $V''(\theta) = 2mga \left( \frac{\left\{ \sqrt{5 - 4 \sin \theta} \cdot 2 \sin \theta - \frac{-2 \cos \theta \cdot (-4 \cos \theta)}{2\sqrt{5 - 4 \sin \theta}} \right\}}{(5 - 4 \sin \theta)} + 2 \cos \theta \right)$ $V''\left(\frac{\pi}{6}\right) = 2mga \left\{ \frac{\sqrt{3} - \frac{8 \times \frac{3}{4}}{2\sqrt{3}}}{3} + \sqrt{3} \right\} = 2mga\sqrt{3} > 0 \text{ so stable}$	<p>M1 A1</p> <p>M1 A1</p> <p>A1</p> <p>(5)</p> <p>M1 A1</p> <p>M1</p> <p>DM1</p> <p>A1</p> <p>(5)</p> <p>M1 A1 A1</p> <p>DM1 A1</p> <p>(5)</p> <p>15</p>

Question Number	Scheme	Marks
Q6		
(a)	$T_1 = \frac{2mge}{a}; T_2 = \frac{mg(2a-e)}{a}$ $T_1 = T_2$ $2e = (2a - e)$ $e = \frac{2a}{3}$ $AP = a + \frac{2a}{3} = \frac{5a}{3}$	B1 (either) M1 A1 A1 (4)
(b)	$T_2 - T_1 - 4m\omega\dot{x} = m\ddot{x}$ $\frac{mg}{a} \left( \frac{4a}{3} - x \right) - \frac{2mg}{a} \left( \frac{2a}{3} + x \right) - 4m\omega\dot{x} = m\ddot{x}$ $\ddot{x} + 4\omega\dot{x} + \frac{3g}{a}x = 0$ $\ddot{x} + 4\omega\dot{x} + 3\omega^2x = 0$	M1 A3 A1 (5)
(c)	$\lambda^2 + 4\omega\lambda + 3\omega^2 = 0$ $(\lambda + 3\omega)(\lambda + \omega) = 0$ $\lambda = -3\omega \text{ or } \lambda = -\omega$ $x = Ae^{-\omega t} + Be^{-3\omega t}$ $\dot{x} = -\omega Ae^{-\omega t} - 3\omega Be^{-3\omega t}$ $t = 0, x = \frac{1}{2}a, \dot{x} = 0$ $\frac{1}{2}a = A + B$ $0 = -\omega A - 3\omega B$ $A = \frac{3}{4}a, B = -\frac{1}{4}a$ $\dot{x} = v = \frac{3}{4}a\omega (e^{-3\omega t} - e^{-\omega t})$	M1 A1 M1 A1 M1 A1 A1 A1 (8)



Further copies of this publication are available from  
Edexcel Publications, Adamsway, Mansfield, Notts, NG18 4FN

Telephone 01623 467467  
Fax 01623 450481

Email [publications@linneydirect.com](mailto:publications@linneydirect.com)

Order Code UA024478 Summer 2010

For more information on Edexcel qualifications, please visit [www.edexcel.com/quals](http://www.edexcel.com/quals)

Edexcel Limited. Registered in England and Wales no.4496750  
Registered Office: One90 High Holborn, London, WC1V 7BH

# Mark Scheme (Results)

June 2011

GCE Mechanics M4 (6680) Paper 1

Edexcel is one of the leading examining and awarding bodies in the UK and throughout the world. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers.

Through a network of UK and overseas offices, Edexcel's centres receive the support they need to help them deliver their education and training programmes to learners.

For further information, please call our GCE line on 0844 576 0025 or visit our website at [www.edexcel.com](http://www.edexcel.com).

If you have any subject specific questions about the content of this Mark Scheme that require the help of a subject specialist, you may find our **Ask The Expert** email service helpful.

Ask The Expert can be accessed online at the following link:  
<http://www.edexcel.com/Aboutus/contact-us/>

June 2011

Publications Code UA028446

All the material in this publication is copyright

© Edexcel Ltd 2011

## EDEXCEL GCE MATHEMATICS

### General Instructions for Marking

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:
  - **M** marks: method marks are awarded for 'knowing a method and attempting to apply it', unless otherwise indicated.
  - **A** marks: Accuracy marks can only be awarded if the relevant method (M) marks have been earned.
  - **B** marks are unconditional accuracy marks (independent of M marks)
  - Marks should not be subdivided.

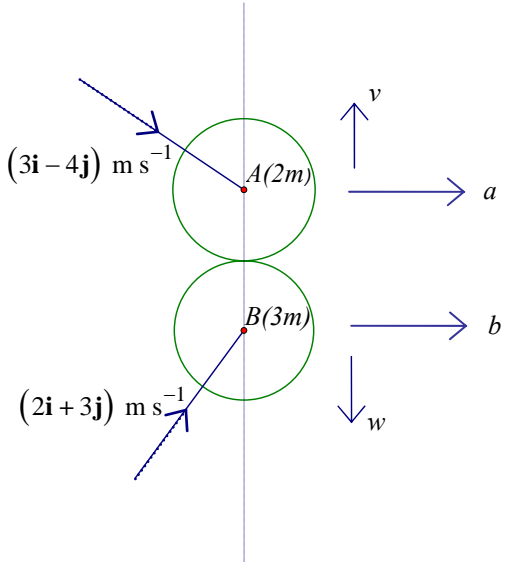
### 3. Abbreviations

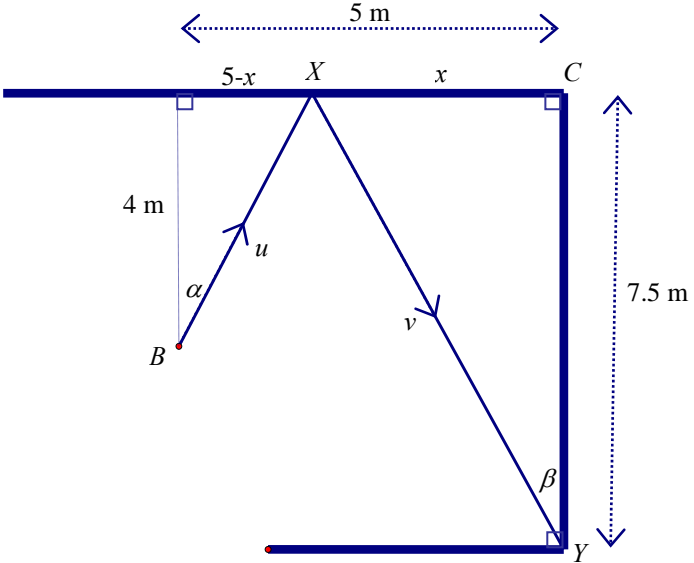
These are some of the traditional marking abbreviations that will appear in the mark schemes and can be used if you are using the annotation facility on ePEN.

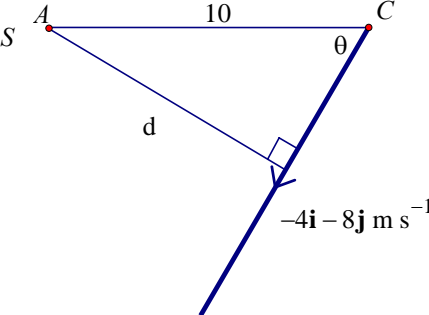
- bod – benefit of doubt
- ft – follow through
- the symbol  $\checkmark$  will be used for correct ft
- cao – correct answer only
- cso - correct solution only. There must be no errors in this part of the question to obtain this mark
- isw – ignore subsequent working
- awrt – answers which round to
- SC: special case
- oe – or equivalent (and appropriate)
- dep – dependent
- indep – independent
- dp decimal places
- sf significant figures
- \* The answer is printed on the paper
- $\square$  The second mark is dependent on gaining the first mark

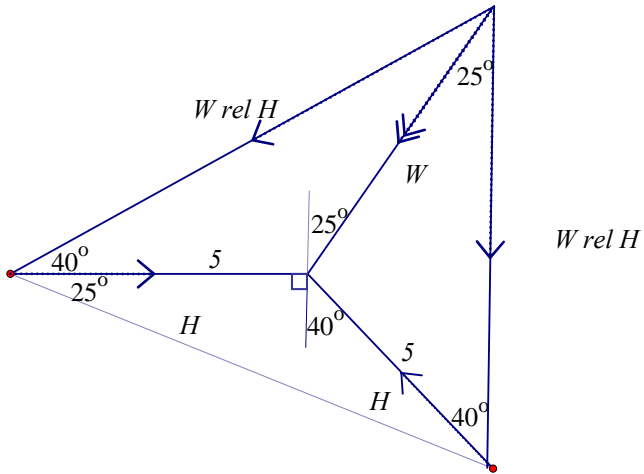


June 2011  
6680 Mechanics M4  
Mark Scheme

Question Number	Scheme	Marks
1.	 <p> <math>\leftrightarrow a = 3 \text{ \&amp; } b = 2</math>  b Conservation of linear momentum : <math>-4 \times 2 + 3 \times 3 = 2v - 3w (=1)</math>  Restitution : <math>v + w = e \times 7 (=3)</math>  Solve the simultaneous equations  giving <math>v = 2</math> and <math>w = 1</math>  KE lost = <math>\frac{1}{2} \times 2m \times ((16+9) - (4-9)) + \frac{1}{2} \times 3m \times ((9+4) - (1-4))</math>  = <math>24m \text{ (J)}</math> </p>	<p>B1 M1A1 M1A1 DM1 A1 M1A1 A1</p> <p style="text-align: right;"><b>10</b></p>

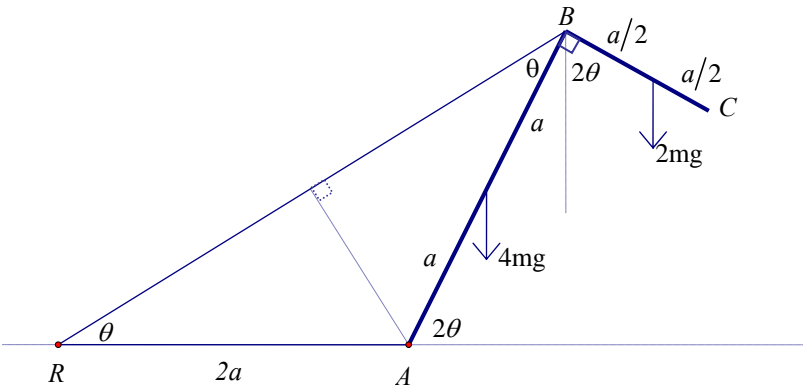
Question Number	Scheme	Marks
2.	 <p>At X: <math>\leftrightarrow u \sin \alpha = v \sin \beta</math>  <math>\updownarrow v \cos \beta = eu \cos \alpha</math>  <math>4v \cos \beta = 3u \cos \alpha</math></p> <p>Eliminate <math>u</math> &amp; <math>v</math> by dividing: <math>\frac{\tan \alpha}{3} = \frac{\tan \beta}{4}</math></p> <p>Substitute for the trig ratios: <math>\frac{5-x}{3 \times 4} = \frac{x}{4 \times 7.5}</math></p> <p>Solve for <math>x</math>: <math>37.5 - 7.5x = 3x</math>  <math>x = 3.57 \text{ (m)}</math> or better, <math>\frac{25}{7}</math></p>	<p>M1A1 M1A1</p> <p>M1</p> <p>DM1A1 DM1 A1</p> <p style="text-align: right;"><b>9</b></p>
3. (a)	<p>Velocity of C relative to S = <math>(8\mathbf{i} + u\mathbf{j}) - (12\mathbf{i} + 16\mathbf{j})</math>  <math>= (-4\mathbf{i} + (u - 16)\mathbf{j}) (\text{m s}^{-1})</math></p>	<p>M1 A1</p> <p style="text-align: right;">(2)</p>
(b) (i)	<p>C intercepts S <math>\Rightarrow</math> relative velocity is parallel to <math>\mathbf{i}</math>.  <math>\Rightarrow u - 16 = 0, u = 16</math></p>	<p>M1A1</p> <p style="text-align: right;">(2)</p>
(ii)	<p>10 km at <math>4 \text{ km h}^{-1}</math> takes 2.5 hours, so 2.30pm</p>	<p>M1A1</p> <p style="text-align: right;">(2)</p>

Question Number	Scheme	Marks
(c)	<p><math>u = 8</math>, relative velocity <math>= -4\mathbf{i} - 8\mathbf{j}</math>.</p>  <p>Correct distance identified</p> <p>Using velocity: <math>\tan \theta = \frac{8}{4} = 2 \Rightarrow \sin \theta = \frac{2}{\sqrt{5}}</math></p> <p>Using distance: <math>\sin \theta = \frac{d}{10} = \frac{2}{\sqrt{5}}</math>,</p> $d = \frac{20}{\sqrt{5}} = 4\sqrt{5} = 8.9 \text{ (km)}$	<p>B1</p> <p>B1</p> <p>M1A1</p> <p>A1 (5)</p> <p><b>11</b></p>

Question Number	Scheme	Marks
<p><b>4.</b></p> <p><b>(a)</b></p>	 <p>2 vector triangles with a common side .....correct and drawn on a single diagram Wind is from bearing 025°, (N 25° E)</p>	<p>M1 A1 A1</p> <p>(3)</p>
<p><b>(b)</b></p>	$\frac{5}{\sin 25^\circ} = \frac{W}{\sin 40^\circ}$ <p>(ft on their 25°)</p> $W = \frac{5 \times \sin 40^\circ}{\sin 25^\circ} = 7.6 \text{ (km h}^{-1}\text{)}$	<p>M1A1ft</p> <p>M1A1</p> <p>(4)</p>

Question Number	Scheme	Marks
<p><b>5.</b></p> <p><b>(a)</b></p>	<p>Need an equation linking speed and displacement, so</p> $mv \frac{dv}{dx} = -(a + bv^2)$ <p>Separating the variables: <math>\int \frac{6v}{a + bv^2} dv = \int -1 dx</math></p> <p>Integrating : <math>\frac{3}{b} \ln(a + bv^2) = -x + (C)</math></p> $X = \frac{3}{b} \left[ \ln(a + bU^2) - \ln(a) \right] = \frac{3}{b} \ln \left[ 1 + \frac{bU^2}{a} \right] \quad **$ <p>as required</p>	<p>M1A1</p> <p>M1</p> <p>A1</p> <p>M1A1</p> <p>(6)</p>
<p><b>(b)</b></p>	<p>Equation connecting <math>v</math> and <math>t</math>: <math>6 \frac{dv}{dt} = -(12 + 3v^2)</math></p> <p>Separate the variables: <math>\int \frac{-6}{12 + 3v^2} dv = \int 1 dt</math></p> $\int_U^0 \frac{-2}{4 + v^2} dv = \int_0^U \frac{2}{4 + v^2} dv = T$ $T = \frac{2}{2} \tan^{-1} \frac{U}{2} = \tan^{-1} \frac{U}{2} (\text{s})$	<p>M1</p> <p>M1, A1</p> <p>M1</p> <p>A1</p> <p>(5)</p> <p><b>11</b></p>

Question Number	Scheme	Marks
<b>6.</b> <b>(a)</b>	Using $F = ma$ : $4 \frac{d^2x}{dt^2} = -9x - 12v$ $= -9x - 12 \frac{dx}{dt}$ Hence $4 \frac{d^2x}{dt^2} + 12 \frac{dx}{dt} + 9x = 0$ **	M1A1 M1 A1 (4)
<b>(b)</b>	Auxiliary eqn : $4m^2 + 12m + 9 = 0$ , $(2m + 3)^2 = 0, m = -3/2, \lambda = 3/2$ $t = 0, x = 4 \Rightarrow B = 4$ $t = 0, \dot{x} = e^{-\lambda t} (-\lambda(At + B) + A) = 0 \Rightarrow -6 + A = 0, A = 6$	B1 B1 B1 B1 (4)
<b>(c)</b>	$\dot{x} = e^{-\frac{3}{2}t} \left( -\frac{3}{2}(6t + 4) + 6 \right) = -9te^{-\frac{3}{2}t}$ $\ddot{x} = e^{-\frac{3}{2}t} \left( -9 - (-9t) \times \frac{3}{2} \right),$ so acceleration = 0 when $t = 2/3$ at which time, $v = -6e^{-1}$ , so max speed = $6/e \approx 2.21 \text{ m s}^{-1}$ (3sf)	M1A1 M1 A1, A1 (5) <b>13</b>

Question Number	Scheme	Marks
<p>7. (a)</p>	 <p> <math>BR = 2 \times 2a \cos \theta = 4a \cos \theta</math>  <math>EPE = 3mg \frac{(4a \cos \theta)^2}{2 \times 2a}</math>  <math>= 12mga \cos^2 \theta = 6mga + 6mga \cos 2\theta</math> </p> <p>           GPE: taking AR as the level of zero GPE,  <math>GPE = GPE \text{ of } AB + GPE \text{ of } BC</math>  <math>= 4mg \times a \sin 2\theta + 2mg(2a \sin 2\theta - a/2 \cos 2\theta)</math>  <math>= 8mga \sin 2\theta - mga \cos 2\theta</math>  <math>\Rightarrow \text{Total } V = 8mga \sin 2\theta + 5mga \cos 2\theta + \text{constant, as required. **}</math> </p>	<p>B1 M1 A1 M1+M1 A1 A1 (7)</p>
<p>(b)</p>	$\frac{dV}{d\theta} = 16mga \cos 2\theta - 10mga \sin 2\theta$ $\frac{dV}{d\theta} = 0 \Rightarrow 10 \sin 2\theta = 16 \cos 2\theta$ $\Rightarrow \tan 2\theta = \frac{8}{5} \Rightarrow \theta = 0.51 \text{ radians } (29.0^\circ)$ <p>Or: <math>8mga \sin 2\theta + 5mga \cos 2\theta = \sqrt{89}mga \cos(2\theta - \alpha)</math>, <math>\tan \alpha = \frac{8}{5}</math>            t. pts when <math>2\theta - \alpha = n\pi \Rightarrow \theta = 0.51 \text{ rads.}</math></p>	<p>M1 A1 M1 A1 (4) M1A1 M1A1</p>
<p>(c)</p>	$\frac{d^2V}{d\theta^2} = -32mga \sin 2\theta - 20mga \cos 2\theta$ $\theta = 0.51 \Rightarrow \frac{d^2V}{d\theta^2} < 0, \text{ equilibrium is unstable.}$ <p>Or: <math>2\theta - \alpha = 0 \Rightarrow \cos(2\theta - \alpha) = 1</math>            Max value <math>\Rightarrow</math> equilibrium is unstable</p>	<p>M1 cso M1A1 (3) <b>14</b></p>





Further copies of this publication are available from  
Edexcel Publications, Adamsway, Mansfield, Notts, NG18 4FN

Telephone 01623 467467

Fax 01623 450481

Email [publication.orders@edexcel.com](mailto:publication.orders@edexcel.com)

Order Code UA028446 June 2011

For more information on Edexcel qualifications, please visit  
[www.edexcel.com/quals](http://www.edexcel.com/quals)

Pearson Education Limited. Registered company number 872828  
with its registered office at Edinburgh Gate, Harlow, Essex CM20 2JE

Ofqual



Llywodraeth Cynulliad Cymru  
Welsh Assembly Government



# Mark Scheme (Results)

Summer 2012

GCE Mechanics M4  
(6680) Paper 1

## **Edexcel and BTEC Qualifications**

Edexcel and BTEC qualifications come from Pearson, the world's leading learning company. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information, please visit our website at [www.edexcel.com](http://www.edexcel.com).

Our website subject pages hold useful resources, support material and live feeds from our subject advisors giving you access to a portal of information. If you have any subject specific questions about this specification that require the help of a subject specialist, you may find our Ask The Expert email service helpful.

[www.edexcel.com/contactus](http://www.edexcel.com/contactus)

### **Pearson: helping people progress, everywhere**

Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

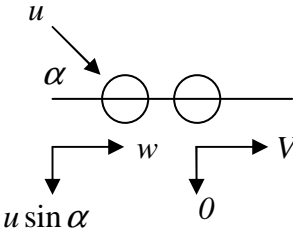
Summer 2012

Publications Code UA032684

All the material in this publication is copyright

© Pearson Education Ltd 2012

June 2012  
6680 Mechanics M4  
Mark Scheme

Question Number	Scheme	Marks	Notes
<p><b>1.</b> <b>(a)</b></p>	<div style="text-align: center;">  </div> <p><math>mu \cos \alpha = mw + 2mV</math></p> <p><math>eu \cos \alpha = -w + V</math></p> <p><math>u \cos \alpha (e + 1) = 3V \Rightarrow</math> (i) <math>u = \frac{15V}{7}</math></p> <p><math>\Rightarrow w = -\frac{2V}{7}</math></p> <p>(ii) speed of S <math>= \sqrt{\left(-\frac{2V}{7}\right)^2 + (u \sin \alpha)^2} = \frac{V\sqrt{85}}{7}</math></p>	<p>M1 A1</p> <p>M1 A1</p> <p>M1 A1</p> <p>A1</p> <p>M1</p> <p>A1</p>	<p>CLM parallel to the line of centres. <math>\frac{4}{5}u = w + 2V</math>.</p> <p>Need all terms but condone sign errors.</p> <p>Impact law. Must be the right way round.</p> <p><math>\frac{3}{4} \times \frac{4}{5}u = V - w</math></p> <p>Eliminate <math>w</math> and solve for <math>u</math> in terms of <math>V</math> or v.v.</p> <p>2.14V or better</p> <p>Solve for <math>w</math> in terms of <math>V</math>. -0.286V or better</p> <p>Use of Pythagoras with their <math>u \sin \alpha</math> and <math>w</math>.</p> <p><math>\sqrt{\left(\frac{-2V}{7}\right)^2 + \left(\frac{15V}{7} \times \frac{3}{5}\right)^2}</math></p> <p><math>\sqrt{\frac{85}{49}}V</math>, accept 1.32V or better</p> <p>(9)</p>

Question Number	Scheme	Marks	Notes
(b)	$\tan \theta = \frac{\frac{9V}{7}}{\frac{2V}{7}} = \frac{9}{2}$ defln angle = $180^\circ - (\theta + \alpha)$ = $65.7^\circ$ (3 sf)	M1 A1 DM1 A1 (4) <b>13</b>	Direction of $S$ after the collision. Condone $\frac{2}{9}$  $77.5^\circ$ or $12.5^\circ$ seen or implied Combine their $\theta$ and $\alpha$ to find the required angle. e.g. $12.5^\circ + \tan^{-1}\left(\frac{4}{3}\right)$ Accept $66^\circ$

Question Number	Scheme	Marks	Notes
2.	<p>With <math>B</math> as origin,</p> $\mathbf{r}_A = (6 \sin 30 \mathbf{i} + 6 \cos 30 \mathbf{j})$ $= (3) \mathbf{i} + (3\sqrt{3}) \mathbf{j}$ $\mathbf{r}_B = vt \mathbf{i} \text{ or } \mathbf{v}_B = v \mathbf{i}$ $(v - 4) \mathbf{i} + (4\sqrt{3}) \mathbf{j}$ <p>or <math>(v - 8 \sin 30) \mathbf{i} + (8 \cos 30) \mathbf{j}</math></p> <p>When <math>B</math> is <math>2\sqrt{3}</math> km south of <math>A</math>,</p> $-3\sqrt{3} + 4\sqrt{3}t = -2\sqrt{3} \Rightarrow t = \frac{1}{4}$ $vt - 3 - 4t = 0 \Rightarrow v = 16$ <p>When <math>B</math> is due east of <math>A</math>,</p> $-3\sqrt{3} + 4\sqrt{3}t = 0 \Rightarrow t = \frac{3}{4} \text{ i.e. at 12.45 pm}$ <p>then distance <math>AB = 16 \times \frac{3}{4} - 3 - 4 \times \frac{3}{4} = 6</math> km.</p>	<p>M1</p> <p>A1</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p><b>13</b></p>	<p>Express the original relative positions in component (vector) form – one term correct.</p> <p>Both terms correct (substitution of trig values not required).</p> <p>Position of <math>B</math> at time <math>t</math> (seen or implied)</p> <p>Express the relative velocity in component form – one term correct.</p> <p>Both terms correct</p> <p>Compare <math>\mathbf{j}</math> displacement with <math>\pm 2\sqrt{3}</math> and solve for <math>t</math></p> <p>cao</p> <p>Equate <math>\mathbf{i}</math> displacement to zero and substitute their value of <math>t</math>.</p> <p>cao</p> <p>Equate <math>\mathbf{j}</math> displacement to zero and solve for <math>t</math>.</p> <p>Any equivalent form for the time.</p> <p>Substitute their <math>v</math> &amp; <math>t</math> in the <math>\mathbf{i}</math> displacement and evaluate</p> <p>cao. Must be a scalar.</p> <p style="text-align: right;"><i>See over page for geometrical alternative</i></p>

or

Triangle  $ABC$ : cosine rule gives

$$BC^2 = 36 + 12 - 2 \times 6 \times 2\sqrt{3} \cos 30$$

Solve for  $BC$  and  $\angle ABC$

$$BC = 2\sqrt{3}, \rightarrow \text{triangle is isosceles}$$

$\angle B$  in velocity triangle is  $30^\circ$

Trig in rt  $\angle$  triangle gives relative velocity

$$= 8 \times \tan 60 = 8\sqrt{3}$$

$\angle APB = 30^\circ$  (angles of a triangle) so triangle is isosceles and

distance  $AP = 6\text{km}$

Using cosine rule or symmetry of isosceles triangle, distance  $BP = 6\sqrt{3}$

$$\text{Time taken} = \frac{6\sqrt{3}}{8\sqrt{3}} = \frac{3}{4} \text{ hr, time is now } 12.45$$

M1A1

M1A1

B1

M1A1

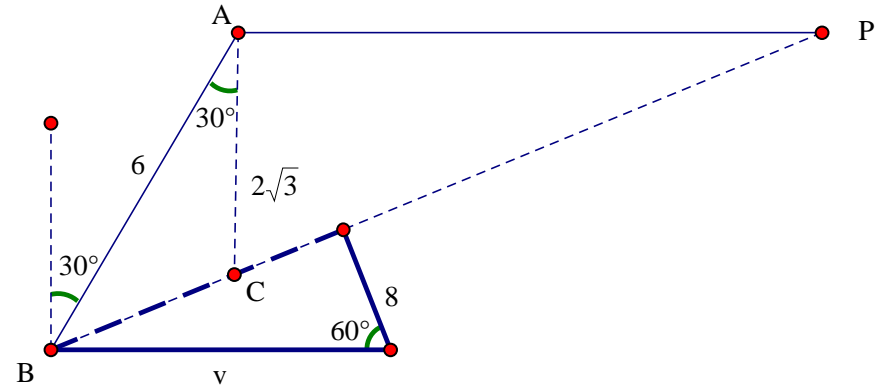
M1A1

M1A1

M1A1

The given information provides us with two triangles - velocities in bold.

Fix  $A$  and  $B$  follows the path  $BP$ .  $C$  is the point when  $B$  is due South of  $A$ , and  $P$  when it is due East.



<p>3. (a)</p>	$2mg - T - kv^2 = 2ma$ $T - mg - kv^2 = ma$ <p>Adding, <math>mg - 2kv^2 = 3ma</math></p> $\frac{2g}{3} - \frac{4kv^2}{3m} = 2v \frac{dv}{dx}$ $\frac{d(v^2)}{dx} + \frac{4kv^2}{3m} = \frac{2g}{3} *$	<p>M1 A1 M1 A1</p> <p>DM1</p> <p>A1</p> <p>(6)</p>	<p>Equation of motion for particle of mass <math>2m</math> aef</p> <p>Equation of motion for particle of mass <math>m</math> aef</p> <p>Eliminate <math>T</math>, substitute for <math>a</math> and rearrange. Dependent on both previous M marks.</p> <p>Reach <b>given answer</b> correctly</p>
<p>(b)</p>	$IF = e^{\int \frac{4k}{3m} dx} = e^{\frac{4kx}{3m}}$ $v^2 e^{\frac{4kx}{3m}} = \frac{2g}{3} \int e^{\frac{4kx}{3m}} dx = \frac{mg}{2k} e^{\frac{4kx}{3m}} (+C)$ $v^2 = \frac{mg}{2k} + Ce^{-\frac{4kx}{3m}}$ $x = 0, v = 0 \Rightarrow C = -\frac{mg}{2k}$ $v^2 = \frac{mg}{2k} (1 - e^{-\frac{4kx}{3m}})$	<p>B1</p> <p>M1 A1</p> <p>M1</p> <p>A1</p> <p>(5)</p>	<p>Use integrating factor to obtain <math>\frac{d}{dx} \left( v^2 e^{\frac{4kx}{3m}} \right) = \frac{2g}{3} e^{\frac{4kx}{3m}}</math> and integrate</p> <p>Use initial values to evaluate <math>C</math> or as limits in a definite integral and find an expression for <math>v^2</math>. aef.</p>
<p>OR</p>	<p>Separate variables: <math>\int \frac{3m}{2mg - 4kv^2} dv^2 = \int 1 dx</math></p> $x = -\frac{3m}{4k} \ln  2mg - 4kv^2  (+C)$ $x = -\frac{3m}{4k} \ln \left  \frac{2mg}{2mg - 4kv^2} \right $ $v^2 = \frac{mg}{2k} (1 - e^{-\frac{4kx}{3m}})$	<p>B1</p> <p>M1A1</p> <p>M1</p> <p>A1</p>	<p>CF <math>v^2 = Ae^{-\frac{4k}{3m}x}</math></p> <p>PI <math>v^2 = b \Rightarrow 0 + \frac{4k}{3m}b = \frac{2g}{3}</math>; GS <math>v^2 = Ae^{-\frac{4k}{3m}x} + \frac{mg}{2k}</math></p> <p><math>x = 0, v = 0 \Rightarrow A = -\frac{mg}{2k}</math></p> $v^2 = \frac{mg}{2k} (1 - e^{-\frac{4kx}{3m}})$



(c) When  $x = 0, T = \frac{4mg}{3}$

As  $x \rightarrow \infty, T \rightarrow \frac{9mg}{6} = \frac{3mg}{2}$

Hence,  $\frac{4mg}{3} \leq T < \frac{3mg}{2}$ . \*

M1  
A1  
M1  
A1  
A1

Substitute  $v = 0$  in the initial equations and solve for  $T$

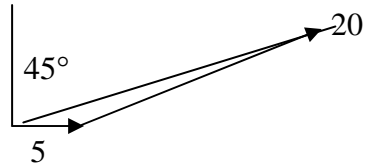
For large  $x, v^2 \rightarrow \frac{mg}{2k}$ .

Substitute in the initial equations and solve for  $T$

cwo – **answer is given.**

(5)16

4.(a)



$$\frac{\sin \theta}{5} = \frac{\sin 45}{20}$$

$$\theta = 10.182\dots$$

Bearing is  $45^\circ - \theta = 34.8 = 35^\circ$  (nearest degree)

OR

$$\text{SW} \rightarrow (20 \sin \theta)T = (5 + 20 \cos \theta)T$$

$$3t^2 + 8t - 5 = 0, t = \frac{-8 + \sqrt{124}}{6} = 0.5225\dots$$

$$\theta = 55.18\dots \text{ Bearing is } 90 - \theta = 34.8^\circ$$

(b)

$$v^2 = 5^2 + 20^2 - 2 \times 5 \times 20 \cos 124.818\dots$$

$$\text{OR } v = \frac{20}{\sin 45} \times \sin 124.8$$

$$\text{OR } v = 5 \cos 45 + 20 \cos \theta$$

$$v = 23.22$$

$$t = \frac{15}{23.22} = 0.646 \text{ h} = 39 \text{ min (nearest min)}$$

(c)

Due N, (since current affects both equally)

(d)

$$t = \frac{4}{20} = 0.2 \text{ h} = 12 \text{ min}$$

M1

A1

M1

A1 (4)

M1

A1

M1A1

(4)

M1

A1

M1

A1

(4)

B1

(1)

B1

(1)10

Use a vector triangle to find  $\theta$ .

Condone the  $5 \text{ ms}^{-1}$  in the wrong direction.

Correct equation for  $\theta$

Use their angle correctly in their triangle to find the bearing.

(4) Accept alternative forms e.g. N 35 E

$45^\circ$  rt angle triangle

t substitution leading to correct equation in  $t$ , use of  $R \cos(\theta + \alpha)$  o.e.

Complete method to find  $v$

Or better  $\left( \frac{5\sqrt{2} + 5\sqrt{62}}{2} \right)$

$\frac{15}{\text{their } v}$

The Q specifies "nearest minute"

cao

cs0



5.  
(a)

$$V = -Wa \cos 2\theta + \frac{1}{2}W \{3a - (L - 6a \cos \theta - 4a)\}$$

$$= -Wa \cos 2\theta + 3Wa \cos \theta + \left(\frac{7Wa}{2} - \frac{WL}{2}\right)$$

$$= Wa(3 \cos \theta - \cos 2\theta) + \text{constant} \quad *$$

(b)

$$\frac{dV}{d\theta} = Wa(-3 \sin \theta + 2 \sin 2\theta)$$

For equilibrium,  $Wa(-3 \sin \theta + 2 \sin 2\theta) = 0$   
 $\sin \theta(4 \cos \theta - 3) = 0$

$$\Rightarrow \theta = 0 \text{ or } \theta = \cos^{-1}\left(\frac{3}{4}\right)$$

$$\frac{d^2V}{d\theta^2} = Wa(-3 \cos \theta + 4 \cos 2\theta)$$

$$\theta = 0: \frac{d^2V}{d\theta^2} = Wa > 0 \Rightarrow \text{stable}$$

$$\theta = \cos^{-1}\frac{3}{4}: \frac{d^2V}{d\theta^2} = -\frac{7Wa}{4} < 0 \Rightarrow \text{unstable}$$

B1

M1

A1

A1

(4)

M1

A1

DM1

A1

A1

M1

A1

A1

(8)

12

GPE of rod e.g.  $-Wa \cos 2\theta$

GPE of the particle e.g.  $\frac{1}{2}W \{3a - (L - 6a \cos \theta - 4a)\}$

Condone 3a term missing.

Correct expression including the 3a (unless in the GPE for the rod)

Accept aef e.g.  $\sqrt{18a^2(1 + \cos 2\theta)}$  for  $6a \cos \theta$

Obtain the **given answer** correctly

Differentiate the given  $V$  wrt  $\theta$

correct

Set their derivative = 0

First answer

Second answer - ignore  $\theta = -\cos^{-1}\left(\frac{3}{4}\right)$ . 0.72 rads or better

Obtain the second derivative of  $V$  and substitute one of their values for  $\theta$

Correct working and conclusion for one value

Correct working and reasoning for the second.

ISW for work on  $-\cos^{-1}\left(\frac{3}{4}\right)$

6.(a)

$$T_1 = mg + T_2$$

$$\frac{3mge}{a} = mg + \frac{mg(2a - e)}{a}$$

$$e = \frac{3a}{4} \Rightarrow AP = \frac{7a}{4} *$$

(b)

$$mg + T_2 - T_1 - mkv = m\ddot{x}$$

$$mg + \frac{mg(\frac{5}{4}a - x)}{a} - \frac{3mg(\frac{3}{4}a + x)}{a} - mkv = m\ddot{x}$$

$$-kx + \frac{4g}{a}x = 0 *$$

(c)

For a damped oscillation,  $k^2 < \frac{16g}{a}$

$$\text{i.e. } k < 4\sqrt{\frac{g}{a}}$$

M1

A1

A1

(3)

M1

A1

DM1

A1

A1

(5)

M1

A1

A1

(3)

11

No resultant force and use of Hooke's law

Correct equation in one unknown

$$\frac{3mg(AP - a)}{a} = mg + \frac{mg(3a - AP)}{a}, 3AP - 3a = a + 3a - AP$$

Derive **given result** correctly.

Condone verification for 3/3

Equation of motion – requires all terms but condone sign errors.

o.e. Correct equation in  $T_1$  &  $T_2$ .

Use Hooke's law with extensions of the form  $ka \pm x$

o.e. Correct unsimplified

**Given answer** derived correctly

AE will have complex roots

Correctly substituted inequality

Only (Q gives  $k > 0$ )  $-4\sqrt{\frac{g}{a}} < k < 4\sqrt{\frac{g}{a}}$  is A0.



Further copies of this publication are available from  
Edexcel Publications, Adamsway, Mansfield, Notts, NG18 4FN

Telephone 01623 467467

Fax 01623 450481

Email [publication.orders@edexcel.com](mailto:publication.orders@edexcel.com)

Order Code UA032684 Summer 2012

For more information on Edexcel qualifications, please visit our website  
[www.edexcel.com](http://www.edexcel.com)

Pearson Education Limited. Registered company number 872828  
with its registered office at Edinburgh Gate, Harlow, Essex CM20 2JE

Ofqual  
■■■■■■■■■■



Llywodraeth Cynulliad Cymru  
Welsh Assembly Government



Mark Scheme (Results)

Summer 2013

GCE Mechanics 4 (6680/01R)



## **Edexcel and BTEC Qualifications**

Edexcel and BTEC qualifications come from Pearson, the world's leading learning company. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information, please visit our website at [www.edexcel.com](http://www.edexcel.com).

Our website subject pages hold useful resources, support material and live feeds from our subject advisors giving you access to a portal of information. If you have any subject specific questions about this specification that require the help of a subject specialist, you may find our Ask The Expert email service helpful.

[www.edexcel.com/contactus](http://www.edexcel.com/contactus)

## **Pearson: helping people progress, everywhere**

Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

Summer 2013

Publications Code UA036436

All the material in this publication is copyright

© Pearson Education Ltd 2013

## General Marking Guidance

- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

# EDEXCEL GCE MATHEMATICS

## General Instructions for Marking

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:
  - **M** marks: method marks are awarded for 'knowing a method and attempting to apply it', unless otherwise indicated.
  - **A** marks: accuracy marks can only be awarded if the relevant method (M) marks have been earned.
  - **B** marks are unconditional accuracy marks (independent of M marks)
  - Marks should not be subdivided.
3. Abbreviations

These are some of the traditional marking abbreviations that will appear in the mark schemes:

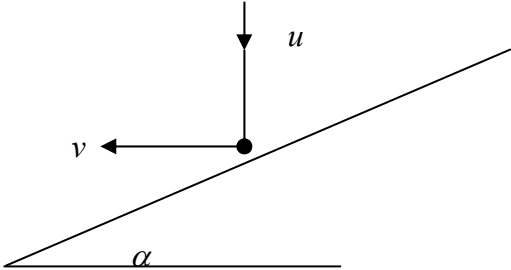
- bod – benefit of doubt
  - ft – follow through
  - the symbol  $\surd$  will be used for correct ft
  - cao – correct answer only
  - cso - correct solution only. There must be no errors in this part of the question to obtain this mark
  - isw – ignore subsequent working
  - awrt – answers which round to
  - SC: special case
  - oe – or equivalent (and appropriate)
  - dep – dependent
  - indep – independent
  - dp decimal places
  - sf significant figures
  - \* The answer is printed on the paper
  - $\square$  The second mark is dependent on gaining the first mark
4. All A marks are 'correct answer only' (cao.), unless shown, for example, as A1 ft to indicate that previous wrong working is to be followed through. After a misread however, the subsequent A marks affected are treated as A ft, but manifestly absurd answers should never be awarded A marks.
  5. For misreading which does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, in that part of the question affected.
  6. If a candidate makes more than one attempt at any question:
    - If all but one attempt is crossed out, mark the attempt which is NOT crossed out.
    - If either all attempts are crossed out or none are crossed out, mark all the attempts and score the highest single attempt.
  7. Ignore wrong working or incorrect statements following a correct answer.
  8. In some instances, the mark distributions (e.g. M1, B1 and A1) printed on the candidate's response may differ from the final mark scheme

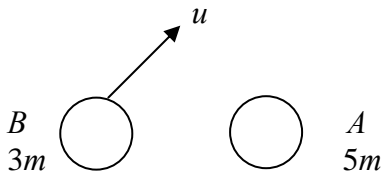
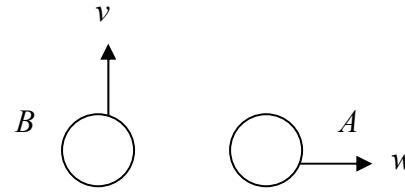
## General Rules for Marking Mechanics

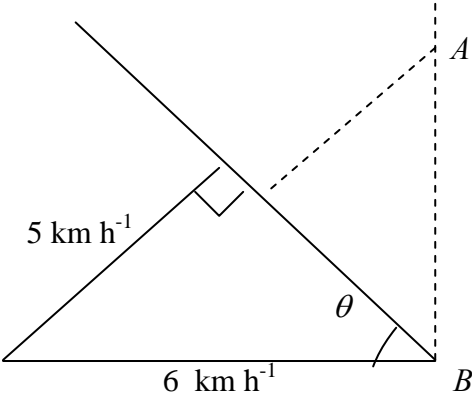
- Usual rules for M marks: correct no. of terms; dim correct; all terms that need resolving (i.e. multiplied by cos or sin) are resolved.
- Omission or extra  $g$  in a resolution is accuracy error not method error.
- Omission of mass from a resolution is method error.
- Omission of a length from a moments equation is a method error.
- Omission of units or incorrect units is not (usually) counted as an accuracy error.
- DM indicates a dependent method mark i.e. one that can only be awarded if a previous specified method mark has been awarded.
- Any numerical answer which comes from use of  $g = 9.8$  should be given to 2 or 3 SF.
- Use of  $g = 9.81$  should be penalised once per (complete) question.
- N.B. Over-accuracy or under-accuracy of correct answers should only be penalised *ONCE* per complete question.
- In all cases, if the candidate clearly labels their working under a particular part of a question i.e. (a) or (b) or (c),.....then that working can only score marks for that part of the question.
- Accept column vectors in all cases.

Misreads – if a misread does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, bearing in mind that after a misread, the subsequent A marks affected are treated as A ft.

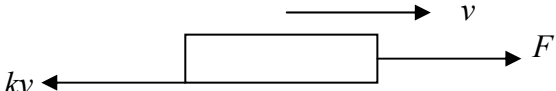
Question Number	Scheme	Marks	
<p><b>1. (a)</b></p>	${}^A \mathbf{v}_B = \mathbf{v}_A - \mathbf{v}_B$ $= -3\mathbf{i} + 9\mathbf{j} \text{ km h}^{-1}$ $\text{Mag} = \sqrt{9+81} = 3\sqrt{10}$	<p>M1 M1A1 <b>(3)</b></p>	<p>9.5 or better</p>
<p><b>(b)</b></p>	$\tan \theta = \frac{3}{9}$ $\theta = 18.4^\circ$ $\text{Direction} = 360 - 18.4$ $= 342^\circ$	<p>M1  A1 <b>(2)</b> <b>[5]</b></p>	<p>Allow <math>\pm</math> or reciprocal  Or <math>71.6^\circ</math>  Allow <math>341.6^\circ</math></p>

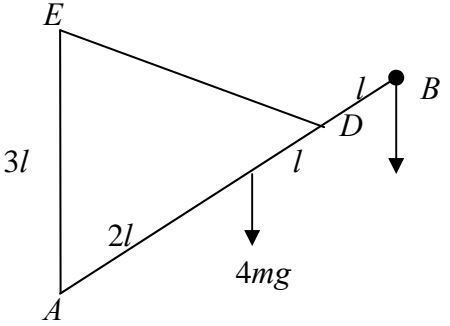
Question Number	Scheme	Marks	
2.	<div style="text-align: center;">  </div> <p>CLM: <math>u \sin \alpha = v \cos \alpha</math></p> <p>Impact: <math>\frac{1}{3} u \cos \alpha = v \sin \alpha</math></p> $\frac{1}{3} \times \frac{1}{\tan \alpha} = \tan \alpha$ $\tan \alpha = \frac{1}{\sqrt{3}}$ $\alpha = 30^\circ \text{ (or } \frac{\pi}{6} \text{ or } 0.52 \text{ rad)}$	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(6)</p> <p>[6]</p>	<p>Must be in correct direction but condone trig confusion</p> <p>Condone consistent trig confusion</p>

Question Number	Scheme	Marks	
<p><b>3.</b></p> <p><b>(a)</b></p> <p><b>(b)</b></p>	<p style="text-align: center;">  </p> <p style="text-align: center;">  </p> <p>After impact <math>B</math> moves perpendicular to the line of centres</p> <p>Perp. to line of centres: <math>v = u \sin 60 = u \frac{\sqrt{3}}{2}</math></p> <p>Parallel to line of centres:  Con of Mom <math>3mu \cos 60 + 5m \times 0 = 3m \times 0 + 5mw</math>  N.L.R. <math>eu \cos 60 = w</math></p> $\frac{1}{2}eu = w \quad \& \quad \frac{3}{2}u = 5w$ $\rightarrow \frac{1}{2}eu = \frac{3}{10}u$ $e = \frac{3}{5}$	<p>B1</p> <p>M1A1</p> <p><b>(3)</b></p> <p>M1A1</p> <p>M1A1</p> <p>DM1</p> <p>A1</p> <p><b>(6)</b></p> <p><b>[9]</b></p>	<p>can be implied by appropriate use of <math>\theta</math> in an equation, or seen on the diagram</p> <p>Dependent on the two previous M marks</p>

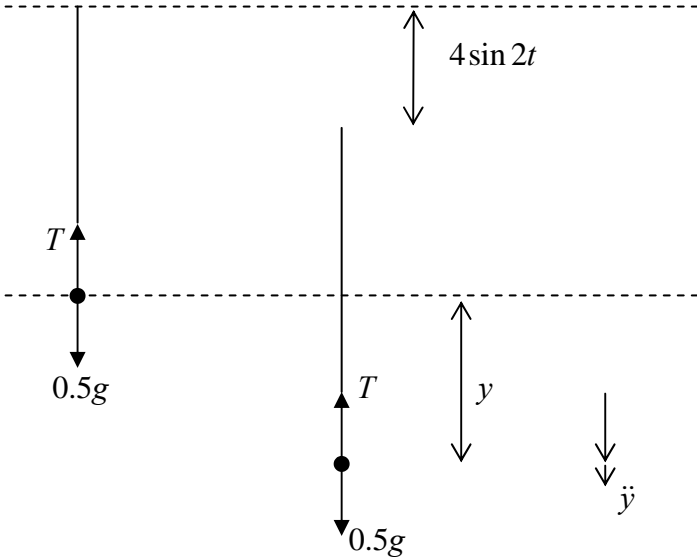
Question Number	Scheme	Marks	
4.	 <p data-bbox="259 738 595 890">(a) <math>\sin \theta = \frac{5}{6}</math>  <math>\theta = 56.44\dots</math>  Bearing = <math>056^\circ</math></p> <p data-bbox="259 938 1032 1034">(b) Least distance = <math>4 \cos \theta = \frac{(4\sqrt{11})}{6}</math> or 2.211 km oe</p> <p data-bbox="259 1082 707 1257">(c) <math>{}_B v_A = \sqrt{6^2 - 5^2} = \sqrt{11}</math>  <math>t = \frac{4 \sin \theta}{\sqrt{11}}</math> (= 1.0050...)  time = 11 am</p>	<p data-bbox="1223 459 1256 491">B1</p> <p data-bbox="1223 762 1256 794">M1</p> <p data-bbox="1223 826 1256 858">A1</p> <p data-bbox="1223 866 1256 898">A1</p> <p data-bbox="1290 898 1323 930">(4)</p> <p data-bbox="1223 954 1256 986">M1</p> <p data-bbox="1223 994 1256 1026">A1</p> <p data-bbox="1290 1042 1323 1074">(2)</p> <p data-bbox="1223 1090 1256 1121">B1</p> <p data-bbox="1223 1145 1256 1177">M1</p> <p data-bbox="1223 1185 1279 1217">A1ft</p> <p data-bbox="1223 1225 1256 1257">B1</p> <p data-bbox="1290 1265 1323 1297">(4)</p> <p data-bbox="1267 1297 1323 1329">[10]</p>	<p data-bbox="1355 443 2000 515">Right angled triangle with the right angle opposite the 6 seen in diagram or implied in working</p> <p data-bbox="1355 738 1514 770">Correct trig.</p> <p data-bbox="1355 866 1514 898">Allow <math>56.4^\circ</math></p> <p data-bbox="1355 954 1641 1018">Correct for their angle 2.2 or better</p> <p data-bbox="1355 1090 1417 1121">3.32</p> <p data-bbox="1355 1137 1794 1201">Condone consistent trig confusion Ft on their <math>\sqrt{11}</math></p>



Question Number	Scheme	Marks	
<p>5.</p> <p>(a)</p> <p>(b)</p>	 $Fv = 40000$ $1200 \frac{dv}{dt} = \frac{40000}{v} - kv$ $\frac{dv}{dt} = 0.3 \quad 1200 \times 0.3 = \frac{40000}{40} - 40k$ $k = 16$ $1200 \frac{dv}{dt} = \frac{40000}{v} - 16v$ $1200v \frac{dv}{dt} = 40000 - 16v^2$ $75v \frac{dv}{dt} = 2500 - v^2$ $75 \int \frac{v}{2500 - v^2} dv = \int dt$ $-\frac{75}{2} \ln(2500 - v^2) = t \quad (+c)$ $t = 0 \quad v = 0 \Rightarrow -\frac{75}{2} \ln 2500 = c$ $-\frac{75}{2} \ln \left( \frac{2500 - v^2}{2500} \right) = t$ $\frac{2500 - v^2}{2500} = e^{-\frac{2t}{75}} \rightarrow v^2 = 2500 \left( 1 - e^{-\frac{2t}{75}} \right)$ $v = 50 \sqrt{1 - e^{-\frac{2t}{75}}}$	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(6)</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>(6)</p> <p>[12]</p>	<p>Use initial conditions to find <math>k</math></p> <p><u>Given Answer</u></p> <p>Separate and attempt integration</p> <p>Use initial values to find <math>c</math></p> <p>Or equivalent</p> <p>Find <math>v</math> or <math>v^2</math> in terms of <math>t</math></p>

Question Number	Scheme	Marks	
<p>6.</p> <p>(a)</p>	 <p>Length of string = <math>2 \times 3l \sin \theta</math>  Extension = <math>6l \sin \theta - l</math>  E.P.E. = <math>\frac{4mg}{2l} (6l \sin \theta - l)^2</math>  G.P.E. of rod = <math>4mg \times 2l \cos 2\theta</math>  G.P.E. of mass at B = <math>kmgl \times 4l \cos 2\theta</math>  <math>V = \frac{4mg}{2l} (6l \sin \theta - l)^2 + 8mgl \cos 2\theta + 4kmgl \cos 2\theta + \text{const}</math></p> <p><math>V = \frac{4mg}{2l} (6l \sin \theta - l)^2 + 8mgl(1 - 2\sin^2 \theta) + 4kmgl \cos 2\theta + \text{const}</math></p> <p><math>= 2mgl(36\sin^2 \theta - 12\sin \theta - 8\sin^2 \theta - 4k \sin^2 \theta) + \text{const}</math>  <math>= 8mgl((7 - k)\sin^2 \theta - 3\sin \theta) + \text{constant}</math></p>	<p>B1</p> <p>M1</p> <p>A2</p> <p>M1</p> <p>A1</p> <p>(6)</p>	<p>EPE term needs to be dimensionally correct. Need all three terms.</p> <p>Correct unsimplified</p> <p>All in <math>\sin \theta</math></p> <p><b>Given Answer</b></p>

Question Number	Scheme	Marks	
(b)	$\frac{dV}{d\theta} = 8mgl(2(7-k)\sin\theta\cos\theta - 3\cos\theta)$ $\frac{dV}{d\theta} = 0 \quad (2(7-k)\sin\theta - 3)\cos\theta = 0$ $\sin\theta = \frac{3}{2(7-k)} \quad (\text{or } \cos\theta = 0, \text{ need not be seen})$ $\theta \leq \frac{\pi}{6} \Rightarrow \frac{3}{2(7-k)} \leq \frac{1}{2}$ $3 \leq 7-k \quad k \leq 4 \quad *$	M1 M1 A1 M1 A1 <b>(5)</b>	Differentiate Set derivative = 0 Use of $\sin\theta \leq \frac{1}{2}$
(c)	$k = 4 \Rightarrow \theta = \frac{\pi}{6}$ $\frac{d^2V}{d\theta^2} = 8mgl[6\cos^2\theta - (6\sin\theta - 3)\sin\theta]$ $= 8mgl\left[6 \times \left(\frac{\sqrt{3}}{2}\right)^2 - 6 \times \left(\frac{1}{2}\right)^2 + 3 \times \frac{1}{2}\right]$ $\frac{d^2V}{d\theta^2} > 0$ <p><math>V</math> is min. <math>\therefore</math> stable equilibrium</p>	B1 M1 A1 M1 A1 <b>(5)</b> <b>[16]</b>	Second derivative ( $8mgl$ or $24mgl$ not needed) [or differentiate $8mgl(3\sin 2\theta - 3\cos\theta)$ ] Numerical unsimplified by numerical evaluation or justification from trig terms ( $36mgl$ ) CSO

Question Number	Scheme	Marks	
7	 <p data-bbox="257 782 302 813">(a) In equilibrium <math>T = 0.5g = \frac{2.7e}{0.6}</math>  <math>e = \frac{g}{9} = \frac{9.8}{9} = \frac{49}{45}</math>  <math>0.6 + \frac{49}{45} - 4 \sin 2t + y = 0.6 + x</math>  <math>y + \frac{49}{45} = x + 4 \sin 2t</math></p> <p data-bbox="257 1189 302 1220">(b) <math>0.5g - \frac{2.7x}{0.6} = 0.5\ddot{y}</math>  <math>g - 9x = \ddot{y}</math>  <math>g - 9\left(y + \frac{g}{9} - 4 \sin 2t\right) = \ddot{y}</math>  <math>\ddot{y} + 9y = 36 \sin 2t</math></p>	<p data-bbox="1220 782 1265 813">M1</p> <p data-bbox="1220 861 1265 893">A1</p> <p data-bbox="1220 1029 1265 1061">A1</p> <p data-bbox="1288 1093 1332 1125">(3)</p> <p data-bbox="1220 1189 1310 1220">M1A1</p> <p data-bbox="1220 1340 1299 1372">DM1</p> <p data-bbox="1220 1380 1265 1412">A1</p> <p data-bbox="1220 1428 1265 1460">A1</p> <p data-bbox="1288 1460 1332 1492">(5)</p>	<p data-bbox="1355 1005 1848 1037"><b>Given Answer</b> – must see justification</p> <p data-bbox="1355 1165 1680 1197">Equation of motion for <math>P</math></p> <p data-bbox="1355 1332 1556 1364">Substitute for <math>x</math></p> <p data-bbox="1355 1420 1556 1452"><b>Given Answer</b></p>

Question Number	Scheme	Marks	
(c)	C.F. is $y = A \cos 3t + B \sin 3t$	M1	Independent. Differentiate and use initial conditions to find $B$
	Gen. soln. is $y = A \cos 3t + B \sin 3t + \frac{36}{5} \sin 2t$	A1	
	$t = 0 \quad y = 0 \Rightarrow A = 0$	B1	
	$\dot{y} = 3B \cos 3t + \frac{72}{5} \cos 2t$	M1	
	$t = 0 \quad \dot{y} = 0 \Rightarrow 3B = -\frac{72}{5} \quad B = -\frac{24}{5}$		
	$\therefore y = -\frac{24}{5} \sin 3t + \frac{36}{5} \sin 2t$	A1	
		(5)	
(d)	$\dot{y} = -\frac{72}{5} \cos 3t + \frac{72}{5} \cos 2t$	M1A1	
	$\dot{y} = -\frac{72}{5} \cos \pi + \frac{72}{5} \cos \frac{2}{3} \pi$	M1	Substitute $t = \frac{\pi}{3}$ in derivative to find $\dot{y}$
	$\dot{y} = 7.2$	A1	Final answer
		(4)	
		[17]	



Further copies of this publication are available from  
Edexcel Publications, Adamsway, Mansfield, Notts, NG18 4FN

Telephone 01623 467467

Fax 01623 450481

Email [publication.orders@edexcel.com](mailto:publication.orders@edexcel.com)

Order Code UA036436 Summer 2013

For more information on Edexcel qualifications, please visit our website  
[www.edexcel.com](http://www.edexcel.com)

Pearson Education Limited. Registered company number 872828  
with its registered office at Edinburgh Gate, Harlow, Essex CM20 2JE

Ofqual  




Llywodraeth Cynulliad Cymru  
Welsh Assembly Government



Mark Scheme (Results)

Summer 2013

GCE Mechanics 4 (6680/01)



## **Edexcel and BTEC Qualifications**

Edexcel and BTEC qualifications come from Pearson, the world's leading learning company. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information, please visit our website at [www.edexcel.com](http://www.edexcel.com).

Our website subject pages hold useful resources, support material and live feeds from our subject advisors giving you access to a portal of information. If you have any subject specific questions about this specification that require the help of a subject specialist, you may find our Ask The Expert email service helpful.

[www.edexcel.com/contactus](http://www.edexcel.com/contactus)

### **Pearson: helping people progress, everywhere**

Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

Summer 2013

Publications Code UA036433

All the material in this publication is copyright

© Pearson Education Ltd 2013

## General Marking Guidance

- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

# EDEXCEL GCE MATHEMATICS

## General Instructions for Marking

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:
  - **M** marks: method marks are awarded for 'knowing a method and attempting to apply it', unless otherwise indicated.
  - **A** marks: accuracy marks can only be awarded if the relevant method (M) marks have been earned.
  - **B** marks are unconditional accuracy marks (independent of M marks)
  - Marks should not be subdivided.
3. Abbreviations

These are some of the traditional marking abbreviations that will appear in the mark schemes:

- bod – benefit of doubt
  - ft – follow through
  - the symbol  $\surd$  will be used for correct ft
  - cao – correct answer only
  - cso - correct solution only. There must be no errors in this part of the question to obtain this mark
  - isw – ignore subsequent working
  - awrt – answers which round to
  - SC: special case
  - oe – or equivalent (and appropriate)
  - dep – dependent
  - indep – independent
  - dp decimal places
  - sf significant figures
  - \* The answer is printed on the paper
  - $\square$  The second mark is dependent on gaining the first mark
4. All A marks are 'correct answer only' (cao.), unless shown, for example, as A1 ft to indicate that previous wrong working is to be followed through. After a misread however, the subsequent A marks affected are treated as A ft, but manifestly absurd answers should never be awarded A marks.
  5. For misreading which does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, in that part of the question affected.
  6. If a candidate makes more than one attempt at any question:
    - If all but one attempt is crossed out, mark the attempt which is NOT crossed out.
    - If either all attempts are crossed out or none are crossed out, mark all the attempts and score the highest single attempt.
  7. Ignore wrong working or incorrect statements following a correct answer.
  8. In some instances, the mark distributions (e.g. M1, B1 and A1) printed on the candidate's response may differ from the final mark scheme

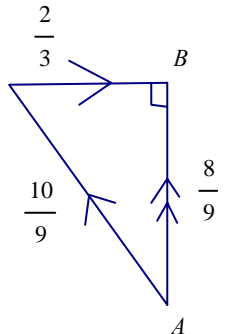
### General Rules for Marking Mechanics

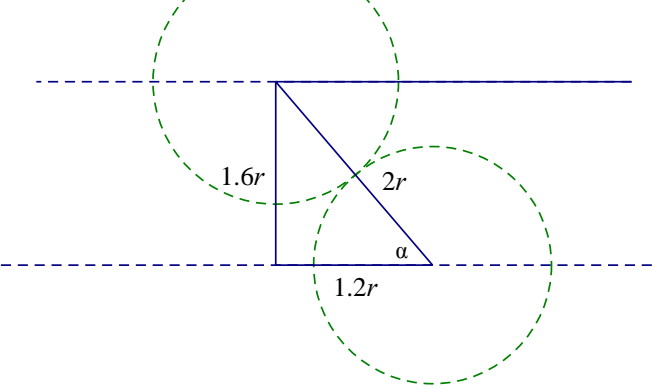
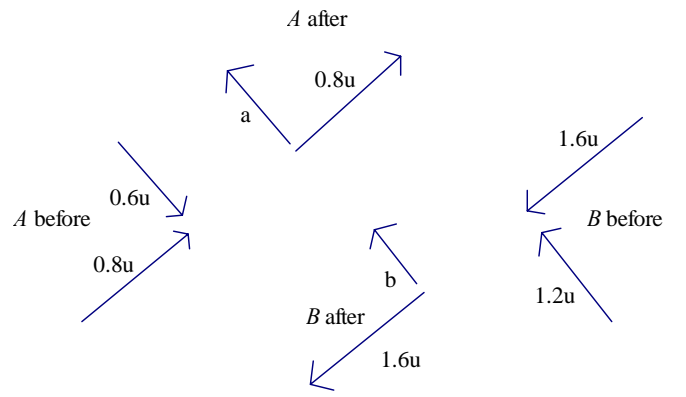
- Usual rules for M marks: correct no. of terms; dim correct; all terms that need resolving (i.e. multiplied by cos or sin) are resolved.
- Omission or extra  $g$  in a resolution is accuracy error not method error.
- Omission of mass from a resolution is method error.
- Omission of a length from a moments equation is a method error.
- Omission of units or incorrect units is not (usually) counted as an accuracy error.
- DM indicates a dependent method mark i.e. one that can only be awarded if a previous specified method mark has been awarded.
- Any numerical answer which comes from use of  $g = 9.8$  should be given to 2 or 3 SF.
- Use of  $g = 9.81$  should be penalised once per (complete) question.
- N.B. Over-accuracy or under-accuracy of correct answers should only be penalised *ONCE* per complete question.
- In all cases, if the candidate clearly labels their working under a particular part of a question i.e. (a) or (b) or (c),.....then that working can only score marks for that part of the question.
- Accept column vectors in all cases.

Misreads – if a misread does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, bearing in mind that after a misread, the subsequent A marks affected are treated as A ft.

Question Number	Scheme	Marks	
<b>1(a)</b>	Equation of motion: $\frac{1}{2}g - \frac{3}{2}v = \frac{1}{2} \frac{dv}{dt}$	M1 A1	Differential equation. All 3 terms required but condone sign errors
NB: these two marks are available in (b) if not scored in (a)			
	$\int 1 dt = \int \frac{1}{9.8 - 3v} dv$ $t + (C) = -\frac{1}{3} \ln(9.8 - 3v)$ $t = 0, v = 0 \Rightarrow C = -\frac{1}{3} \ln 9.8$ $t = -\frac{1}{3} \ln\left(\frac{9.8 - 3v}{9.8}\right)$ $3v = 9.8(1 - e^{-3t})$ <b>*Given Answer*</b>	M1 A1=A1 M1 A1 A1 (8)	Separate the variables and attempt to integrate A1 for each side. $C$ not needed Use initial conditions to evaluate $C$ or limits on a definite integral. Or equivalent <b>Watch out.</b> cwo
<b>(a) alt</b>	Equation of motion: $\frac{1}{2}g - \frac{3}{2}v = \frac{1}{2} \frac{dv}{dt}$  $e^{3t} \frac{dv}{dt} + 3e^{3t}v = ge^{3t}, \frac{d}{dt}(ve^{3t}) = ge^{3t}$ $ve^{3t} = \frac{1}{3}ge^{3t} (+c)$ $t = 0, v = 0 \Rightarrow 0 = \frac{1}{3}g + C$ $\Rightarrow ve^{3t} = \frac{1}{3}g(e^{3t} - 1), 3v = 9.8(1 - e^{-3t})$	M1 A1 M1 A1=A1 M1 A1 A1	All 3 terms required but condone sign errors  Use of integrating factor $e^{3t}$ A1 for each side. $+C$ not required. Use initial conditions to evaluate $C$  Correct equation in any equivalent form <b>Given form</b> cwo

Question Number	Scheme	Marks	
<b>1(b)</b>	$\frac{dx}{dt} = \frac{9.8}{3}(1 - e^{-3t}) \Rightarrow x = \frac{9.8}{3}\left(t + \frac{1}{3}e^{-3t}\right) + C$ $t = 0, x = 0 \Rightarrow C = -\frac{9.8}{9}$ $t = 2, x \approx 5.4 \text{ (m)}$	M1 A1  M1 A1  A1  (5) <b>(13)</b>	Integrate the given $v$ to find $x$ $C$ not needed  Use the initial conditions to evaluate $C$ or use limits correctly in a definite integral  5.45, $\frac{g}{9}(5 + e^{-6})$ or equivalent
<b>(b) alt</b>	$g - 3v = v \frac{dv}{dx}$		
	$\int 1 dx = \int \frac{v}{g - 3v} dv = \int -\frac{1}{3} + \frac{g}{3(g - 3v)} dv$	M1	Separate the variables and rearrange the RHS
	$x = -\frac{v}{3} - \frac{g}{9} \ln(g - 3v) + C$	A1	+ $C$ not needed
	$x = 0, v = 0 \Rightarrow C = \frac{g}{9} \ln g \text{ and}$ $t = 2, v = \frac{g}{3}(1 - e^{-6}) (= 3.258\dots)$	M1  A1	Use the initial conditions to find $C$ & find the value of $v$ when $t = 2$
	$x = \frac{g}{9}(1 - e^{-6}) - \frac{g}{9} \ln(e^{-6}) = 5.4$	A1	
		(5)	
		<b>(13)</b>	

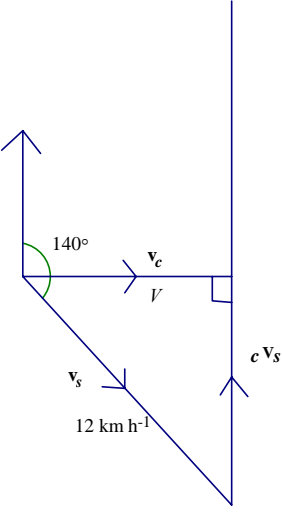
Question Number	Scheme	Marks	
2(a)	Shortest time $50 \div \frac{10}{9}, = 45$ (s)	M1,A1	
(b)	Drifts $\frac{2}{3} \times "45", = 30$ (m)	M1 A1	$\frac{2}{3} \times$ their time
(c)	 <p data-bbox="705 343 1008 454">Trig or pythag to find velocity of swimmer in direction <math>AB</math></p> <p data-bbox="705 550 795 622"><math>\frac{8}{9} \text{ms}^{-1}</math></p> <p data-bbox="403 790 672 861"><math>50 \div \frac{8}{9}, = 56.25</math> (s)</p>	M1  A1  DM1,A1  (8)	0.88 or better   Dependent on the previous M 56 or better

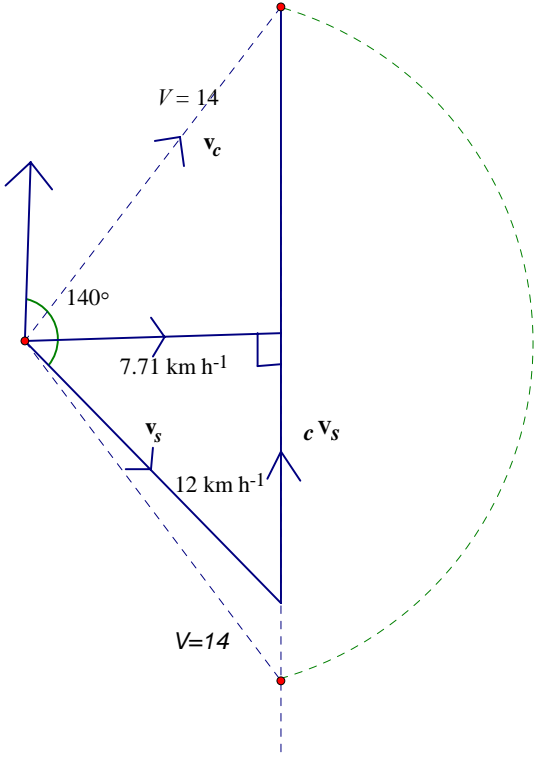
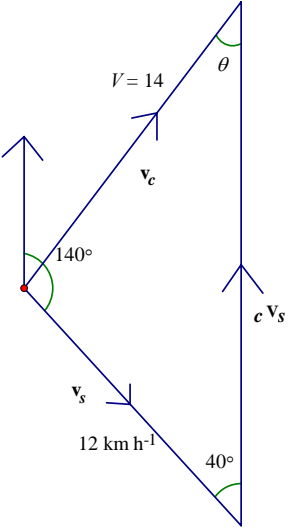
Question Number	Scheme	Marks	
3	 <p> <math>0.6u</math> or <math>u \cos \alpha</math>  <math>1.2u</math> or <math>2u \cos \alpha</math>  <math>2m \times 1.2u - 3m \times 0.6u = 3ma + 2mb</math>  <math>(3a + 2b = 0.6u)</math>  <math>e(1.2u + 0.6u) = a - b</math>  <math>(a - b = 0.3u)</math>  <math>a = 0.24u</math> or <math>b = -0.06u</math>  <math>(1.2u - (-0.06u)) \times 2m = 2.52mu</math>  or <math>(0.24u - (-0.6u)) \times 3m = 2.52mu</math> </p>	<p>B1</p> <p>B1</p> <p>M1</p> <p>A1ft</p> <p>M1</p> <p>A1ft</p> <p>DM1</p> <p>A1</p> <p>M1</p> <p>A1 (10)</p>	 <p> component of the initial velocity of <math>A</math> parallel to the line of centres on impact  component of the initial velocity of <math>B</math> parallel to the line of centres on impact  CLM parallel to the line of centres. Requires all the terms.  Correct unsimplified for their <math>0.6u</math> and <math>1.2u</math>  Restitution parallel to the line of centres. Must be used the right way round.  Correct unsimplified for their <math>0.6u</math> and <math>1.2u</math>  If signs are inconsistent between the two equations, penalise here.  Solve a pair of simultaneous eqns in <math>a</math> &amp; <math>b</math> for one of <math>a</math> &amp; <math>b</math>. Dependent on the two previous M marks.  In terms of <math>u</math> only  Find impulse on <math>A</math> or <math>B</math>. Unsimplified. For their <math>a</math> or <math>b</math>.  Correct mass for the velocities used. </p> <p><math>\frac{63}{25}</math></p>

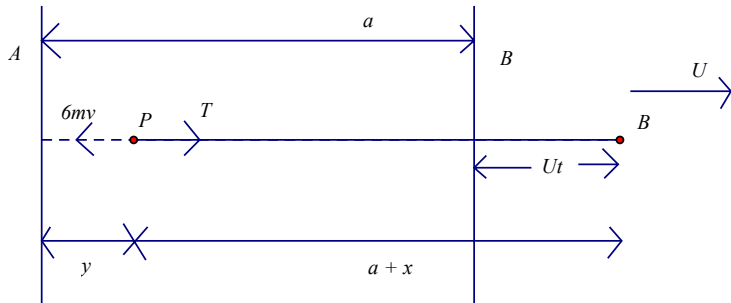


Question Number	Scheme	Marks	
4(a)	PE of ring = $-mgx$ PE of particle = $-3mg(L - \sqrt{x^2 + d^2})$ $\Rightarrow V = 3mg\sqrt{x^2 + d^2} - mgx + \text{constant. AG}$	B1 M1 A1 A1	Taking the level of the peg as zero PE  Watch out
(b)	$\frac{dV}{dx} = \frac{3mg \cdot 2x}{2\sqrt{x^2 + d^2}} - mg$ $\frac{dV}{dx} = 0 \Rightarrow 3x = \sqrt{x^2 + d^2}, 9x^2 = x^2 + d^2, 8x^2 = d^2$ $x = \frac{d}{\sqrt{8}} = \left(\frac{\sqrt{2}d}{4}\right)$	M1  M1 A1	(4)  Set $\frac{dV}{dx} = 0$ and solve for $x$ 0.354d of better
(c)	$\frac{d^2V}{dx^2} = 3mg \left( \frac{\sqrt{x^2 + d^2} \cdot 1 - x \cdot \frac{2x}{2\sqrt{x^2 + d^2}}}{x^2 + d^2} \right) =$ $3mg \left( \frac{\sqrt{9x^2} \cdot 1 - x \cdot \frac{2x}{2\sqrt{9x^2}}}{9x^2} \right) = \frac{3mgd^2}{(x^2 + d^2)^{\frac{3}{2}}} (> 0)$ Stable	M1  A1  A1ft	Product or quotient rule $\frac{d^2V}{dx^2} = \frac{3mg}{\sqrt{x^2 + d^2}} - \frac{3mgx}{2} \cdot 2x \cdot (x^2 + d^2)^{-\frac{3}{2}}$ OR $= 3mg \left( \frac{3x - \frac{x}{3}}{9x^2} \right) (> 0)$ Correct unsimplified. $\frac{16\sqrt{2}mg}{9d}, 2.5 \frac{mg}{d}, \frac{d^2V}{d\theta^2} = \frac{9mgd}{\sqrt{8}}$ Correct conclusion for their expression

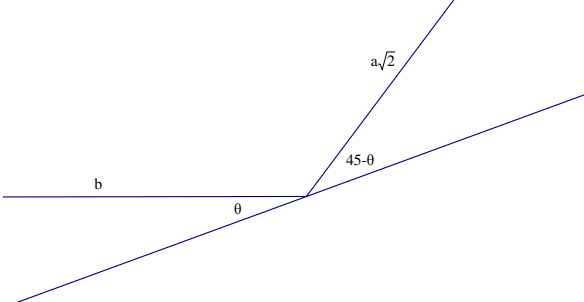
(10)

Question Number	Scheme	Marks	
5(a)	 <p data-bbox="779 220 969 292">Minimum <math>V = 12 \cos 50^\circ</math></p> <p data-bbox="779 411 869 443"><math>\approx 7.71</math></p>	<p data-bbox="1126 220 1182 252">M1</p> <p data-bbox="1126 331 1182 363">A1</p> <p data-bbox="1126 411 1182 443">A1</p>	<p data-bbox="1261 220 1953 268">Use of triangle with right angle between <math>v_c</math> and <math>c v_s</math>.</p> <p data-bbox="1261 268 1619 300">Condone sin/cos confusion.</p> <p data-bbox="1261 300 1731 339">Correct unsimplified trig expression</p> <p data-bbox="1261 411 1395 451">7.71 only</p>

Question Number	Scheme	Marks	
5(b)	 <p data-bbox="465 1002 1079 1145">Vector triangle for relative velocities when <math>V = 14</math> Select the vector triangle with the relative velocity due N.</p> $\frac{\sin \theta}{12} = \frac{\sin 40}{14}$ <p data-bbox="465 1273 645 1305">Bearing <math>033^\circ</math></p>	<p data-bbox="1131 1002 1176 1034">M1</p> <p data-bbox="1131 1082 1176 1114">A1</p> <p data-bbox="1131 1193 1198 1225">DM1</p> <p data-bbox="1131 1233 1176 1265">A1</p> <p data-bbox="1131 1273 1176 1305">A1</p> <p data-bbox="1198 1313 1243 1345">(8)</p>	 <p data-bbox="1261 1002 1944 1074">could have relative velocity due S. Could show both possibilities.</p> <p data-bbox="1261 1193 1765 1225">Use of sine rule or equivalent to find <math>\theta</math></p> <p data-bbox="1261 1273 1630 1305">Final answer. Accept <math>33.4^\circ</math></p>

Question Number	Scheme	Marks	
<p><b>6(a)</b></p>	 <p> <math>a + Ut = y + (a + x)</math>  <math>Ut = x + y</math> <b>*Answer Given*</b> </p>	<p>M1 A1</p>	<p>Diagram or clear explanation using distances Watch out for fudges.</p>
<p><b>(b)</b></p>	<p> <math>T = \frac{9ma \times x}{a} = 9mx</math>  <math>T - 6m\ddot{y} = m\ddot{y}</math>  <math>9mx - 6m(U - \dot{x}) = -m\ddot{x}</math>  <math>\ddot{x} + 6\dot{x} + 9x = 6U</math> </p>	<p>B1 M1 A2 A1</p>	<p>Equation of motion of <math>P</math>. Requires all 3 terms in terms of <math>x</math> and/or <math>y</math> Expressed in terms of <math>x</math>. -1 each error <b>Answer given.</b> Watch out for fudges</p>
<p><b>(c)</b></p>	<p> <math>t = 0, x = 0, \dot{x} = U \quad 0 = AU + \frac{2U}{3}, A = -\frac{2}{3}</math>  <math>\dot{x} = BUe^{-3t} - 3(A + Bt)Ue^{-3t}</math>  <math>U = BU - 3AU, B = 3A + 1 = -1</math> </p>	<p>M1 A1 M1 A1 A1</p>	<p>Use initial conditions to find <math>A</math> Differentiate</p>
<p><b>(d)</b></p>	<p> <math>\dot{y} = U - \dot{x} = U - (-Ue^{-3t} + 2Ue^{-3t} + 3Ute^{-3t})</math>  <math>= U(1 - e^{-3t} - 3te^{-3t})</math> </p>	<p>M1 A1</p>	<p>Or equivalent</p>
		<b>(14)</b>	

Question Number	Scheme	Marks	
7(a)	<p>State that impulse acts perpendicular to the wall and demonstrate that <math>(2\mathbf{i} + \mathbf{j}) \cdot (-\mathbf{i} + 2\mathbf{j}) = 0</math></p>	B1	Requires scalar product or gradient diagram.
(b)	<p>Impulse momentum equation:  <math>m(\mathbf{v} - \mathbf{u}) = m[(a-b)\mathbf{i} + a\mathbf{j}] = \lambda(-\mathbf{i} + 2\mathbf{j})</math>  <math>\Rightarrow a = -2(a - b), 3a = 2b</math></p> <p>OR</p> <p>Taking scalar products of velocities with <math>(2\mathbf{i} + \mathbf{j})</math>  <math>\begin{pmatrix} b \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 2b</math> and <math>\begin{pmatrix} a \\ a \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 3a</math>  No change parallel to the wall so <math>2b = 3a</math>.</p> <p>Scalar products with <math>(-\mathbf{i} + 2\mathbf{j})</math>:  <math>\begin{pmatrix} b \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 2 \end{pmatrix} = -b</math> and <math>\begin{pmatrix} a \\ a \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 2 \end{pmatrix} = a</math></p> <p>Impact equation: <math>a = eb</math>  <math display="block">e = \frac{2}{3}</math></p>	M1 A2 A1  M1 A1A1  A1  B1  M1A1 A1	Requires all terms present and of the correct structure -1 each error

Question Number	Scheme	Marks	
7(b) alt	 <p> <math>b \cos \theta = a\sqrt{2} \cos(45 - \theta)</math>  <math>b \cos \theta = a \cos \theta + a \sin \theta, \quad 2b - 2a = a</math>  <math>2b = 3a</math>            Use of <math>\tan \theta = \frac{1}{2}</math>  <math>a\sqrt{2} \sin(45 - \theta) = eb \sin \theta</math>  <math>a \cos \theta = (a + eb) \sin \theta, \quad 2a = a + eb</math>  <math>e = \frac{2}{3}</math> </p>	<p>M1 A2</p> <p>A1 B1</p> <p>M1 A1</p> <p>A1</p>	<p>Parallel to the wall. Condone trig confusion? -1 each error. Both angles in same variable?</p> <p>When seen in (b). Implied by 26.6 or 18.4</p> <p>Perpendicular to the wall. Condone consistent trig confusion? <math>e = \sqrt{\frac{10a^2}{b^2} - 4}</math></p> <p>0.67 or better</p>
(c)	<p>Fraction of KE lost = <math>\frac{b^2 - 2a^2}{b^2}</math></p> $= \frac{1 - 2 \times \frac{4}{9}}{1} = \frac{1}{9}$	<p>M1A1</p> <p>A1</p> <p>(12)</p>	

Further copies of this publication are available from  
Edexcel Publications, Adamsway, Mansfield, Notts, NG18 4FN

Telephone 01623 467467

Fax 01623 450481

Email [publication.orders@edexcel.com](mailto:publication.orders@edexcel.com)

Order Code UA036433 Summer 2013

For more information on Edexcel qualifications, please visit our website  
[www.edexcel.com](http://www.edexcel.com)

Pearson Education Limited. Registered company number 872828  
with its registered office at Edinburgh Gate, Harlow, Essex CM20 2JE

Ofqual  




Llywodraeth Cynulliad Cymru  
Welsh Assembly Government





Mark Scheme (Results)

Summer 2014

Pearson Edexcel GCE in Mechanics 4R  
(6680/01R)



## Edexcel and BTEC Qualifications

Edexcel and BTEC qualifications come from Pearson, the world's leading learning company. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information, please visit our website at [www.edexcel.com](http://www.edexcel.com).

Our website subject pages hold useful resources, support material and live feeds from our subject advisors giving you access to a portal of information. If you have any subject specific questions about this specification that require the help of a subject specialist, you may find our Ask The Expert email service helpful.

[www.edexcel.com/contactus](http://www.edexcel.com/contactus)

### **Pearson: helping people progress, everywhere**

Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

Summer 2014

Publications Code UA039506

All the material in this publication is copyright

© Pearson Education Ltd 2014

## General Marking Guidance

- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

## PEARSON EDEXCEL GCE MATHEMATICS

### General Instructions for Marking

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:

#### 'M' marks

These are marks given for a correct method or an attempt at a correct method. In Mechanics they are usually awarded for the application of some mechanical principle to produce an equation.

e.g. resolving in a particular direction, taking moments about a point, applying a suvat equation, applying the conservation of momentum principle etc.

The following criteria are usually applied to the equation.

To earn the M mark, the equation

(i) should have the correct number of terms

(ii) be dimensionally correct i.e. all the terms need to be dimensionally correct

e.g. in a moments equation, every term must be a 'force x distance' term or 'mass x distance', if we allow them to cancel 'g' s.

For a resolution, all terms that need to be resolved (multiplied by sin or cos) must be resolved to earn the M mark.

M marks are sometimes dependent (DM) on previous M marks having been earned.

e.g. when two simultaneous equations have been set up by, for example, resolving in two directions and there is then an M mark for solving the equations to find a particular quantity – this M mark is often dependent on the two previous M marks having been earned.

#### 'A' marks

These are dependent accuracy (or sometimes answer) marks and can only be awarded if the previous M mark has been earned. E.g. M0 A1 is impossible.

#### 'B' marks

These are independent accuracy marks where there is no method (e.g. often given for a comment or for a graph)

A few of the A and B marks may be f.t. – follow through – marks.

### 3. General Abbreviations

These are some of the traditional marking abbreviations that will appear in the mark schemes.

- bod – benefit of doubt
  - ft – follow through
  - the symbol  $\checkmark$  will be used for correct ft
  - cao – correct answer only
  - cso - correct solution only. There must be no errors in this part of the question to obtain this mark
  - isw – ignore subsequent working
  - awrt – answers which round to
  - SC: special case
  - oe – or equivalent (and appropriate)
  - dep – dependent
  - indep – independent
  - dp decimal places
  - sf significant figures
  - \* The answer is printed on the paper
  - The second mark is dependent on gaining the first mark
4. All A marks are 'correct answer only' (cao.), unless shown, for example, as A1 ft to indicate that previous wrong working is to be followed through. After a misread however, the subsequent A marks affected are treated as A ft, but manifestly absurd answers should never be awarded A marks.
5. If a candidate makes more than one attempt at any question:
- If all but one attempt is crossed out, mark the attempt which is NOT crossed out.
  - If either all attempts are crossed out or none are crossed out, mark all the attempts and score the highest single attempt.
6. Ignore wrong working or incorrect statements following a correct answer.

## General Principles for Mechanics Marking

*(But note that specific mark schemes may sometimes override these general principles)*

- Rules for M marks: correct no. of terms; dimensionally correct; all terms that need resolving (i.e. multiplied by cos or sin) are resolved.
- Omission or extra  $g$  in a resolution is an accuracy error not method error.
- Omission of mass from a resolution is a method error.
- Omission of a length from a moments equation is a method error.
- Omission of units or incorrect units is not (usually) counted as an accuracy error.
- DM indicates a dependent method mark i.e. one that can only be awarded if a previous specified method mark has been awarded.
- Any numerical answer which comes from use of  $g = 9.8$  should be given to 2 or 3 SF.
- Use of  $g = 9.81$  should be penalised once per (complete) question.

N.B. Over-accuracy or under-accuracy of correct answers should only be penalised *once* per complete question. However, premature approximation should be penalised every time it occurs.

- Marks must be entered in the same order as they appear on the mark scheme.
- In all cases, if the candidate clearly labels their working under a particular part of a question i.e. (a) or (b) or (c),.....then that working can only score marks for that part of the question.
- Accept column vectors in all cases.
- Misreads – if a misread does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, bearing in mind that after a misread, the subsequent A marks affected are treated as A ft
- Mechanics Abbreviations

M(A) Taking moments about A.

N2L Newton's Second Law (Equation of Motion)

NEL Newton's Experimental Law (Newton's Law of Impact)

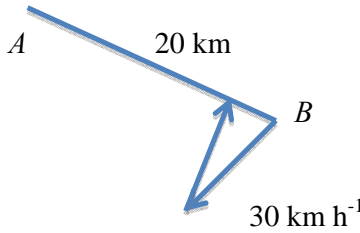
HL Hooke's Law

SHM Simple harmonic motion

PCLM Principle of conservation of linear momentum

RHS, LHS Right hand side, left hand side.

Question Number	Scheme	Marks
1.	$v \cos 45^\circ = u \sin \alpha$ $v \sin 45^\circ = eu \cos \alpha$ $e = \tan \alpha$ $I = m(v \cos 45^\circ + u \cos \alpha)$ $= mu(\sin \alpha + \cos \alpha)$ $= \frac{mu(1+e)}{\sqrt{1+e^2}}$	<p>parallel perpendicular</p> <p>or square &amp; add impulse in terms of <math>u, \alpha</math></p> <p>in terms of <math>u, e</math></p> <p>M1 A1 M1 A1 M1 A1 M1 A1 M1 A1</p> <p style="text-align: right;"><b>11</b></p>

Question Number	Scheme	Marks
2. (a)	 <p>Vector triangle with perpendicular</p> <p>Minimum speed = <math>30\sin 60^\circ</math></p> <p style="text-align: right;"><math>= 15\sqrt{3}</math> oe (26.0)</p>	M1 M1 A1 (3)
(b)	$\frac{\sin \theta}{30} = \frac{\sin 60^\circ}{32}$ $\Rightarrow \theta = 54.281\dots^\circ$ $v^2 = 32^2 + 30^2 - 2 \cdot 32 \cdot 30 \cos(120^\circ - \theta)$ $= 33.68\dots \quad (15 + \sqrt{349})$ $t = \frac{20}{33.68\dots} = 0.59379\dots \text{h} = 35.62\dots \text{min}$ <p style="text-align: center;">Time is 2.36 pm (14.36)</p>	M1 A1 A1 M1 A1 A1 M1 A1 (8) <b>11</b>

Question Number	Scheme	Marks
3.	$-(mg + mkv) = mv \frac{dv}{dx}$ $\int_0^H dx = \int_U^0 -\frac{v}{(g + kv)} dv$ $\int_0^H dx = -\int_U^0 \frac{1}{k} - \frac{g}{k(g + kv)} dv$ $- \quad H = \left[ \frac{-v}{k} + \frac{g}{k^2} \ln(g + kv) \right]_U^0$ $= \frac{U}{k} - \frac{g}{k^2} \ln\left(\frac{g + kU}{g}\right)$	<p>Differential equation M1 A1</p> <p>Separate variables M1</p> <p>Split for integration M1 A1</p> <p>A1</p> <p>Use of limits M1 A1</p> <p style="text-align: right;"><b>8</b></p>



Question Number	Scheme	Marks	
4. (a)	$mv_1 + mv_2 = mu \cos 60^\circ$ $-v_1 + v_2 = eu \cos 60^\circ$ $v_1 = \frac{u(1-e)}{4}$ <p>Speed of <math>S = \sqrt{\frac{u^2(1-e)^2}{16} + \frac{3u^2}{4}}</math> speed</p> $= \frac{u}{4} \sqrt{e^2 - 2e + 13}$ $\tan \theta = \frac{u\sqrt{3}}{2v_1} = \frac{2\sqrt{3}}{(1-e)}$ <p>dirn</p> <p><math>S</math> moves at <math>\arctan \frac{2\sqrt{3}}{(1-e)}</math> to the line of centres</p> $v_2 = \frac{u(1+e)}{4}$	<p>Momentum Impact law</p> <p>Solve for <math>v_1</math> and find</p> <p>Use components to find</p> <p><math>v_2</math> in terms of <math>u, e</math></p>	<p>M1 A1 M1 A1 M1 A1 A1 M1 A1 M1 A1 B1 (12)</p>
(b)	<p><math>T</math> has speed <math>\frac{u(1+e)}{4}</math> along the line of centres</p> <p><math>\theta</math> is a max when <math>e = 1</math> then <math>\theta = 90^\circ</math> then deflection angle is <math>90^\circ - 60^\circ = 30^\circ</math> <math>\delta = 30</math></p>	<p>Conclusion</p>	<p>M1 A1 A1 (3) <b>15</b></p>

Question Number	Scheme	Marks
<p><b>5.(a)</b></p> <p><b>(b)</b></p>	<p> <math>-12mgl \sin \theta</math>  <math>-mg(L - 4l \sin \frac{1}{2}\theta)</math>  <math>4mgl(\sin \frac{1}{2}\theta - 3 \sin \theta) + \text{constant}</math> </p> <p> <math>\frac{dV}{d\theta} = 4mgl(\frac{1}{2} \cos \frac{1}{2}\theta - 3 \cos \theta)</math>  <math>4mgl(\frac{1}{2} \cos \frac{1}{2}\theta - 3 \cos \theta) = 0</math>  <math>\frac{1}{2} \cos \frac{1}{2}\theta - 3(2 \cos^2 \frac{1}{2}\theta - 1) = 0</math>  <math>\cos \frac{1}{2}\theta = \frac{3}{4}</math> or <math>-\frac{2}{3}</math>  <math>\cos \theta = \frac{1}{8}</math> or <math>-\frac{1}{9}</math>  <math>\theta = 1.45</math> as <math>\theta &lt; \frac{1}{2}\pi</math> (83.0°)  <math>\frac{d^2V}{d\theta^2} = 4mgl(-\frac{1}{4} \sin \frac{1}{2}\theta + 3 \sin \theta)</math>            When <math>\theta = 1.45</math>, <math>\frac{d^2V}{d\theta^2} = 11.25mgl &gt; 0</math>, hence stable         </p> <p>rod particle *given answer*</p> <p>Differentiate Derivative = 0 In terms of <math>\cos \frac{1}{2}\theta</math> Solve for <math>\theta</math> Second derivative</p>	<p>B1 M1 A1 A1 (4)</p> <p>M1 A1 M1 M1 A1 M1 A1 A1 M1 A1 (10)</p> <p><b>14</b></p>

Question Number	Scheme	Marks
<b>6.(a)</b>	$-Mkv - T = M\dot{x}$ $-Mk\dot{x} - \frac{Mn^2ax}{a} = M\dot{x}$ $\ddot{x} + k\dot{x} + n^2x = 0 \quad \text{*Answer Given*}$	M1 A1 M1 A1 (4)
<b>(b)</b>	<p>Aux equn: <math>p^2 + \frac{5n}{2}p + n^2 = 0</math></p> $p = -\frac{n}{2} \text{ or } -2n$ $x = Ae^{-\frac{n}{2}t} + Be^{-2nt}$ <p>General solution</p> $t = 0, x = 0 \Rightarrow 0 = A + B$ $\dot{x} = -\frac{nA}{2}e^{-\frac{n}{2}t} - 2nBe^{-2nt}$ <p>Differentiate</p> $t = 0, x = U \Rightarrow U = -\frac{nA}{2} - 2nB$ $\Rightarrow -\frac{2U}{n} = A + 4B$ <p>Solve for A, B</p> $A = \frac{2U}{3n}; B = -\frac{2U}{3n}$ $x = \frac{2U}{3n}e^{-\frac{n}{2}t} - \frac{2U}{3n}e^{-2nt}$	M1 A1 B1 M1 A1 M1 A1 (7)
<b>(c)</b>	$\dot{x} = \frac{U}{3}(4e^{-2nt} - e^{-\frac{n}{2}t})$ $\dot{x} = 0 \Rightarrow 4e^{-2nt} - e^{-\frac{n}{2}t} = 0$ $e^{\frac{3n}{2}t} = 4$ $x = \frac{2U}{3n}(2^{-\frac{2}{3}} - 2^{-\frac{8}{3}}) = \frac{U}{n}(2^{\frac{5}{3}}) \quad \left(0.31\frac{U}{n}\right)$	M1 M1 A1 M1 A1 (5)
		<b>16</b>







Mark Scheme (Results)

Summer 2014

Pearson Edexcel GCE in Mechanics M4  
(6680/01)

## Edexcel and BTEC Qualifications

Edexcel and BTEC qualifications come from Pearson, the world's leading learning company. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information, please visit our website at [www.edexcel.com](http://www.edexcel.com).

Our website subject pages hold useful resources, support material and live feeds from our subject advisors giving you access to a portal of information. If you have any subject specific questions about this specification that require the help of a subject specialist, you may find our Ask The Expert email service helpful.

[www.edexcel.com/contactus](http://www.edexcel.com/contactus)

## **Pearson: helping people progress, everywhere**

Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

Summer 2014

Publications Code UA039503

All the material in this publication is copyright

© Pearson Education Ltd 2014

## General Marking Guidance

- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.



## PEARSON EDEXCEL GCE MATHEMATICS

### General Instructions for Marking

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:

#### 'M' marks

These are marks given for a correct method or an attempt at a correct method. In Mechanics they are usually awarded for the application of some mechanical principle to produce an equation.

e.g. resolving in a particular direction, taking moments about a point, applying a suvat equation, applying the conservation of momentum principle etc.

The following criteria are usually applied to the equation.

To earn the M mark, the equation

(i) should have the correct number of terms

(ii) be dimensionally correct i.e. all the terms need to be dimensionally correct

e.g. in a moments equation, every term must be a 'force x distance' term or 'mass x distance', if we allow them to cancel 'g' s.

For a resolution, all terms that need to be resolved (multiplied by sin or cos) must be resolved to earn the M mark.

M marks are sometimes dependent (DM) on previous M marks having been earned.

e.g. when two simultaneous equations have been set up by, for example, resolving in two directions and there is then an M mark for solving the equations to find a particular quantity – this M mark is often dependent on the two previous M marks having been earned.

#### 'A' marks

These are dependent accuracy (or sometimes answer) marks and can only be awarded if the previous M mark has been earned. E.g. M0 A1 is impossible.

#### 'B' marks

These are independent accuracy marks where there is no method (e.g. often given for a comment or for a graph)

A few of the A and B marks may be f.t. – follow through – marks.

### 3. General Abbreviations

These are some of the traditional marking abbreviations that will appear in the mark schemes.

- bod – benefit of doubt
  - ft – follow through
  - the symbol  $\surd$  will be used for correct ft
  - cao – correct answer only
  - cso - correct solution only. There must be no errors in this part of the question to obtain this mark
  - isw – ignore subsequent working
  - awrt – answers which round to
  - SC: special case
  - oe – or equivalent (and appropriate)
  - dep – dependent
  - indep – independent
  - dp decimal places
  - sf significant figures
  - \* The answer is printed on the paper
  - The second mark is dependent on gaining the first mark
4. All A marks are 'correct answer only' (cao.), unless shown, for example, as A1 ft to indicate that previous wrong working is to be followed through. After a misread however, the subsequent A marks affected are treated as A ft, but manifestly absurd answers should never be awarded A marks.
5. If a candidate makes more than one attempt at any question:
- If all but one attempt is crossed out, mark the attempt which is NOT crossed out.
  - If either all attempts are crossed out or none are crossed out, mark all the attempts and score the highest single attempt.
6. Ignore wrong working or incorrect statements following a correct answer.

## General Principles for Mechanics Marking

*(But note that specific mark schemes may sometimes override these general principles)*

- Rules for M marks: correct no. of terms; dimensionally correct; all terms that need resolving (i.e. multiplied by cos or sin) are resolved.
- Omission or extra  $g$  in a resolution is an accuracy error not method error.
- Omission of mass from a resolution is a method error.
- Omission of a length from a moments equation is a method error.
- Omission of units or incorrect units is not (usually) counted as an accuracy error.
- DM indicates a dependent method mark i.e. one that can only be awarded if a previous specified method mark has been awarded.
- Any numerical answer which comes from use of  $g = 9.8$  should be given to 2 or 3 SF.
- Use of  $g = 9.81$  should be penalised once per (complete) question.

N.B. Over-accuracy or under-accuracy of correct answers should only be penalised *once* per complete question. However, premature approximation should be penalised every time it occurs.

- Marks must be entered in the same order as they appear on the mark scheme.
- In all cases, if the candidate clearly labels their working under a particular part of a question i.e. (a) or (b) or (c),.....then that working can only score marks for that part of the question.
- Accept column vectors in all cases.
- Misreads – if a misread does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, bearing in mind that after a misread, the subsequent A marks affected are treated as A ft
- Mechanics Abbreviations

M(A) Taking moments about A.

N2L Newton's Second Law (Equation of Motion)

NEL Newton's Experimental Law (Newton's Law of Impact)

HL Hooke's Law

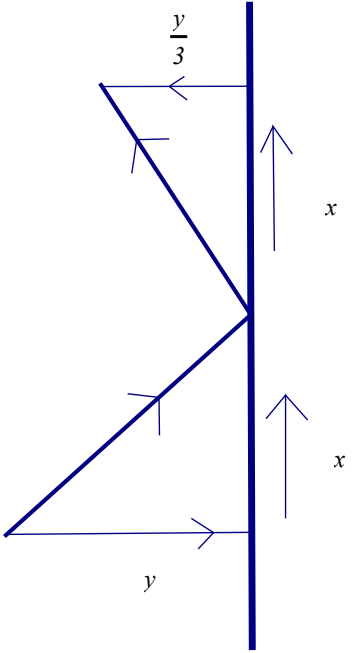
SHM Simple harmonic motion

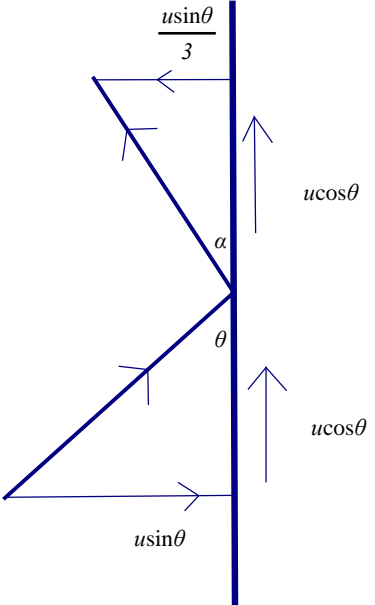
PCLM Principle of conservation of linear momentum

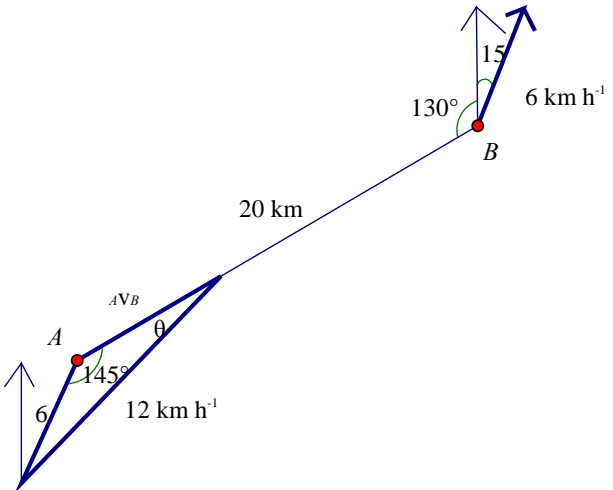
RHS, LHS Right hand side, left hand side.

Question Number	Scheme	Marks	Notes
<b>1a</b>	$\mathbf{r}_A = (-6\mathbf{i} + 4\mathbf{j} - 3\mathbf{k}) + t(3\mathbf{i} + \mathbf{j}) = ((-6 + 3t)\mathbf{i} + (4 + t)\mathbf{j} + (-3)\mathbf{k})$ $\mathbf{r}_B = (-2\mathbf{i} + 2\mathbf{j} + 3\mathbf{k}) + t(\mathbf{i} - \mathbf{k}) = ((-2 + t)\mathbf{i} + (2)\mathbf{j} + (3 - t)\mathbf{k})$ ${}_B\mathbf{r}_A = (-2 + t + 6 - 3t)\mathbf{i} + (2 - 4 - t)\mathbf{j} + (3 - t + 3)\mathbf{k}$ $= (4 - 2t)\mathbf{i} + (-2 - t)\mathbf{j} + (6 - t)\mathbf{k}$ $ {}_B\mathbf{r}_A ^2 = (4 - 2t)^2 + (t + 2)^2 + (6 - t)^2$	M1 A1 M1 M1	Position vector for $A$ or $B$ Both position vectors correct (seen or implied) Position of $B$ relative to $A$ (or $A$ relative to $B$ ) Use of Pythagoras
<b>alt1</b>	$= 6t^2 - 24t + 56 = 6(t - 2)^2 + 32$	M1	Complete the square
	Minimum distance = $\sqrt{32} = 4\sqrt{2}$ m **	A1	Reach <b>given answer</b> correctly
		[6]	
<b>alt2</b>	$ {}_B\mathbf{r}_A ^2 = (4 - 2t)^2 + (t + 2)^2 + (6 - t)^2 (= 6t^2 - 24t + 56)$ $12t - 24 = 0 \Rightarrow t = 2$	M1 M1	Use of Pythagoras Differentiate and solve for $t$
	Minimum distance = $\sqrt{32} = 4\sqrt{2}$ m **	A1	Reach <b>given answer</b> correctly
<b>alt3</b>	$\begin{pmatrix} 4 - 2t \\ -2 - t \\ 6 - t \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = 0 \Rightarrow 8 - 4t - 2 - t + 6 - t = 12 - 6t = 0$	M1	Scalar product of position vector with relative velocity = zero and form equation in $t$
	Distance = $\sqrt{0^2 + 4^2 + 4^2} = \sqrt{32} = 4\sqrt{2}$	M1 A1	Use of Pythagoras Reach <b>given answer</b> correctly
<b>1b</b>	When $t = 2$ , $\mathbf{r}_A = 6\mathbf{j} - 3\mathbf{k}$	B1 B1 [2]	Seen or implied cso

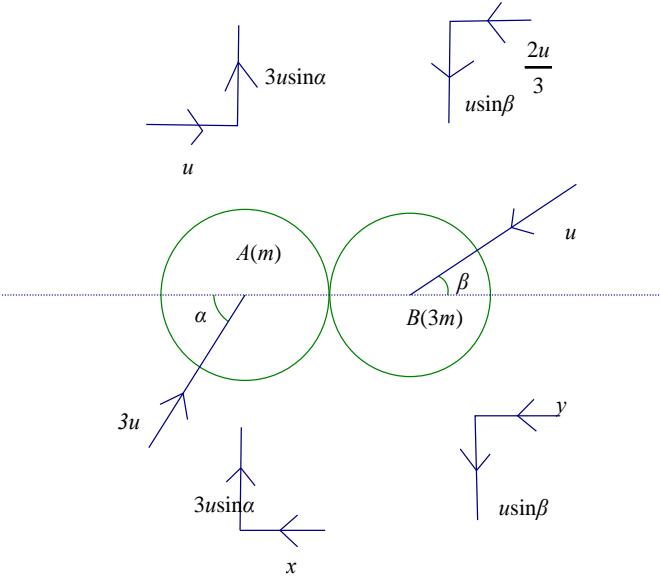
Question Number	Scheme	Marks	Notes
2a	$\frac{P}{v} - 10v = ma; \frac{25000}{v} - 10v = 1000a$	M1	Equation of motion
	$v = 20, (\text{m s}^{-2}) \quad a = \frac{\frac{25000}{20} - 10 \times 20}{1000} = \frac{25 - 2}{10} = 1.05 (\text{m s}^{-2}) **$	DM1 A1 [3]	Substitute $v = 20$ Obtain <b>given answer</b> correctly
2b	$v \frac{dv}{dx} = \frac{25000}{1000} - 10v = \frac{25000 - 10v^2}{1000v} = \frac{2500 - v^2}{100v}$	M1	Differential equation in $v$ and $x$
	$\int \frac{100v^2}{2500 - v^2} dv = \int 1 dx \quad \left( = 100 \int -1 + \frac{2500}{2500 - v^2} dv \right)$	A1	Any equivalent form
alt1	$= 100 \int -1 + \frac{25}{50 - v} + \frac{25}{50 + v} dv$	M1	Separate the variables
	$x(+C) = 100 \left\{ -v + 25 \ln \left  \frac{50 + v}{50 - v} \right  \right\}$	DM1 A1	Split using partial fractions Or equivalent
alt2	$x = 100 \left( -20 + 25 \ln \frac{70}{30} \right) - 100 \left( -10 + 25 \ln \frac{60}{40} \right) = 105 (\text{m})$	A1 [8]	Integration correct Correct use of limits Or better $\left( 2500 \ln \left( \frac{14}{9} \right) - 1000 \right)$
	$= 100 \left( v - 50 \operatorname{arc} \tanh \left( \frac{v}{50} \right) \right)$	DM1 A1	Use of arctanh correct
	$x(+C) = 100 \left\{ -v + 25 \ln \left  \frac{50 + v}{50 - v} \right  \right\}$	A1	Convert to log form
	$x = 100 \left( -20 + 25 \ln \frac{70}{30} \right) - 100 \left( -10 + 25 \ln \frac{60}{40} \right) = 105 (\text{m})$	DM1 A1	Correct use of limits Or better $\left( 2500 \ln \left( \frac{14}{9} \right) - 1000 \right)$
	NB A correct numerical answer that does not follow from integration scores no marks.		

Question Number	Scheme	Marks	Notes
<p><b>3</b> <b>alt1</b></p>	 <p>Speed perpendicular to wall after collision = <math>\frac{y}{3}</math></p> <p>Speed parallel to the wall is unchanged</p> $\frac{1}{2}(x^2 + y^2) = x^2 + \frac{1}{9}y^2$ $9(x^2 + y^2) = 2(9x^2 + y^2), \quad 9x^2 = 7y^2, \quad x = \frac{\sqrt{7}}{3}y$ <p>direction deflected by <math>\tan^{-1} \frac{y}{x} + \tan^{-1} \frac{y}{3x}</math></p> $= \tan^{-1} \sqrt{\frac{27}{5}} + \tan^{-1} \sqrt{\frac{3}{5}} = 104.5^\circ \quad (104)$	<p>B1</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>[8]</p>	<p>Use the speeds to form an equation in <math>x</math> &amp; <math>y</math> (or equivalent)</p> <p>Correct unsimplified</p> <p>Correct ratio for <math>x</math> &amp; <math>y</math> (any equivalent form)</p> <p>To find the correct angle</p> <p>Correct in <math>x</math> &amp; <math>y</math></p>

Question Number	Scheme	Marks	Notes
alt2	 <p data-bbox="401 836 1039 901">Speed perpendicular to wall after collision = <math>\frac{u \sin \theta}{3}</math></p> <p data-bbox="401 909 871 950">Speed parallel to the wall is unchanged</p> $\frac{u^2}{4} = \frac{u^2}{9} \sin^2 \theta + u^2 \cos^2 \theta$ $27 \cos^2 \theta = 5 \sin^2 \theta, \quad \tan^2 \theta = \frac{27}{5}$ <p data-bbox="401 1144 1113 1291">deflected by <math>\theta + \alpha</math>, <math>\tan(\theta + \alpha) = \frac{\tan \theta + \frac{1}{3} \tan \theta}{1 - \frac{1}{3} \tan^2 \theta} (= -\sqrt{15})</math></p> $\theta + \alpha = 104.5^\circ \quad (104)$	<p data-bbox="1178 852 1228 885">B1</p> <p data-bbox="1178 909 1228 941">B1</p> <p data-bbox="1178 966 1228 998">M1</p> <p data-bbox="1178 1023 1228 1055">A1</p> <p data-bbox="1178 1079 1228 1112">A1</p> <p data-bbox="1178 1136 1228 1169">M1</p> <p data-bbox="1178 1193 1228 1226">A1</p> <p data-bbox="1178 1250 1228 1282">A1</p> <p data-bbox="1228 1323 1270 1356">[8]</p>	<p data-bbox="1287 941 1816 1015">Use the speeds to form an equation in <math>u</math> &amp; <math>\theta</math> (or equivalent)</p> <p data-bbox="1287 1015 1543 1047">Correct unsimplified</p> <p data-bbox="1287 1063 1753 1096">Correct trig ratio for <math>\theta</math> (or equivalent)</p> <p data-bbox="1287 1136 1585 1169">To find the correct angle</p> <p data-bbox="1287 1226 1627 1258">Correct in <math>\theta</math> (or equivalent)</p>

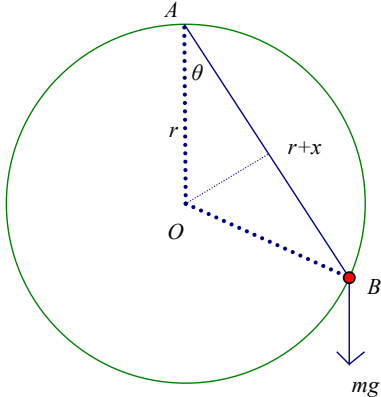
Question Number	Scheme	Marks	Notes
<p><b>4a</b></p>	 <p>Relative velocity triangle</p> $\frac{\sin 145}{12} = \frac{\sin \theta}{6}, \theta = 16.7^\circ$ $\text{Bearing} = 15 + (180 - 145 - 16.7) = 33.3^\circ$ <p>Bearing 033°</p>	<p>M1</p> <p>M1</p> <p>M1</p> <p>A1</p> <p>[4]</p>	<p>Seen or implied</p> <p>Use of trig to find a relevant angle</p> <p>To find the required angle</p> <p>They were asked for an answer "to the nearest degree". Accept N 33° E</p>
<p><b>4b</b></p>	$\frac{{}_A v_B}{\sin 18.3} = \frac{12}{\sin 145}$ ${}_A v_B = 6.58 (\text{km h}^{-1})$ $\text{Time taken} = \frac{20}{6.58} \text{ (hrs)}$ <p>Time is 3:02 pm (1502)</p>	<p>M1</p> <p>A1</p> <p>M1</p> <p>A1</p> <p>[4]</p>	<p>Correct method to find the relative velocity</p> <p>For their 6.58</p>



Question Number	Scheme	Marks	Notes
5a	<p data-bbox="394 310 457 334"><i>Before</i></p>  <p data-bbox="422 716 474 740"><i>After</i></p> <p data-bbox="373 850 1140 886">CLM: <math>mx + 3my = 3m \times u \cos \beta - m \times 3u \cos \alpha = mu \quad (x + 3y = u)</math></p> <p data-bbox="373 943 1056 1019">NEL: <math>x - y = \frac{1}{5}(3u \cos \alpha + u \cos \beta) \left( = \frac{1}{5} \left( u + \frac{2}{3}u \right) = \frac{1}{3}u \right)</math></p> <p data-bbox="380 1073 579 1133"><math>x = \frac{u}{2}</math>, or <math>y = \frac{u}{6}</math></p> <p data-bbox="373 1179 1052 1252">Magnitude of the impulse on A = <math>mu - \left( m \times -\frac{u}{2} \right) = \frac{3mu}{2}</math></p>	<p data-bbox="1199 841 1241 865">M1</p> <p data-bbox="1199 894 1241 919">A1</p> <p data-bbox="1199 943 1241 967">M1</p> <p data-bbox="1199 1005 1241 1029">A1</p> <p data-bbox="1199 1065 1262 1089">DM1</p> <p data-bbox="1199 1127 1241 1151">A1</p> <p data-bbox="1199 1170 1241 1195">M1</p> <p data-bbox="1199 1214 1241 1239">A1</p> <p data-bbox="1262 1247 1297 1271">[8]</p>	<p data-bbox="1325 821 1850 881">Terms of correct structure but condone sign errors</p> <p data-bbox="1325 927 1818 987">equation of correct structure but condone sign errors</p> <p data-bbox="1325 1049 1818 1109">Dependent on the two previous M marks. Solve for x or y</p> <p data-bbox="1325 1162 1591 1187">Correct for their x or y</p> <p data-bbox="1325 1211 1524 1235">Must be positive</p>

Question Number	Scheme	Marks	Notes
5b	<p>Component of velocity perpendicular to the line of centres before            = component after = <math>3u \sin \alpha = 3u \times \frac{\sqrt{8}}{3} = \sqrt{8}u</math></p> <p>KE lost = <math>\frac{m}{2} \left( 9u^2 - \left( 8u^2 + \frac{1}{4}u^2 \right) \right) \left[ = \frac{3}{8}mu^2 \right]</math></p> <p>Fraction lost = <math>\frac{\frac{3}{8}}{\frac{9}{2}} = \frac{3}{8} \times \frac{2}{9} = \frac{1}{12}</math></p>	<p>B1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>[4]</p>	<p>Change in KE.            Does not need to be a fraction at this stage.            Does not need to include the (cancelling) component perpendicular to the line of centre.            Correct unsimplified</p>

Question Number	Scheme	Marks	Notes
<b>6a</b>	$m\ddot{x} = 4mv - \frac{5ma \times x}{a}$ $v = -\dot{x}$	M1	Equation of motion as far as $m\ddot{x} = \pm 4mv - T$
	$\ddot{x} + 4\dot{x} + 5x = 0$ **	M1 A1	Use of $v = -\dot{x}$
<b>6b</b>	AE $m^2 + 4m + 5 = 0$ , $m = \frac{-4 \pm \sqrt{4^2 - 4 \times 5}}{2} = -2 \pm i$	A1	Reach <b>given answer</b> correctly.
	$x = e^{-2t}(A \cos t + B \sin t)$	[3]	
	$t = 0, x = a = A$	M1	Solve AE to find GS
	$\dot{x} = -2e^{-2t}(a \cos t + B \sin t) + e^{-2t}(-a \sin t + B \cos t)$	A1	Use $t = 0, x = a$ to find A
<b>6c</b>	$t = 0, \dot{x} = 0 = -2a + B$ $x = e^{-2t}(a \cos t + 2a \sin t)$	M1	Differentiate and use boundary conditions to find B
	String goes slack when $x = e^{-2t}(a \cos t + 2a \sin t) = 0$	A1	
	$\cos t = -2 \sin t, \tan t = -\frac{1}{2}$	M1	Set $x = 0$ and solve for $t$ or $\tan t$
	$\dot{x} = -2e^{-2t}(a \cos t + 2a \sin t) + e^{-2t}(-a \sin t + 2a \cos t)$	A1	
	$= e^{-2t}(-5a \sin t) = -0.01 \dots a$ Speed = $0.011a$ ( $\text{ms}^{-1}$ )	M1	Substitute a positive value of $t$ to find the speed. An answer of 0.88... indicates a negative $t$ .
		A1	The question specifies 2 sf
	[4]		

Question Number	Scheme	Marks	Notes
7a	 <p>Measuring GPE from A, GPE = <math>-mg \cos \theta (r+x)</math></p> $\text{EPE} = \frac{kmgx^2}{2r}$ <p>From the isosceles triangle, <math>\cos \theta = \frac{x+r}{2r}</math></p> $V = -mg \cos \theta (r+x) + \frac{kmgx^2}{2r}$ $= -mg \cos \theta \times 2r \cos \theta + \frac{kmg r^2 (2 \cos \theta - 1)^2}{2r}$ $= mgr \left\{ -2 \cos^2 \theta + 2k \cos^2 \theta - 2k \cos \theta + \frac{k}{2} \right\}$ $= 2mgr \left\{ (k-1) \cos^2 \theta - k \cos \theta \right\} + \text{constant} \quad **$	<p>B1</p> <p>B1</p> <p>B1</p> <p>M1</p> <p>A1</p> <p>A1</p> <p>(6)</p>	<p>Or <math>-2mgr \cos^2 \theta</math> , or <math>-mgr(1 + \cos 2\theta)</math> or equivalent</p> <p>Correct unsimplified total</p> <p>In terms of <math>r</math> &amp; <math>\theta</math></p> <p>Reach <b>given answer</b> correctly</p>

Question Number	Scheme	Marks	Notes
<b>7b</b>	$V = 2mgr(2\cos^2\theta - 3\cos\theta) + \text{constant}$ $V' = 2mgr(-4\cos\theta\sin\theta + 3\sin\theta)$ $V' = 0 \Rightarrow \sin\theta = 0 \text{ or } \cos\theta = \frac{3}{4}$ $\theta = 0 \text{ or } \theta = \pm 0.72 \text{ rads}$ $V'' = 2mgr(-4\cos 2\theta + 3\cos\theta)$ $\theta = 0, V'' = -2mgr < 0, \text{ unstable equilibrium}$ $\cos\theta = \frac{3}{4}, V'' = \frac{7mgr}{2} > 0, \text{ stable equilibrium}$	M1 A1 M1 A3 M1 A1 A1 (9)	Differentiate $V$ Derivative = 0 and solve for $\theta$ -1 for each missing solution Second derivative of $V$ Need to see $-2mgr$ or equivalent Do not need to consider the symmetrical position as well





# Mark Scheme (Results)

Summer 2015

Pearson Edexcel GCE in Mechanics 4  
(6680/01)

## **Edexcel and BTEC Qualifications**

Edexcel and BTEC qualifications are awarded by Pearson, the UK's largest awarding body. We provide a wide range of qualifications including academic, vocational, occupational and specific programmes for employers. For further information visit our qualifications websites at [www.edexcel.com](http://www.edexcel.com) or [www.btec.co.uk](http://www.btec.co.uk). Alternatively, you can get in touch with us using the details on our contact us page at [www.edexcel.com/contactus](http://www.edexcel.com/contactus).

## **Pearson: helping people progress, everywhere**

Pearson aspires to be the world's leading learning company. Our aim is to help everyone progress in their lives through education. We believe in every kind of learning, for all kinds of people, wherever they are in the world. We've been involved in education for over 150 years, and by working across 70 countries, in 100 languages, we have built an international reputation for our commitment to high standards and raising achievement through innovation in education. Find out more about how we can help you and your students at: [www.pearson.com/uk](http://www.pearson.com/uk)

Summer 2015

Publications Code UA042157

All the material in this publication is copyright

© Pearson Education Ltd 2015





## General Marking Guidance

- All candidates must receive the same treatment. Examiners must mark the first candidate in exactly the same way as they mark the last.
- Mark schemes should be applied positively. Candidates must be rewarded for what they have shown they can do rather than penalised for omissions.
- Examiners should mark according to the mark scheme not according to their perception of where the grade boundaries may lie.
- There is no ceiling on achievement. All marks on the mark scheme should be used appropriately.
- All the marks on the mark scheme are designed to be awarded. Examiners should always award full marks if deserved, i.e. if the answer matches the mark scheme. Examiners should also be prepared to award zero marks if the candidate's response is not worthy of credit according to the mark scheme.
- Where some judgement is required, mark schemes will provide the principles by which marks will be awarded and exemplification may be limited.
- Crossed out work should be marked UNLESS the candidate has replaced it with an alternative response.

**PEARSON EDEXCEL GCE MATHEMATICS****General Instructions for Marking**

1. The total number of marks for the paper is 75.
2. The Edexcel Mathematics mark schemes use the following types of marks:

'M' marks

These are marks given for a correct method or an attempt at a correct method. In Mechanics they are usually awarded for the application of some mechanical principle to produce an equation.

e.g. resolving in a particular direction, taking moments about a point, applying a suvat equation, applying the conservation of momentum principle etc.

The following criteria are usually applied to the equation.

To earn the M mark, the equation

(i) should have the correct number of terms

(ii) be dimensionally correct i.e. all the terms need to be dimensionally correct

e.g. in a moments equation, every term must be a 'force x distance' term or 'mass x distance', if we allow them to cancel 'g' s.

For a resolution, all terms that need to be resolved (multiplied by sin or cos) must be resolved to earn the M mark.

M marks are sometimes dependent (DM) on previous M marks having been earned.

e.g. when two simultaneous equations have been set up by, for example, resolving in two directions and there is then an M mark for solving the equations to find a particular quantity – this M mark is often dependent on the two previous M marks having been earned.

'A' marks

These are dependent accuracy (or sometimes answer) marks and can only be awarded if the previous M mark has been earned. E.g. M0 A1 is impossible.

'B' marks

These are independent accuracy marks where there is no method (e.g. often given for a comment or for a graph)

A few of the A and B marks may be f.t. – follow through – marks.

### 3. General Abbreviations

These are some of the traditional marking abbreviations that will appear in the mark schemes.

- bod – benefit of doubt
  - ft – follow through
  - the symbol  $\checkmark$  will be used for correct ft
  - cao – correct answer only
  - cso - correct solution only. There must be no errors in this part of the question to obtain this mark
  - isw – ignore subsequent working
  - awrt – answers which round to
  - SC: special case
  - oe – or equivalent (and appropriate)
  - dep – dependent
  - indep – independent
  - dp decimal places
  - sf significant figures
  - \* The answer is printed on the paper
  - The second mark is dependent on gaining the first mark
4. All A marks are 'correct answer only' (cao.), unless shown, for example, as A1 ft to indicate that previous wrong working is to be followed through. After a misread however, the subsequent A marks affected are treated as A ft, but manifestly absurd answers should never be awarded A marks.
5. For misreading which does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, in that part of the question affected.
6. If a candidate makes more than one attempt at any question:
- If all but one attempt is crossed out, mark the attempt which is NOT crossed out.
  - If either all attempts are crossed out or none are crossed out, mark all the attempts and score the highest single attempt.
7. Ignore wrong working or incorrect statements following a correct answer.

### General Principles for Mechanics Marking

*(But note that specific mark schemes may sometimes override these general principles)*

- Rules for M marks: correct no. of terms; dimensionally correct; all terms that need resolving (i.e. multiplied by cos or sin) are resolved.
- Omission or extra g in a resolution is an accuracy error not method error.
- Omission of mass from a resolution is a method error.
- Omission of a length from a moments equation is a method error.
- Omission of units or incorrect units is not (usually) counted as an accuracy error.
- DM indicates a dependent method mark i.e. one that can only be awarded if a previous specified method mark has been awarded.
- Any numerical answer which comes from use of  $g = 9.8$  should be given to 2 or 3 SF.
- Use of  $g = 9.81$  should be penalised once per (complete) question.

N.B. Over-accuracy or under-accuracy of correct answers should only be penalised *once* per complete question. However, premature approximation should be penalised every time it occurs.

- Marks must be entered in the same order as they appear on the mark scheme.
- In all cases, if the candidate clearly labels their working under a particular part of a question i.e. (a) or (b) or (c),.....then that working can only score marks for that part of the question.
- Accept column vectors in all cases.
- Misreads – if a misread does not alter the character of a question or materially simplify it, deduct two from any A or B marks gained, bearing in mind that after a misread, the subsequent A marks affected are treated as A ft
- Mechanics Abbreviations

M(A) Taking moments about A.

N2L Newton's Second Law (Equation of Motion)

NEL Newton's Experimental Law (Newton's Law of Impact)

HL Hooke's Law

SHM Simple harmonic motion

PCLM Principle of conservation of linear momentum

RHS, LHS Right hand side, left hand side.



**June 2015**  
**6680 Mechanics 4**  
**Mark Scheme**

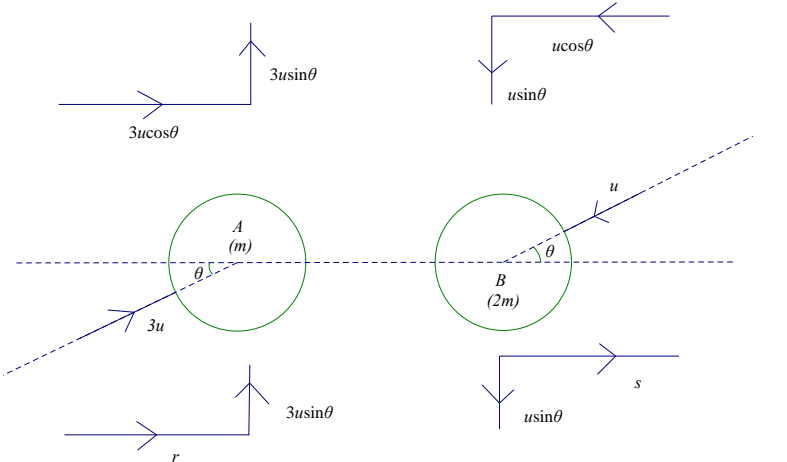
Question Number	Scheme	Marks	Notes
1	$\mathbf{r}_P - \mathbf{r}_Q$	M1	Find position vector of one particle relative to the other . $\mathbf{r}_P = \begin{pmatrix} 16+t \\ -12+2t \end{pmatrix}$ , $\mathbf{r}_Q = \begin{pmatrix} -5+2t \\ 4+t \end{pmatrix}$
	$= \begin{pmatrix} 21-t \\ -16+t \end{pmatrix}$	A1	Accept +/-
	$d^2 = (21-t)^2 + (-16+t)^2$		Pythagoras
	$\frac{d}{dt}d^2 = -2(21-t) + 2(-16+t) (= -74 + 4t)$	M1	Differentiate $d$ or $d^2$ wrt $t$
		M1	Set derivative = 0 and solve for $t$
	Min when $t = 18.5(\text{s})$	A1	
	Relative position $\begin{pmatrix} 2.5 \\ 2.5 \end{pmatrix}$ , distance $\sqrt{2.5^2 + 2.5^2}$ (m)	M1	Substitute their $t$ to find $d$
	$= \sqrt{\frac{25}{2}} = 3.54$ (m)	A1	
		[7]	
	See over for alternatives.		

Question Number	Scheme	Marks	Notes
<b>alt1</b>	$\mathbf{r}_P - \mathbf{r}_Q$	M1	Position of $P$ relative to $Q$
	$= \begin{pmatrix} 21-t \\ -16+t \end{pmatrix}$	A1	Accept +/-
	$d^2 = (21-t)^2 + (-16+t)^2 (= 2t^2 - 74t + 697)$	M1	Use Pythagoras to express $d^2$ as a quadratic in $t$
		M1	Complete the square
	$2(t-18.5)^2 - 684.5 + 697$	A1	
	Min $d^2 = 697 - 684.5$	M1	Use completed square to find minimum value for their expression
	Min. $d = \sqrt{697 - 684.5} = \sqrt{12.5}$	A1	
<b>alt2</b>	$\mathbf{r}_P - \mathbf{r}_Q$	M1	Position of $P$ relative to $Q$
	$= \begin{pmatrix} 21-t \\ -16+t \end{pmatrix}$	A1	Accept +/-
	Relative velocity $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$	M1	
	$: \begin{pmatrix} 21-t \\ -16+t \end{pmatrix} \cdot \begin{pmatrix} -1 \\ 1 \end{pmatrix} = -(21-t) + (-16+t) = 0,$	M1	Set scalar product of relative position and relative velocity = 0 and solve for $t$ .
	$t = 18.5 \text{ (s)}$	A1	
	Relative position $\begin{pmatrix} 2.5 \\ 2.5 \end{pmatrix}$ , distance $\sqrt{2.5^2 + 2.5^2}$ (m)	M1	Substitute their $t$ to find $d$
	$= \sqrt{\frac{25}{2}} = 3.54 \text{ (m)}$	A1	
	See over for alternative		



Question Number	Scheme	Marks	Notes
<b>alt 3</b>	$\mathbf{r}_P - \mathbf{r}_Q$	M1	Initial position of $P$ relative to $Q$
	$= \begin{pmatrix} 21 \\ -16 \end{pmatrix}$	A1	Accept +/-
	Relative velocity $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$	M1	
		M1	Use scalar product to find $\cos \theta$
	$\cos \theta = \frac{-37}{\sqrt{2}\sqrt{687}} \quad (-0.998\dots)$	A1	Accept +/-
	$d = PQ \sin \theta$	M1	Use trig to find distance
	$= \sqrt{697} \times \sqrt{1 - \frac{37^2}{2 \times 697}} = \frac{5}{\sqrt{2}} \approx 3.54$	A1	
		[7]	

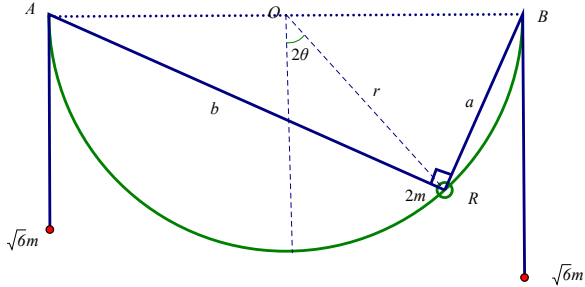
Question Number	Scheme	Marks	Notes
2		B1	Either triangle of velocities
		M1	Two triangles combined using their common velocity
		A1	Correct diagram seen or implied
	Correct method to obtain one of $v, w, \theta$	M1	$(v = 16, w = 16.5, \theta = 76^\circ)$ <b>Make it dependent?</b>
	speed is $16.5 \text{ (km h}^{-1}\text{)}$	A1	$4\sqrt{17}$
	Direction $S 76^\circ E$ or equivalent	A1	$104^\circ$
		[6]	
<b>Alt</b>	Velocity of wind = $w$		
	$w = -vi + 4j$	B1	one correct equation
	$w = ai + bj - 8j \quad a^2 + b^2 = 400$	M1	2 <sup>nd</sup> equation and compare coefficients
	coeff <b>j</b> : $4 = b - 8 \quad b = 12$	A1	2 correct eqns
	<b>i</b> : $-v = a$		
	$a^2 + 144 = 400 \Rightarrow a = -16 \quad (v > 0)$	M1	
	$ w  = \sqrt{4^2 + 16^2} = 4\sqrt{17}$	A1	
	Bearing $104^\circ$	A1	

Question Number	Scheme	Marks	Notes
3			
	After collision $u \sin \theta$ and $3u \sin \theta$ perpendicular to $l$ of $c$	B1	
	CLM : $r + 2s = 3u \cos \theta - 2u \cos \theta (= u \cos \theta)$	M1	Requires all four terms but condone sign errors.
		A1	Correct unsimplified equation
	Impact: $s - r = e \times 4u \cos \theta \left( = \frac{u \cos \theta}{2} \right)$	M1	Must be the right way round, but condone sign errors
		A1	Correct unsimplified equation
	$\Rightarrow r = 0, s = \frac{u \cos \theta}{2}$	DM1	Solve the simultaneous equations to find the horizontal components of velocities. Dependent on the two preceding M marks
		A1	Both correct
	After the collision: $(3u \sin \theta)^2 + r^2 = 4((u \sin \theta)^2 + s^2)$	M1	Use $v_A = 2v_B$ . <b>Condone 2 on the wrong side?</b>
		A1	Correct unsimplified equation (their $r$ and $s$ )
	$9u^2 \sin^2 \theta = 4u^2 \sin^2 \theta + 4 \cdot \frac{u^2}{4} \cos^2 \theta$	A1	Obtain an equation in $\theta$
	$\tan^2 \theta = \frac{1}{5}, \quad \theta = 24.1(^{\circ}) \quad (0.421 \text{ radians})$	DM1	Solve for $\theta$ . Dependent on the previous M1
		A1	Correct to 3 sf or better

Question Number	Scheme	Marks	Notes
<b>3 alt</b>	For those who prefer everything with trig:		
	$v_A \sin \alpha = 3u \sin \theta$ , $v_B \sin \beta = u \sin \theta$	B1	Perpendicular to the l.o.c.
	$m.3u \cos \theta - 2m.u \cos \theta = mv_A \cos \alpha + 2mv_B \cos \beta$	M1	CLM
	$(u \cos \theta = v_A \cos \alpha + 2v_B \cos \beta)$	A1	
	$\frac{1}{8} \times (3u \cos \theta + u \cos \theta) = v_B \cos \beta - v_A \cos \alpha$	M1	Impact law
	$\left( \frac{u}{2} \cos \theta = v_B \cos \beta - v_A \cos \alpha \right)$	A 1	
	$\frac{u}{2} \cos \theta = v_B \cos \beta$ , $0 = v_A \cos \alpha (\Rightarrow \sin \alpha = 1)$	DM1	Simultaneous equations
		A1	
	$v_A \sin \alpha = v_A = 2v_B = 3u \sin \theta$	M1	Use $v_A = 2v_B$ to find $\beta$
	$v_B \sin \beta = u \sin \theta \Rightarrow \frac{3u \sin \theta}{2} \sin \beta = u \sin \theta$	A1	
	$\sin \beta = \frac{2}{3}$	A1	
	$2v_B = 3u \sin \theta$ & $\frac{u}{2} \cos \theta = v_B \cos \beta$ $\Rightarrow 6 \tan \theta = \frac{2}{\cos \beta} \left( = 2 \times \frac{3}{\sqrt{5}} \right)$	M1	Solve for $\theta$
	$\tan \theta = \frac{1}{\sqrt{5}}$ , $\theta = 24.1(^{\circ})$ (0.421 radians)	A1	
		[12]	

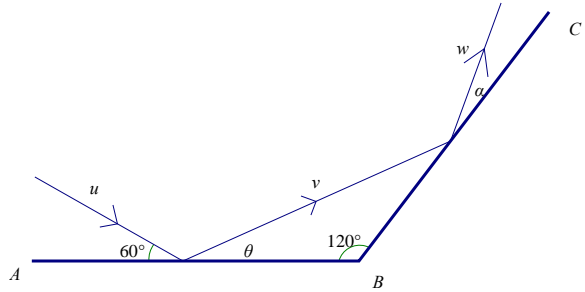
Question Number	Scheme	Marks	Notes
<b>4a</b>	Equation of motion: $900a = \frac{22500}{v} - 25v$	M1	Requires all three terms. Condone sign errors
		A1	Correct unsimplified equation
	$a = \frac{\frac{22500}{v} - 25v}{900} = \frac{900 - v^2}{36v}$	A1 [3]	Obtain <b>**Given answer**</b> with no errors seen
<b>4b</b>	$\frac{dv}{dt} = \frac{900 - v^2}{36v}$	B1	Differential equation in $v$ and $t$
	$\int \frac{36v}{900 - v^2} dv = \int 1 dt,$	M1	Separate & integrate
	$t = -18 \ln(900 - v^2) (+C)$	A1	
	: $T = -18 \ln 500 + 18 \ln 800 = 18 \ln \frac{8}{5}$	M1	Use limits correctly <b>Dependent?</b>
		A1	Obtain <b>**Given answer**</b> with no errors seen
		[5]	
<b>4c</b>	$\frac{900 - v^2}{36v} = v \frac{dv}{dx}$	B1	Differential equation in $v$ and $x$
	$\int \frac{v^2}{900 - v^2} dv = \int \frac{1}{36} dx$	M1	Separate variables
	$= \int \frac{900}{900 - v^2} - 1 dv = \left( \int \frac{900}{60} \left( \frac{1}{30 - v} + \frac{1}{30 + v} \right) - 1 dv \right)$	M1	Use partial fractions or equivalent
	$15 \ln \left  \frac{30 + v}{30 - v} \right  - v = \frac{x}{36} (+C)$	A1	
	$15 \ln \left( \frac{50}{10} \times \frac{20}{40} \right) - (20 - 10) = \frac{x}{36}$	M1	Use limits and solve for $x$ <b>Dependent?</b>
	$x = 135 \text{ (m)} \quad (540 \ln 2.5 - 360)$	A1	
		[6]	
		(14)	

Question Number	Scheme	Marks	Notes
5a			Extension in $AP : 2 + x$ , Extension in $BP : 3 + \frac{1}{4} \sin 2t - x - 1$
	$T_1 = \frac{12(2+x)}{1}$	B1	Force towards $A$
	$T_2 = 12 \left( 2 + \frac{1}{4} \sin 2t - x \right)$	B1	Force towards $B$
	$1.5 \frac{d^2x}{dt^2} = T_2 - T_1 = 3 \sin 2t - 24x$	M1	Form equation of motion of $P$ . Requires derivative and both tensions, but condone sign errors.
		A1	
	$\frac{d^2x}{dt^2} + 16x = 2 \sin 2t$	A1	Obtain <b>***given answer***</b> with no errors seen.
		[5]	
5b	$t = 0, x = 0 \Rightarrow C = 0$	B1	
	$t = 0, \dot{x} = 0 = 4D \cos 4t + \frac{1}{3} \cos 2t$	M1	
	$D = -\frac{1}{12}$	A1	
	$\dot{x} = 0 \Rightarrow \cos 4t = \cos 2t$	M1	At rest: set $\dot{x} = 0$
	$2 \cos^2 2t - 1 = \cos 2t$		
	$\cos 2t = 1, -\frac{1}{2} \quad 2t = \frac{2\pi}{3}, \quad t = \frac{\pi}{3} \quad (1.05)$	A1	Not $\frac{1}{2} \cos^{-1} \left( \frac{-1}{2} \right)$ ?
		[5]	

Question Number	Scheme	Marks	Notes
<b>6a</b>			
	GPE of the ring: $-2mgr \cos 2\theta$	B1	
	GPE of suspended particles: $-\sqrt{6}mg(L_1 - a) - \sqrt{6}mg(L_2 - b)$	M1	Expression of the correct structure involving their $L_1$ , $L_2$ , $a$ and $b$
	$a = 2r \sin(45 - \theta) = \frac{2r}{\sqrt{2}}(\cos \theta - \sin \theta)$	A1	Correct expression for $BR$ in terms of $r$ and $\theta$ Accept $r\sqrt{2}(1 - \sin 2\theta)$
	$b = 2r \cos(45 - \theta) = \frac{2r}{\sqrt{2}}(\cos \theta + \sin \theta)$	A1	Correct expression for $AR$ in terms of $r$ and $\theta$ Accept $r\sqrt{2}(1 + \sin 2\theta)$
	GPE of system: $-\sqrt{6}mg(L_1 - a) - \sqrt{6}mg(L_2 - b) - 2mgr \cos 2\theta$	DM1	Add the three components. Dependent on the previous M
	$= 2 \times \frac{2r}{\sqrt{2}} \cos \theta \times \sqrt{6}mg - 2mgr \cos 2\theta + \text{constant}$		
	$= 2mgr(2\sqrt{3} \cos \theta - \cos 2\theta) + \text{constant}$	A1	Simplify to the <b>given answer</b>
		[6]	

Question Number	Scheme	Marks	Notes
<b>6b</b>	$\frac{dV}{d\theta} = -4\sqrt{3} mgr \sin \theta + 4mgr \sin 2\theta$	M1	Differentiate
	In equilibrium: $\frac{dV}{d\theta} = 0 = 4mgr \sin \theta (-\sqrt{3} + 2 \cos \theta)$	M1	Set $\frac{dV}{d\theta} = 0$ and solve for $\theta$
	$\theta = \pm \cos^{-1} \left( \frac{\sqrt{3}}{2} \right) = \pm \frac{\pi}{6} (= \pm 0.52)$	A1	
	or $\theta = 0$	B1	
		[4]	
<b>6c</b>	$\frac{d^2V}{d\theta^2} = -4\sqrt{3} mgr \cos \theta + 8mgr (\cos^2 \theta - \sin^2 \theta)$	M1	Second derivative - needs to be the full expression.
	$\frac{d^2V}{d\theta^2} = mgr \left( -4\sqrt{3} \times \frac{\sqrt{3}}{2} + 8 \left( \frac{3}{4} - \frac{1}{2} \right) \right) = -2mgr < 0$	M1	Substitute $\theta = \frac{\pi}{6}$
	So equilibrium is unstable	A1	No errors seen
		[3]	
		<b>(13)</b>	



Question Number	Scheme	Marks	Notes	
<b>7a</b>	Resolve parallel to barrier - condone sin/cos confusion	M1		
	$u \cos 60 = v \cos \theta$	A1		
	Resolve perpendicular to the barrier - condone sin/cos confusion	M1		
	$eu \sin 60 = v \sin \theta$	A1		
	$v^2 = u^2 \cos^2 60 + e^2 u^2 \sin^2 60 = \frac{u^2}{4} + \frac{3u^2}{16} = \frac{7u^2}{16}$	M1		Eliminate $\theta$ and solve for $v$ .
	$v = \frac{\sqrt{7}}{4} u$	A1		Obtain given answer correctly with no errors seen
		[6]		
<b>7b</b>	Angle of approach with $BC = 19.1^\circ$	B1		
	$v \cos 19.1 = w \cos \phi$	M1	Components parallel to $BC$	
	$\frac{1}{2} v \sin 19.1 = w \sin \phi$	M1	Components perpendicular to $BC$	
		A1	Equations correct for their 19.1	
	Form equation in $v$ and $\phi$	M1	Square and add or divide to find $\tan \phi$	
	$w^2 = v^2 \left( \frac{1}{4} \sin^2 19.1 + \cos^2 19.1 \right)$	A1	$(\phi = 9.83^\circ)$ Follow their 19.1?	
	$0.634u$	A1		
<b>7balt</b>	$\tan \theta = \frac{1}{2} \tan 60$	B1		

Question Number	Scheme	Marks	Notes
	$\tan \alpha = \frac{1}{2} \tan(60 - \theta) \quad \left( = \frac{1}{2} \left( \frac{\sqrt{3} - \frac{1}{2}\sqrt{3}}{1 + \sqrt{3} \cdot \frac{1}{2}\sqrt{3}} \right) = \frac{\sqrt{3}}{10} \right)$	M1	
		A1	
	$v \cos(60 - \theta) = w \cos \alpha$	M1	
	$v \left( \frac{1}{2} \cdot \frac{2}{\sqrt{7}} + \frac{\sqrt{3}}{2} \cdot \frac{\sqrt{3}}{\sqrt{7}} \right) = w \frac{10}{\sqrt{103}} \left( = v \frac{5}{2\sqrt{7}} \right)$	M1	
		A1	
	$w = \frac{\sqrt{103}}{4\sqrt{7}} v = \frac{\sqrt{103}}{4\sqrt{7}} \cdot \frac{\sqrt{7}}{4} u = \frac{\sqrt{103}}{16} u \quad (0.634u)$	A1	
		[7]	

